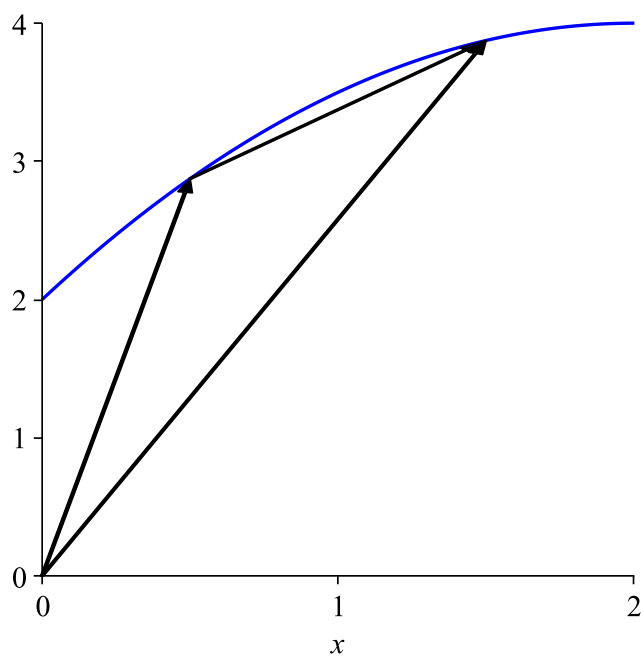
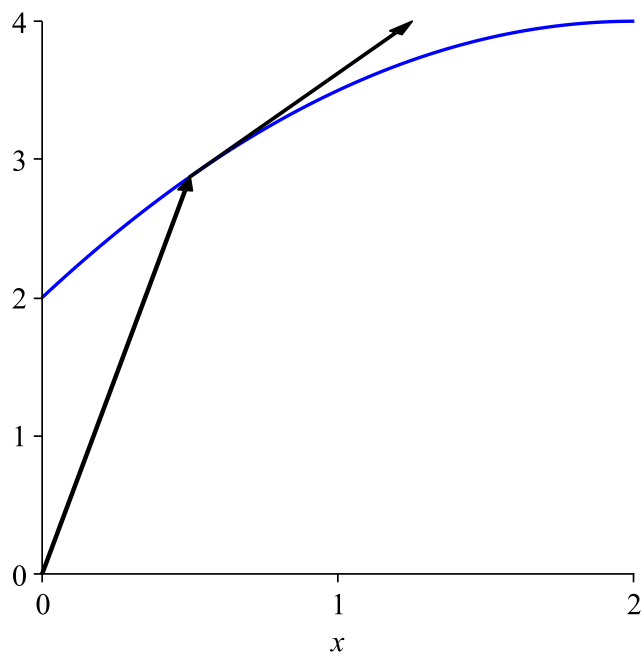


Calculus 3 - Vector Functions

Last class we considered $\vec{r}(t + \Delta t) - \vec{r}(t)$



then computed $\lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t}$



It is interesting to note the the derivative of the vector functions gives rise to a vector that is tangent to the curve. This we will define later. Now we consider the derivative analytically for the vector function

$$\vec{r}(t) = \langle f(t), g(t) \rangle$$

$$\begin{aligned} \vec{r}'(t) &= \lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t} \\ &= \lim_{\Delta t \rightarrow 0} \frac{\langle f(t + \Delta t), g(t + \Delta t) \rangle - \langle f(t), g(t) \rangle}{\Delta t} \\ &= \lim_{\Delta t \rightarrow 0} \left\langle \frac{f(t + \Delta t) - f(t)}{\Delta t}, \frac{g(t + \Delta t) - g(t)}{\Delta t} \right\rangle \quad (1) \\ &= \left\langle \lim_{\Delta t \rightarrow 0} \frac{f(t + \Delta t) - f(t)}{\Delta t}, \lim_{\Delta t \rightarrow 0} \frac{g(t + \Delta t) - g(t)}{\Delta t} \right\rangle \\ &= \langle f'(t), g'(t) \rangle \end{aligned}$$

so we have

$$\vec{r}'(t) = \langle f'(t), g'(t) \rangle \quad (2)$$

and all the derivative rules from Calc 1 apply.

Example 1

If $\vec{r}(t) = \langle t, t^2 \rangle$ find $\vec{r}'(t)$.

A simple calculation gives $\vec{r}'(t) = \langle 1, 2t \rangle$

Example 2

If $\vec{r}(t) = \langle \cos t, \sin t \rangle$ find $\vec{r}'(t)$.

A simple calculation gives $\vec{r}'(t) = \langle -\sin t, \cos t \rangle$

Example 3

If $\vec{r}(t) = \langle t^2 - 1, 2t, t^2 + 1 \rangle$ find $\vec{r}'(t)$ and $\vec{r}''(t)$.

A simple calculation gives $\vec{r}'(t) = \langle 2t, 2, 2t \rangle$ and $\vec{r}''(t) = \langle 2, 0, 2 \rangle$. A

physical interpretation of $\vec{r}''(t)$ will be given later.

Integrals

As much as we can take derivatives of vector functions, we can integrate vector functions. So if $\vec{r}(t) = \langle f(t), g(t) \rangle$ then for indefinite integrals

$$\int \vec{r}(t) dt = \langle \int f(t) dt + c_1, \int g(t) dt + c_2 \rangle \quad (3)$$

where c_1 and c_2 are arbitrary functions and for definite integrals

$$\int_a^b \vec{r}(t) dt = \langle \int_a^b f(t) dt, \int_a^b g(t) dt \rangle. \quad (4)$$

Example 4

If $\vec{r}(t) = \langle \cos t, \sin t \rangle$ find $\int \vec{r}(t) dt$.

A simple calculation gives

$$\int \vec{r}(t) dt = \langle \int \cos t dt + c_1, \int \sin t dt + c_2 \rangle = \langle \sin t + c_1, -\cos t + c_2 \rangle$$

Example 5

If $\vec{r}(t) = \langle 3t^2, 2t, \frac{1}{t^2} \rangle$ find $\int_1^2 \vec{r}(t) dt$.

A simple calculation gives

$$\begin{aligned} \int_1^2 \vec{r}(t) dt &= \left\langle \int_1^2 3t^2 dt, \int_1^2 2t dt, \int_1^2 \frac{1}{t^2} dt \right\rangle \\ &= \left\langle t^3 \Big|_1^2, t^2 \Big|_1^2, -\frac{1}{t} \Big|_1^2 \right\rangle \\ &= \left\langle 7, 3, \frac{1}{2} \right\rangle \end{aligned} \quad (5)$$

In calculus 2 we introduced two ways of multiplying vectors: the dot product and cross product.

Dot Product The dot product of two vectors $\vec{u} = \langle u_1, u_2 \rangle$ and $\vec{v} = \langle v_1, v_2 \rangle$ is

$$\vec{u} \cdot \vec{v} = u_1v_1 + u_2v_2$$

or in 3D where $\vec{u} = \langle u_1, u_2, u_3 \rangle$ and $\vec{v} = \langle v_1, v_2, v_3 \rangle$ is

$$\vec{u} \cdot \vec{v} = u_1v_1 + u_2v_2 + u_3v_3$$

The alternate definition is

$$\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$$

where $\|\vec{u}\|$ and $\|\vec{v}\|$ is the magnitude of the two vectors and θ is the angle between the vectors.

Cross Product

Given vectors $\vec{u} = \langle u_1, u_2, u_3 \rangle$ and $\vec{v} = \langle v_1, v_2, v_3 \rangle$ we define the cross product between two vectors as

$$\vec{u} \times \vec{v} = \langle u_2v_3 - u_3v_2, u_3v_1 - u_1v_3, u_1v_2 - u_2v_1 \rangle$$

Now we define the cross product

$$\vec{u} \times \vec{v} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}$$

$$= \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} \vec{i} - \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} \vec{j} + \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} \vec{k}$$

Properties of the Dot Product

Let \vec{u} , \vec{v} and \vec{w} be vectors and c a scalar (a number)

- (i) $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$
- (ii) $\vec{u} \cdot (\vec{v} + \vec{w}) = \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w}$
- (iii) $c(\vec{u} \cdot \vec{v}) = (\vec{cu}) \cdot \vec{v} = \vec{u} \cdot (\vec{cv})$
- (iv) $\vec{0} \cdot \vec{v} = 0$
- (v) $\vec{u} \cdot \vec{u} = \|\vec{u}\|^2$

Properties of the Cross Product

Let \vec{u} , \vec{v} and \vec{w} be vectors and c a scalar (a number)

- (i) $\vec{u} \times \vec{v} = -\vec{v} \times \vec{u}$
- (ii) $\vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$
- (iii) $c(\vec{u} \times \vec{v}) = (\vec{cu}) \times \vec{v} = \vec{u} \times (\vec{cv})$
- (iv) $\vec{0} \times \vec{v} = \vec{0}$
- (v) $\vec{u} \times \vec{u} = \vec{0}$
- (vi) $\vec{u} \cdot (\vec{v} \times \vec{w}) = (\vec{u} \times \vec{v}) \cdot \vec{w}$

With the introduction of derivative of vector functions

$$\vec{r}(t) = \langle f(t), g(t) \rangle \quad \text{then} \quad \vec{r}'(t) = \langle f'(t), g'(t) \rangle \quad (6)$$

We have the following derivative rules. Let \vec{u} and \vec{v} be vector functions

and $f(t)$ a differentiable scalar function, and \vec{c} a constant vector, then

- (i) $\frac{d}{dt} \vec{c} = \vec{0}$
- (ii) $\frac{d}{dt} (\vec{u}(t) + \vec{v}(t)) = \vec{u}'(t) + \vec{v}'(t)$
- (iii) $\frac{d}{dt} (f(t) \vec{u}(t)) = f'(t) \vec{u} + f(t) \vec{u}'(t)$
- (iv) $\frac{d}{dt} (\vec{u}(f(t))) = \vec{u}'(f(t)) f'(t)$
- (v) $\frac{d}{dt} (\vec{u}(t) \cdot \vec{v}(t)) = \vec{u}'(t) \cdot \vec{v}(t) + \vec{u}(t) \cdot \vec{v}'(t)$
- (vi) $\frac{d}{dt} (\vec{u}(t) \times \vec{v}(t)) = \vec{u}'(t) \times \vec{v}(t) + \vec{u}(t) \times \vec{v}'(t)$

One thing that's important to realize is that if a vector has constant length (say c) then

$$\vec{u}(t) \cdot \vec{u}(t) = c^2 \quad (7)$$

and using the property (v) above then

$$\vec{u}'(t) \cdot \vec{u}(t) + \vec{u}(t) \cdot \vec{u}'(t) = 0 \quad (8)$$

so that

$$\vec{u}(t) \cdot \vec{u}'(t) = 0 \quad (9)$$

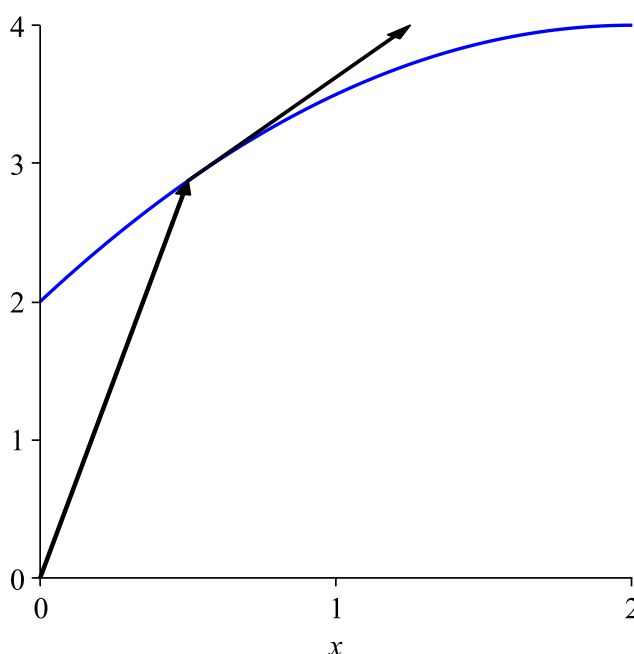
meaning that $\vec{u}(t)$ and $\vec{u}'(t)$ are perpendicular to one another. This is important in what follows.

Unit Tangent Vector

As we saw when we first introduced derivatives, that $\vec{r}'(t)$ is tangent to the space curve given by

$$x = f(t), \quad y = g(t). \quad (10)$$

so we define the unit tangent vector as



$$\vec{T} = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} \quad (11)$$

So, for example, if $\vec{r} = \langle t, \frac{1}{2}t^2 \rangle$ then $\vec{r}' = \langle 1, t \rangle$ and the unit tangent vector is

$$\vec{T} = \frac{\langle 1, t \rangle}{\sqrt{1+t^2}}, \quad (12)$$

if $\vec{r} = \langle \cos t, \sin t, t \rangle$ then $\vec{r}' = \langle -\sin t, \cos t, 1 \rangle$ and the unit tangent vector is

$$\vec{T} = \frac{\langle -\sin t, \cos t, 1 \rangle}{\sqrt{2}} \quad (13)$$

since the magnitude of $\vec{r}'(t)$ is $\sqrt{2}$. Since the tangent vector is a unit vector, then the derivative of this would give another vector that is perpendicular to \vec{T} .

Unit Normal Vector

We define the unit normal vector as

$$\vec{N} = \frac{\vec{T}'(t)}{\|\vec{T}'(t)\|} \quad (14)$$

If we consider the examples above then

$$\vec{T}' = \left\langle \frac{-t}{(1+t^2)^{3/2}}, \frac{1}{(1+t^2)^{3/2}} \right\rangle \quad (15)$$

then

$$\|\vec{T}'\| = \sqrt{\left(\frac{-t}{(1+t^2)^{3/2}}\right)^2 + \left(\frac{1}{(1+t^2)^{3/2}}\right)^2} = \frac{1}{1+t^2} \quad (16)$$

and we obtain

$$\vec{N} = \frac{\left\langle \frac{-t}{(1+t^2)^{3/2}}, \frac{1}{(1+t^2)^{3/2}} \right\rangle}{\frac{1}{1+t^2}} = \left\langle \frac{-t}{\sqrt{1+t^2}}, \frac{1}{\sqrt{1+t^2}} \right\rangle \quad (17)$$

and the reader can verify that $|\vec{T}| = 1$, $|\vec{N}| = 1$ and $\vec{T} \cdot \vec{N} = 0$.

In the second example, where

$$\vec{T} = \frac{\langle -\sin t, \cos t, 1 \rangle}{\sqrt{2}} \quad (18)$$

then

$$\vec{T}' = \frac{\langle -\cos t, -\sin t, 0 \rangle}{\sqrt{2}} \quad (19)$$

$|\vec{T}'| = \frac{1}{\sqrt{2}}$ and \vec{N} is given by

$$\vec{N} = \langle -\cos t, -\sin t, 0 \rangle \quad (20)$$

and the reader can also verify that $\|\vec{T}\| = 1$, $\|\vec{N}\| = 1$ and $\vec{T} \cdot \vec{N} = 0$.

Unit Binormal

If we are in 3D, we now have two vectors, the unit tangent vector and the unit normal vector. We can create a third vector which is perpendicular to both. We define the unit Binormal as

$$\vec{B} = \vec{T} \times \vec{N} \quad (21)$$

For the example above where $\vec{r} = \langle \cos t, \sin t, t \rangle$ then

$$\vec{B} = \vec{T} \times \vec{N} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{-\sin t}{\sqrt{2}} & \frac{\cos t}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\cos t & -\sin t & 0 \end{vmatrix} = \langle \frac{\sin t}{\sqrt{2}}, \frac{-\cos t}{\sqrt{2}}, \frac{1}{\sqrt{2}} \rangle$$