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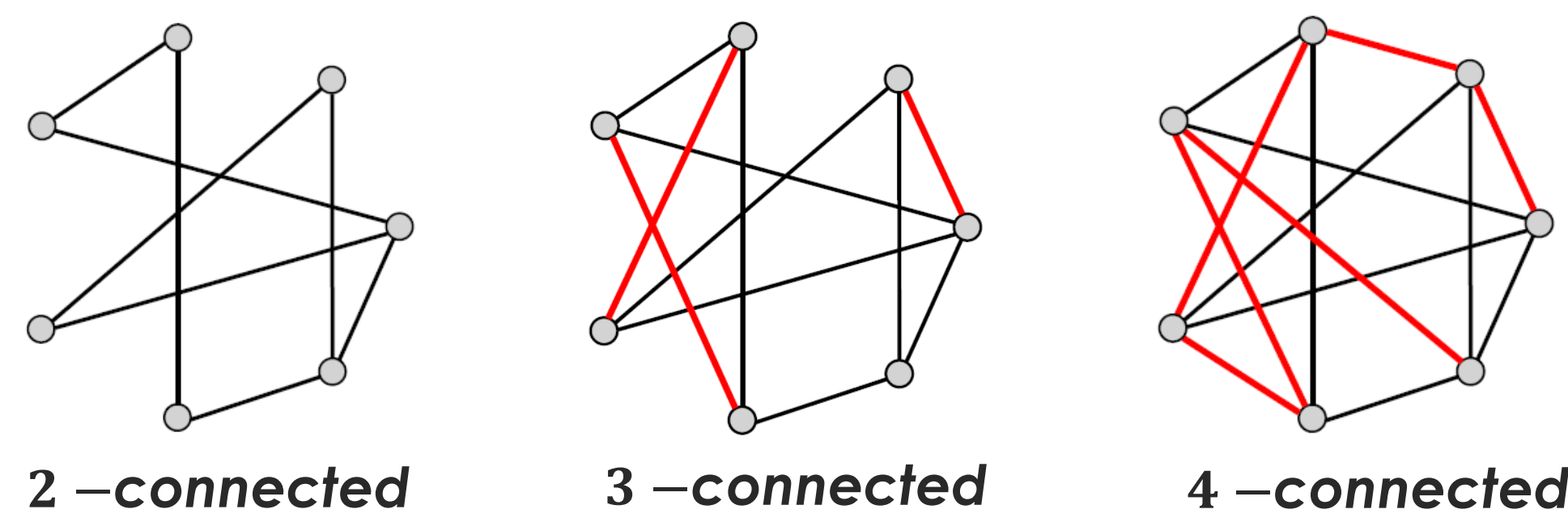
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## Abstract

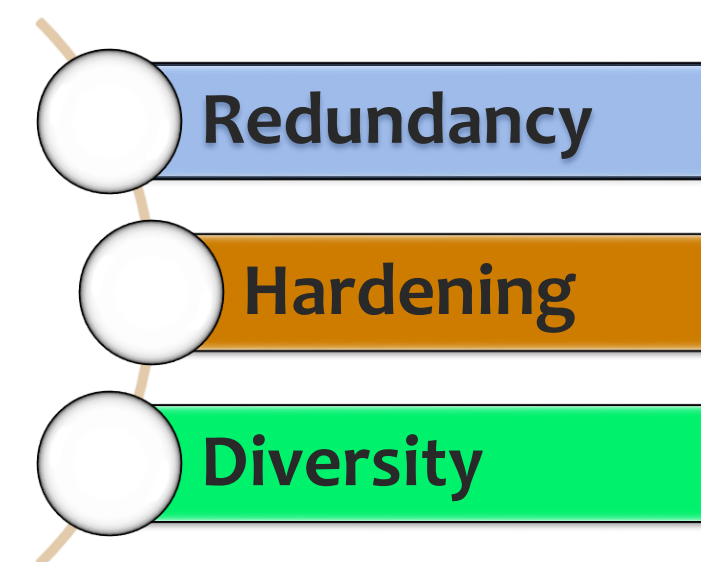
- We propose an alternative way of improving network's robustness by considering **heterogeneity of nodes**. Nodes in a network can be of different types having **disjoint sets of vulnerabilities**. Thus, an attacker can only compromise a particular type of nodes by exploiting a particular vulnerability.
- We show that, by such a diversification of nodes, attacker's ability to change the underlying network structure is significantly reduced. Consequently, even a **sparse network** with heterogeneous nodes can exhibit the properties of a **structurally robust network**.
- Using these ideas, we propose a distributed control policy that utilizes heterogeneity in the network to achieve resilient consensus in adversarial environment. By extending the notion of **(r, s)-robustness** to incorporate the diversity of nodes, we provide necessary and sufficient conditions to guarantee **resilient distributed consensus in heterogeneous networks**.

## Motivation Improving Robustness in Sparse Networks

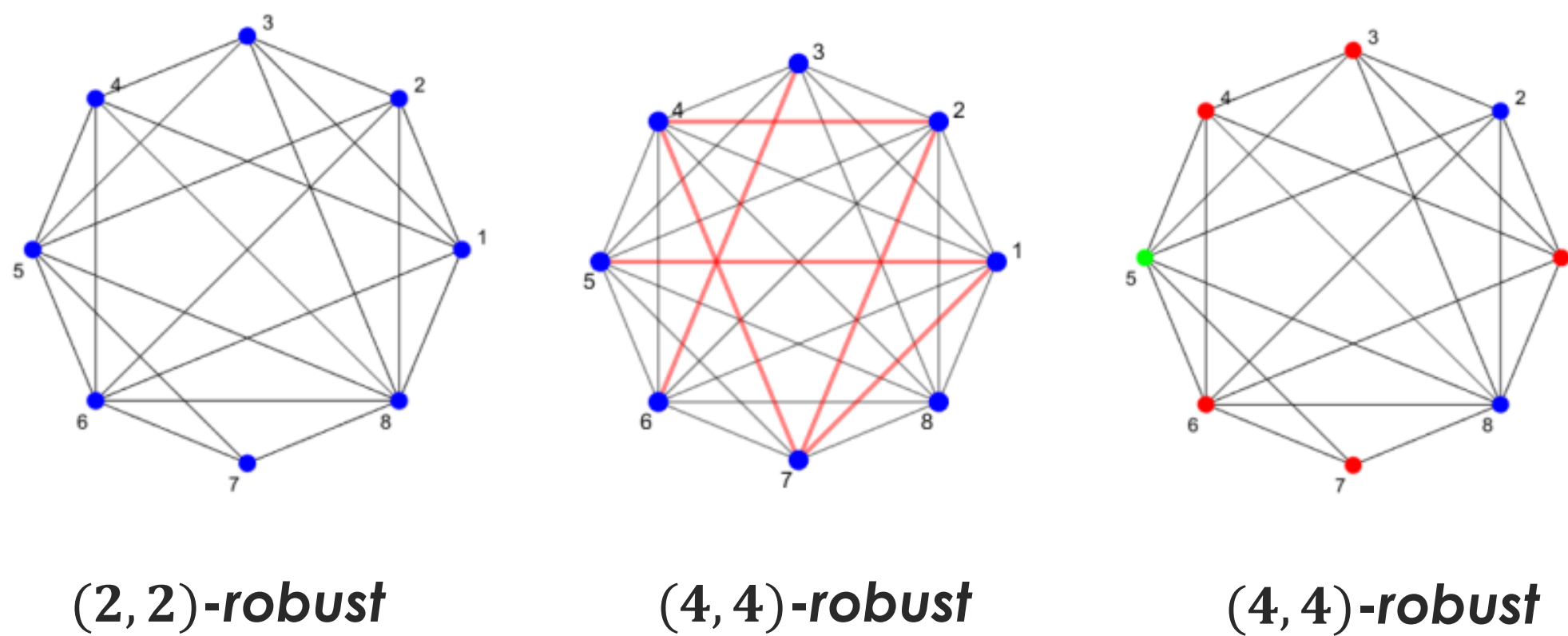
- A typical way of improving structural robustness in networks is by strategically adding edges.



- What can be alternate approaches, especially in sparse networks?

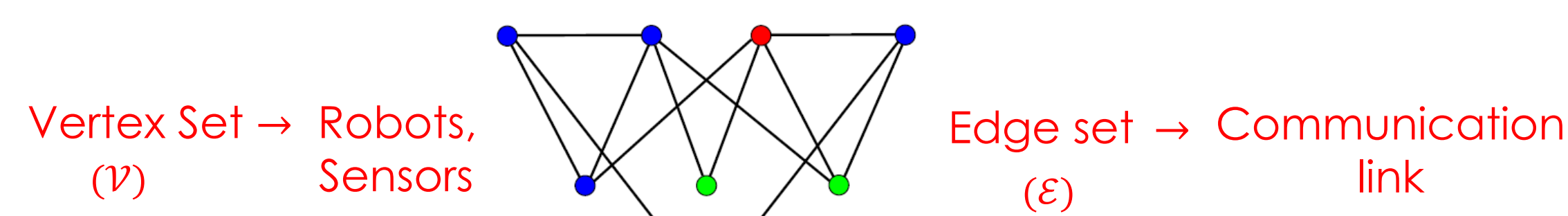


- Diversification** can improve structural robustness in sparse heterogeneous networks without adding extra links.



## Resilient Consensus Network Model and Problem Formulation

- Multi-agent System  $\rightarrow$  Undirected Graph



- Different types of nodes are represented by different **colors**. They share their states and color classes with each other.

- An attacker compromises nodes of the **same type** by exploiting a particular vulnerability.

- Two types of nodes:  
Normal Nodes  
Adversarial Nodes

### Threat Scope

- F-Total** : At most  $F$  adversarial nodes of the same color in the overall network.
- F-Local** : At most  $F$  adversarial nodes of the same color in the neighborhood of a node.

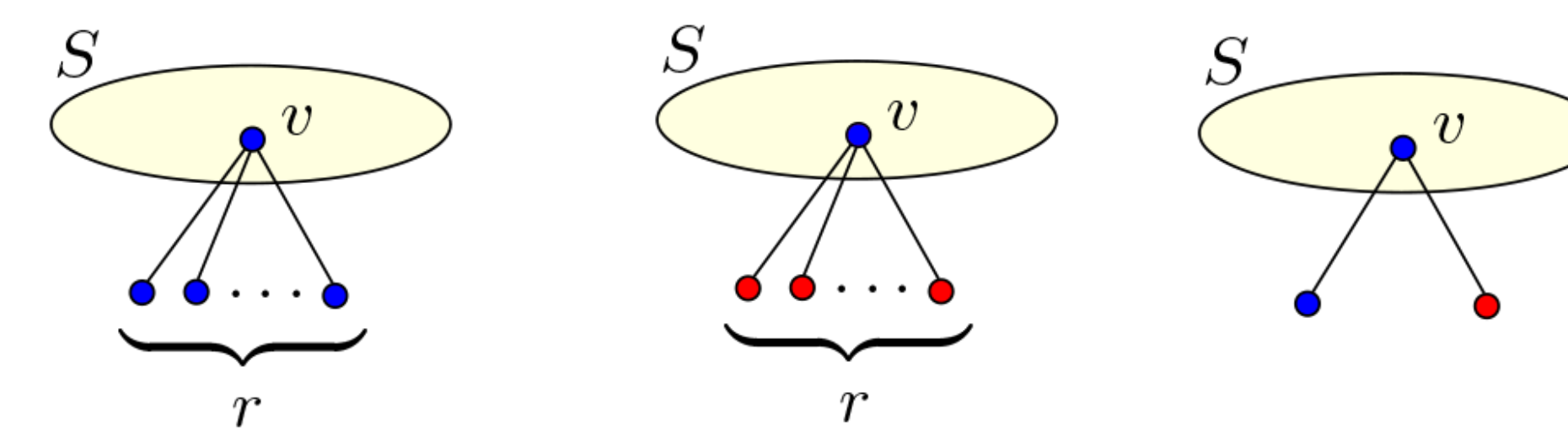
### Objective : Resilient Consensus

- Agreement** : Asymptotic convergence of normal nodes' states to a common value .
- Safety** : State of every normal node is within the interval defined by the maximum and minimum of the initial values

## Network Robustness with Coloring

### r-valid node

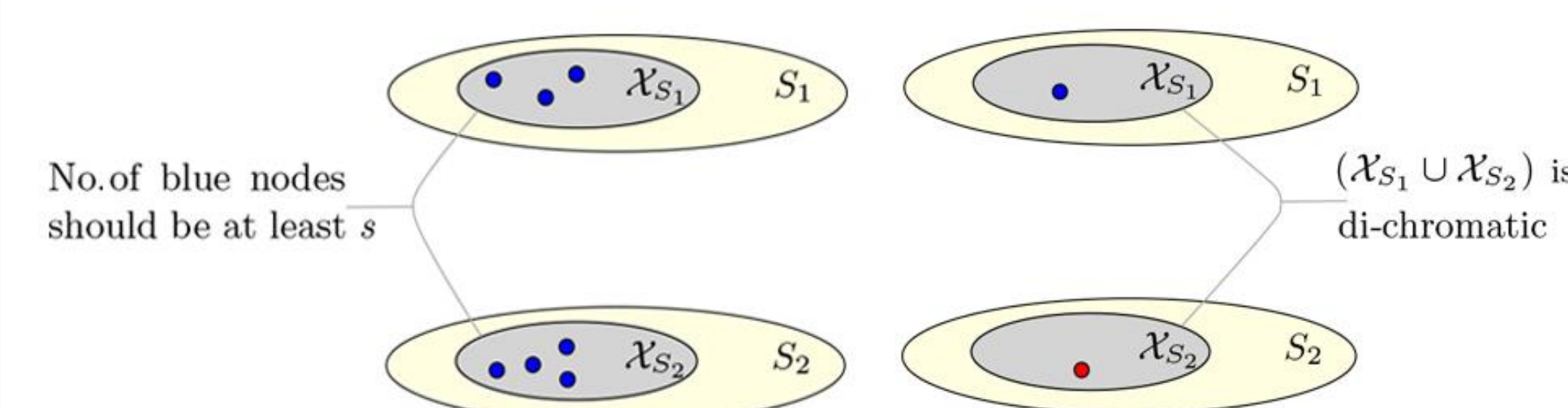
A node  $v \in S$  having at least  $r$  monochromatic or two distinct color neighbours outside of  $S$ .



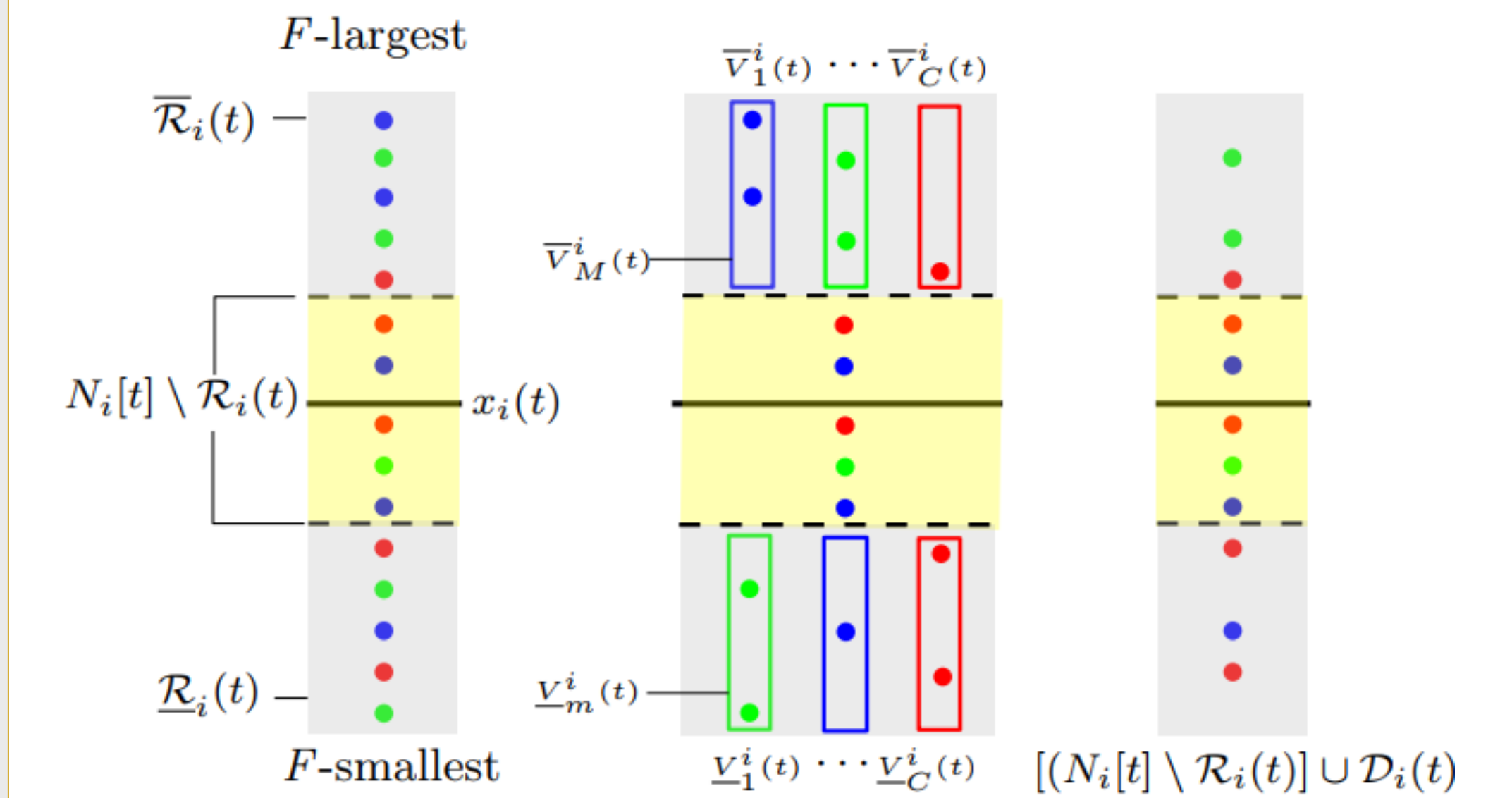
### (r, s)-robustness with coloring

Let  $r, s > 1$ , and  $S_1$  and  $S_2$  be non-empty, disjoint subsets of  $\mathcal{V}$ . Let  $\mathcal{X}_r^{S_1}$  and  $\mathcal{X}_r^{S_2}$  be sets of  $r$ -valid nodes in  $S_1$  and  $S_2$  respectively. A graph  $\mathcal{G}(\mathcal{V}, \mathcal{E})$  is  $(r, s)$ -robust with coloring if at least one is always satisfied:

- $|\mathcal{X}_r^{S_1}| = |S_1|$
- $|\mathcal{X}_r^{S_2}| = |S_2|$
- $(\mathcal{X}_r^{S_1} \cup \mathcal{X}_r^{S_2})$  is polychromatic
- $(\mathcal{X}_r^{S_1} \cup \mathcal{X}_r^{S_2})$  is monochromatic and  $|\mathcal{X}_r^{S_1} \cup \mathcal{X}_r^{S_2}| \geq s$



## Resilient Consensus Protocol with Coloring (RCP-C)



### Update Rule

$$x_i(t+1) = \sum_{j \in [(N_i[t] \setminus \mathcal{R}_i(t)) \cup \mathcal{D}_i(t)]} w_{ij}(t) x_j(t)$$

where

$$\mathcal{R}_i(t) = \bar{\mathcal{R}}_i(t) \cup \underline{\mathcal{R}}_i(t)$$

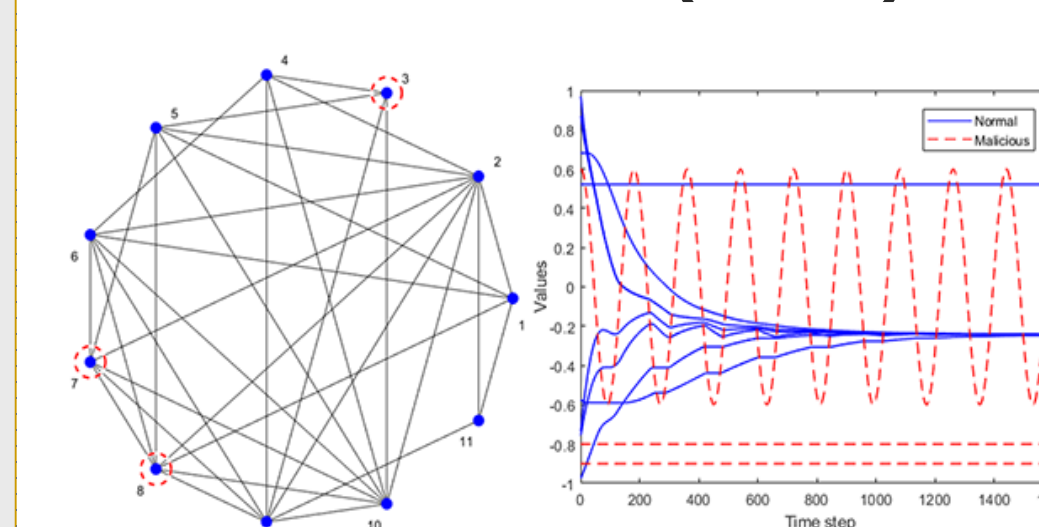
$$\mathcal{D}_i(t) = (\bar{\mathcal{R}}_i(t) \setminus \bar{\mathcal{V}}_M^i(t)) \cup (\underline{\mathcal{R}}_i(t) \setminus \underline{\mathcal{V}}_m^i(t))$$

**Theorem.** Let  $\mathcal{G}(\mathcal{V}, \mathcal{E})$  be a colored network, in which normal nodes follow RCP-C. Then,

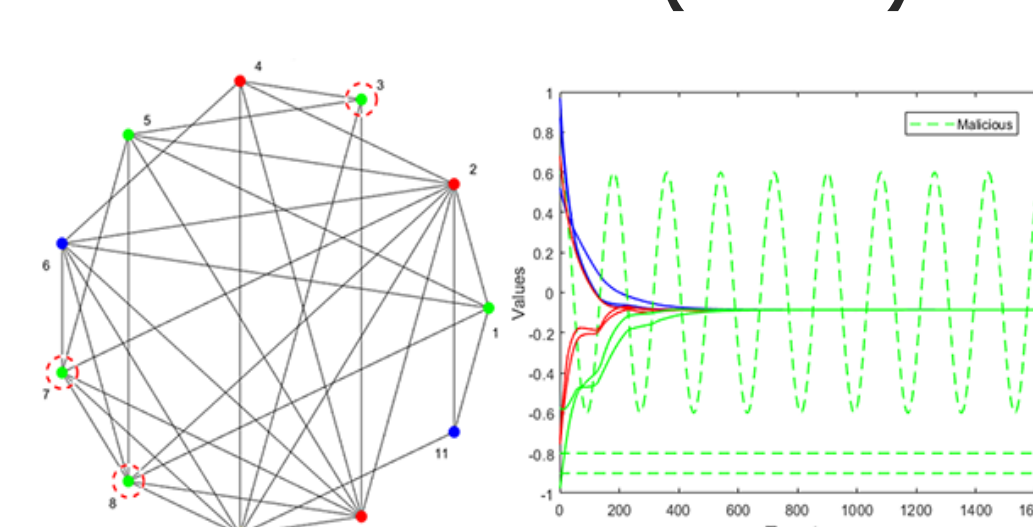
- F-total model**: resilient asymptotic consensus is achieved if and only if the underlying graph topology is  $(F+1, F+1)$ -robust with colors.
- F-local model**: resilient asymptotic consensus is achieved if the graph topology is  $(2F+1)$ -robust with colors.

## Simulations

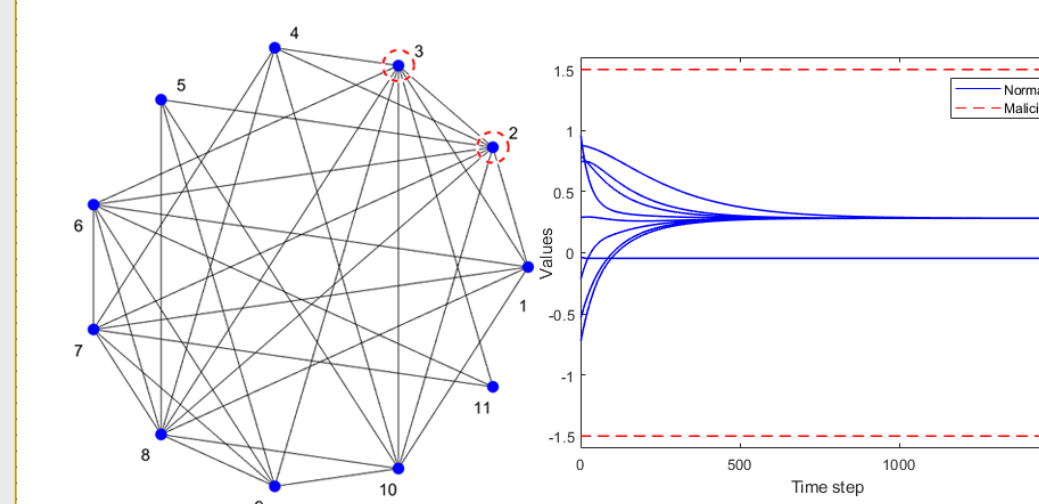
### F-Total Model (WMSR)



### F-Total Model (RCP-C)



### F-Local Model (WMSR)



### F-Local Model (RCP-C)

