

Using the simulator various operation regimes and control strategies can be studied / designed and various types of transients can be studied



Use of Dynamic simulator for developing correction factors for transients for a Steady state simulator



- Electricity yield calculations are generally done by steady-state simulation, in hourly time-resolution, using at least one year data.
- Such calculations are fairly quick, but fail to capture the ill effects of Start-up and interruptions due to broken clouds.
- Such effects can only be handled by a dynamic simulator, but the use of a dynamic simulation is not feasible for such long term data in an iterative mode. Its feasible only for short term analysis.
- DLR has therefore developed certain correction factors, that can account for such dynamic effects in a quasi-static simulator, thus ensuring that the calculations are quick as well as close to reality.
- For developing these correction factors, DLR has used their dynamic simulator which was presented in the previous slides.



Use of Dynamic simulator for developing correction factors for taking care of reduction during Start up



The minimum start-up energy is the difference between the Energy level (required to start the power production) and Energy level of the system in the morning.

The ratio of theoretically available energy during the start-up process to the minimum start-up energy is called start-up effort ratio

$$\psi_{\text{start-up}} = \frac{\Delta E_{\text{avail}}}{\Delta E_{\text{min}}} > 1 .$$

A value close to 1 indicates a good quality of start up.

By simulating start ups on enough number of days with varying conditions, it is possible to get start up effort ratios.



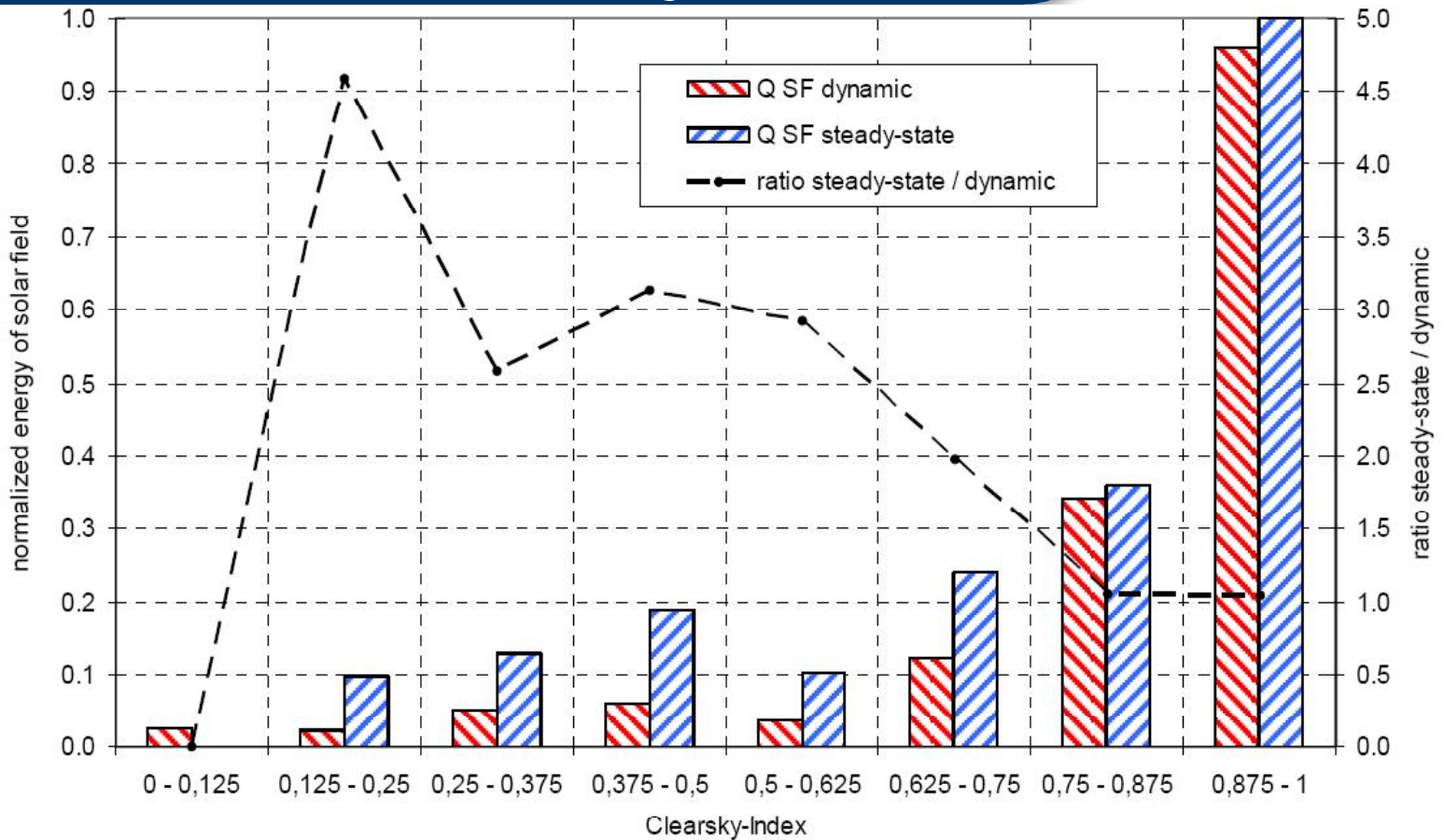
Use of Dynamic simulator for developing correction factors for taking care of reduction due to clouding



- For studying the impact of short-term fluctuations (clouds) on the electricity yield, simulations with the same dynamic model were performed as were done for Start up effects.
- Simulations have been performed over a number of days including all kinds of cloud situations
- Based on the above, an appropriate reduction factor for the steady-state model could be derived in the form of a clear sky factor as shown in the graph on the next slide.



Use of Dynamic simulator for developing correction factors for taking care of reduction due to clouding



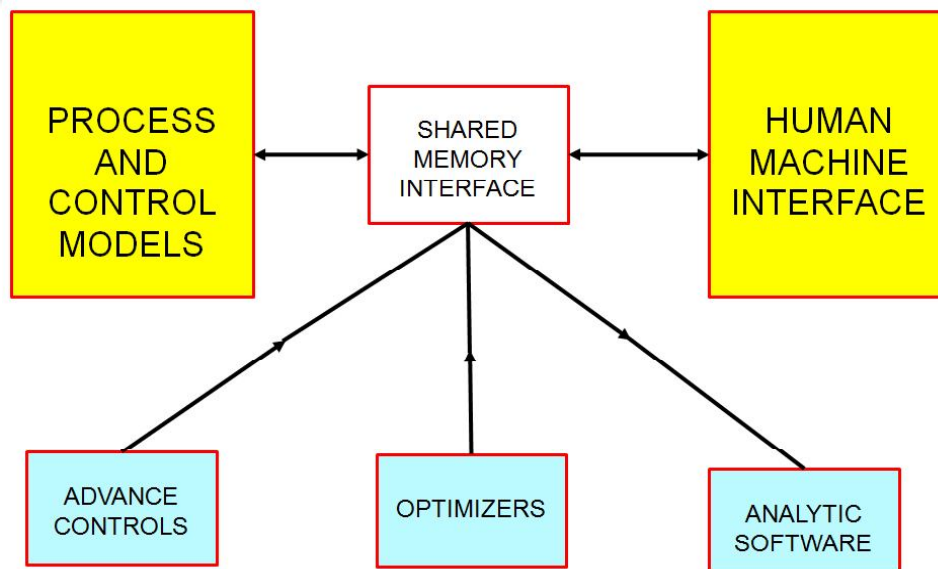
The derived reduction factors would be only applicable for the considered steady-state model.



Topics for discussion



- Simulator types – Steady state, Quasi Steady state and Dynamic
- Applications of Dynamic simulators in Solar thermal
 - Dynamic simulators – Case studies – DLR, SESI
 - Basic applications – Training
 - Simulation studies – Correction factors for a Steady State simulator
 - **Research on Operational Optimization**
 - Startup time optimization
 - Plant trip risk minimization – Transients
 - Mirror cleaning frequency optimization
 - Thermal storage usage optimization
- Applications of Steady state simulators in Solar thermal
 - Design optimization - Field sizing and Annual electricity generation
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 - PG testing of plant and Daily performance monitoring



- It is possible to write interface software to exchange data between simulator and other softwares such as optimizers and Advanced control software like Model Predictive Control.
- With this interface it is possible to writing the setpoints generated by external software simulator fields and test the results.



R&D on operational optimization on simulator platform



Startup time optimization :

- A solar plant needs a daily start up and shut down.
- Since it has to be done daily, a small reduction in the startup time can be a big additional revenue
- Startup under different DNI conditions is different and so is the startup strategy and the startup optimization challenge.

Mirror cleaning optimization:

- The mirrors in the solar field need cleaning periodically and each cleaning process is very resource intensive.
- It is therefore required to optimize the frequency of cleaning by comparing the cost of cleaning to the loss being incurred by the dirty surfaces.



Optimization of Thermal Energy Storage Operation

- This process of thermal storage operation has to be scheduled and optimized such that it maximizes the power production while meeting ramp rates and other process/ equipment constraints.

Minimizing the risk of plant trip during transients

- Transients like cloudy conditions can sometimes trip the plant
- The plant can sometimes sustain the operations by reducing the load sometimes without tripping.
- This is also an important research problem and an important application of such simulators.



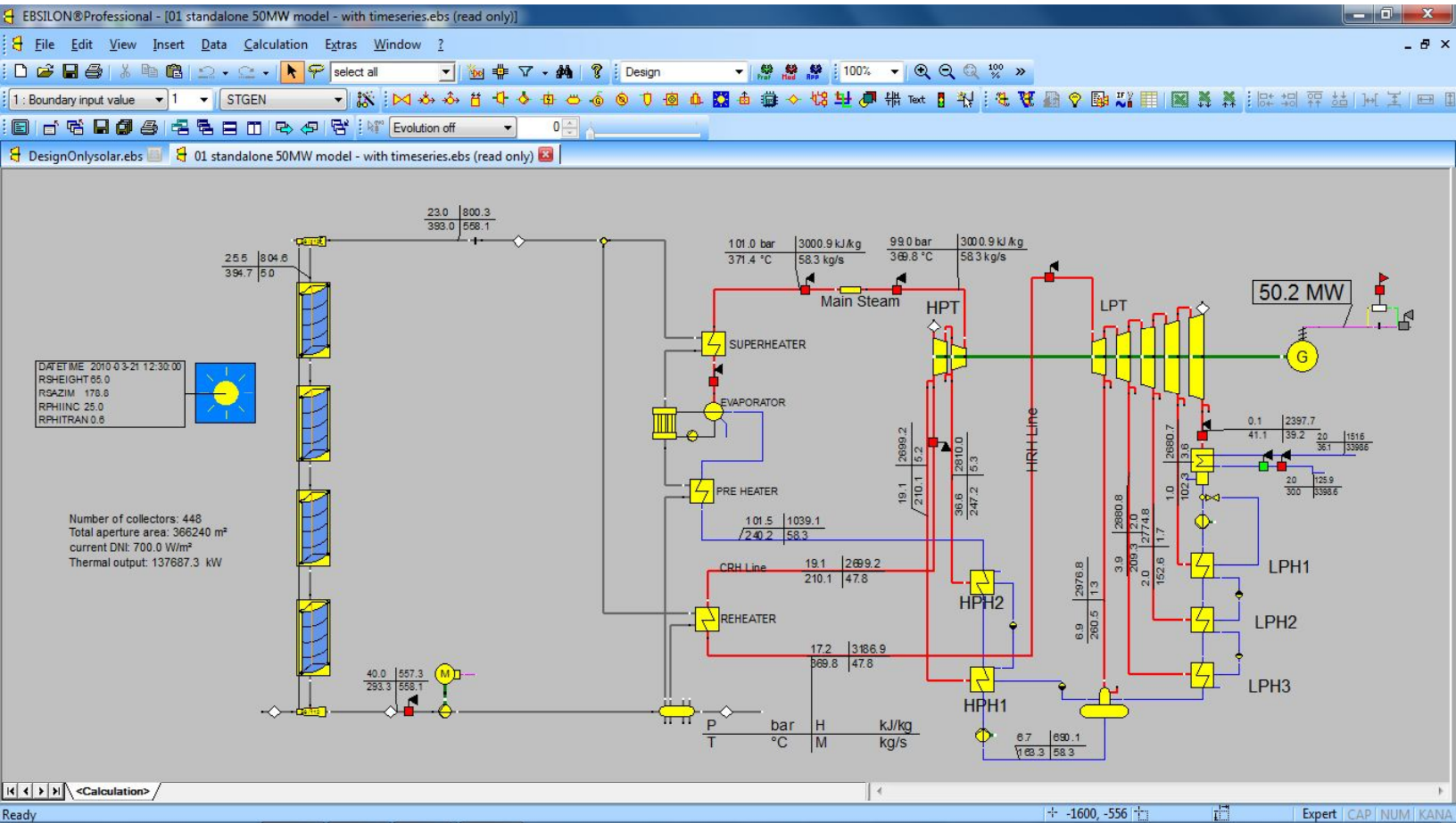
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Solar plant design



Step 1 - Creation of the components of solar field as well as the power block



Solar field sizing



Component properties of Sun [Component Type 117: The sun]

Specification-Values	Results	Basic Properties	Fluids	View Properties	Extended Options	SRx
Time reference system	FTFRAME	Local time : 1				
Time zone in which local time is given	FTZONE	Indian Standard Time (UTC+5:3)				
Algorithm for sun angles	FSANGLE	Calculation according to NREL				
Incident angle calculation	FIANGLE	Calculation from sun angles : 0				
Latitude (positive on northern hemisphere, -90°..180°)	LATI	25.2 °				
Longitude (east of Greenwich, -180°..180°)	LONG	76.3 °				
Date and time	DATETIME	2010-03-21 12:30:00				
Sun height angle (angle between sun center and horizon)	SHEIGHT					
Sun azimuth angle (north=0°, positive in east direction)	SAZIM					
Azimuth angle of collector (direction of the post)	CAZIM	0 °				
Slope of collector axis (angle between axis and horizontal)	CSLOP	0 °				
Incident angle (Trough)	PHIINC					
Track angle (Trough)	PHITRAN					
Direct normal irradiance specification	FDNI	use specification value : 0				
Direct normal irradiance	DNI	750 W/m²				
Ambient temperature	TAMB	30 °C				

Profile Design

Number of collectors: 448
Total aperture area: 366240 m²
current DNI: 700.0 W/m²
Thermal output: 137687.3 kW

50.2 MW

LPH1
LPH2
LPH3

HPH1

6.7 630.1
103.3 58.3

Step 2 – Initial sizing of the solar field based on a design point at a specific day



Annual power output



Anmerkung		DNI	Tamb	generator po...	Sur
Typ	auto-inserted	spec	spec	result	res
Definition		Sun.DNI	Sun.TAMB	Gross_OP.Q	Sur
2010-01-01 06:30:00		0	15.3	0.00300896	-2
2010-01-01 07:30:00		0	15.6	0.00339918	3.2
2010-01-01 08:30:00		259	17.9	8733.37	14
2010-01-01 09:30:00		482	20.3	23152	25
2010-01-01 10:30:00		585	22.6	26306.8	33
2010-01-01 11:30:00		718	24.7	31144.1	39
2010-01-01 12:30:00		701	26.2	29073.4	41
2010-01-01 13:30:00		797	27.2	35915.4	39
2010-01-01 14:30:00		772	27.7	38397.2	33
2010-01-01 15:30:00		764	27.5	43136.6	24
2010-01-01 16:30:00		345	26.4	13843.7	14

Step 3 – Linking the DNI (tmy file) and computing the yearly power output



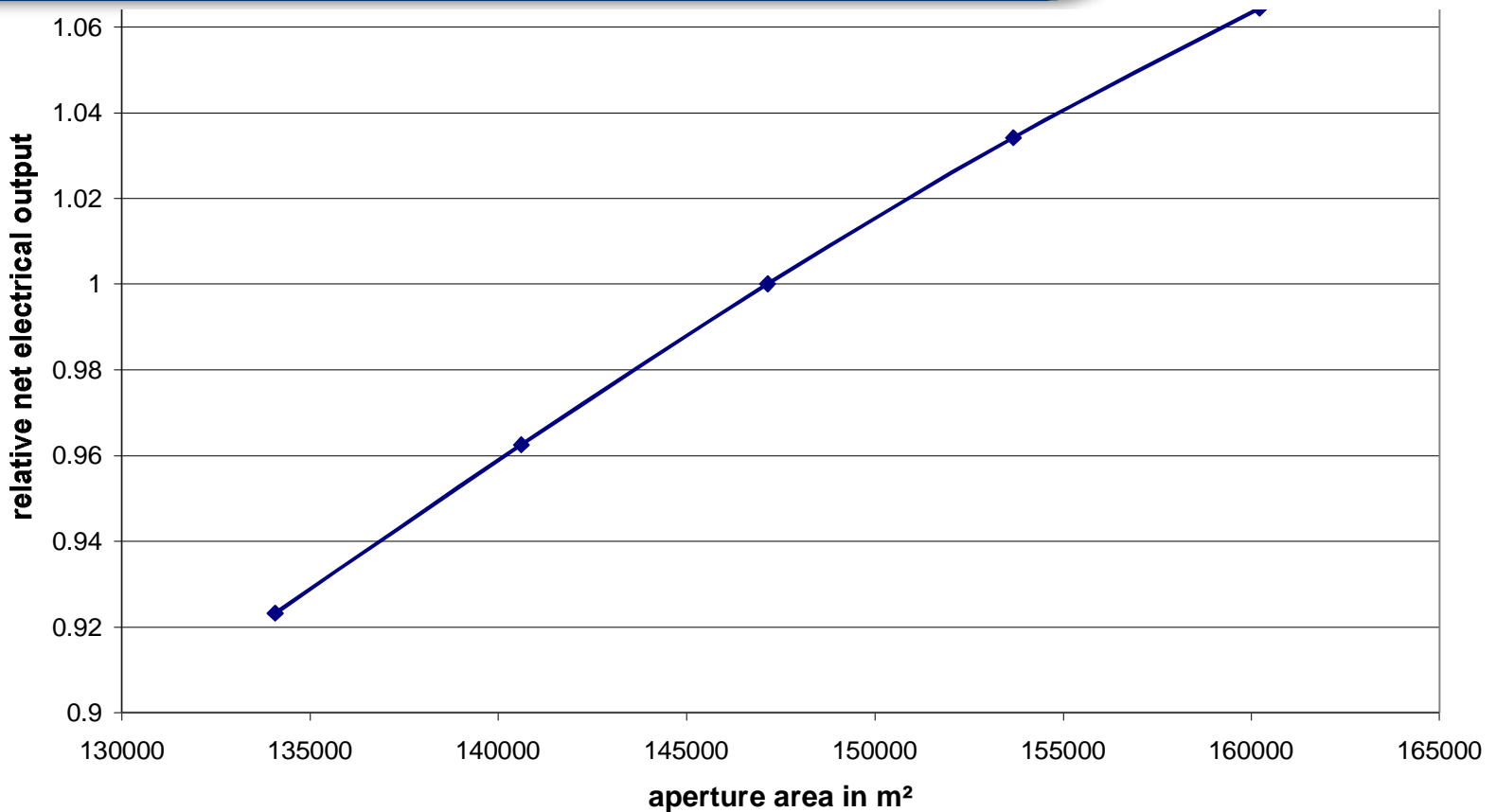
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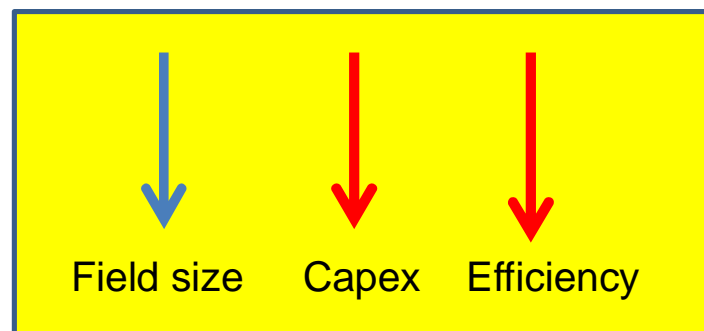
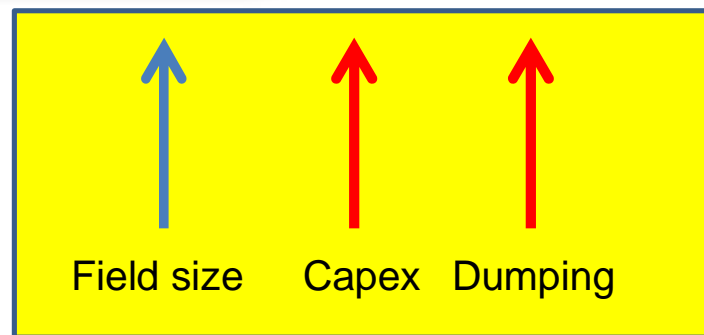


Calculation of field size for minimum LCOE



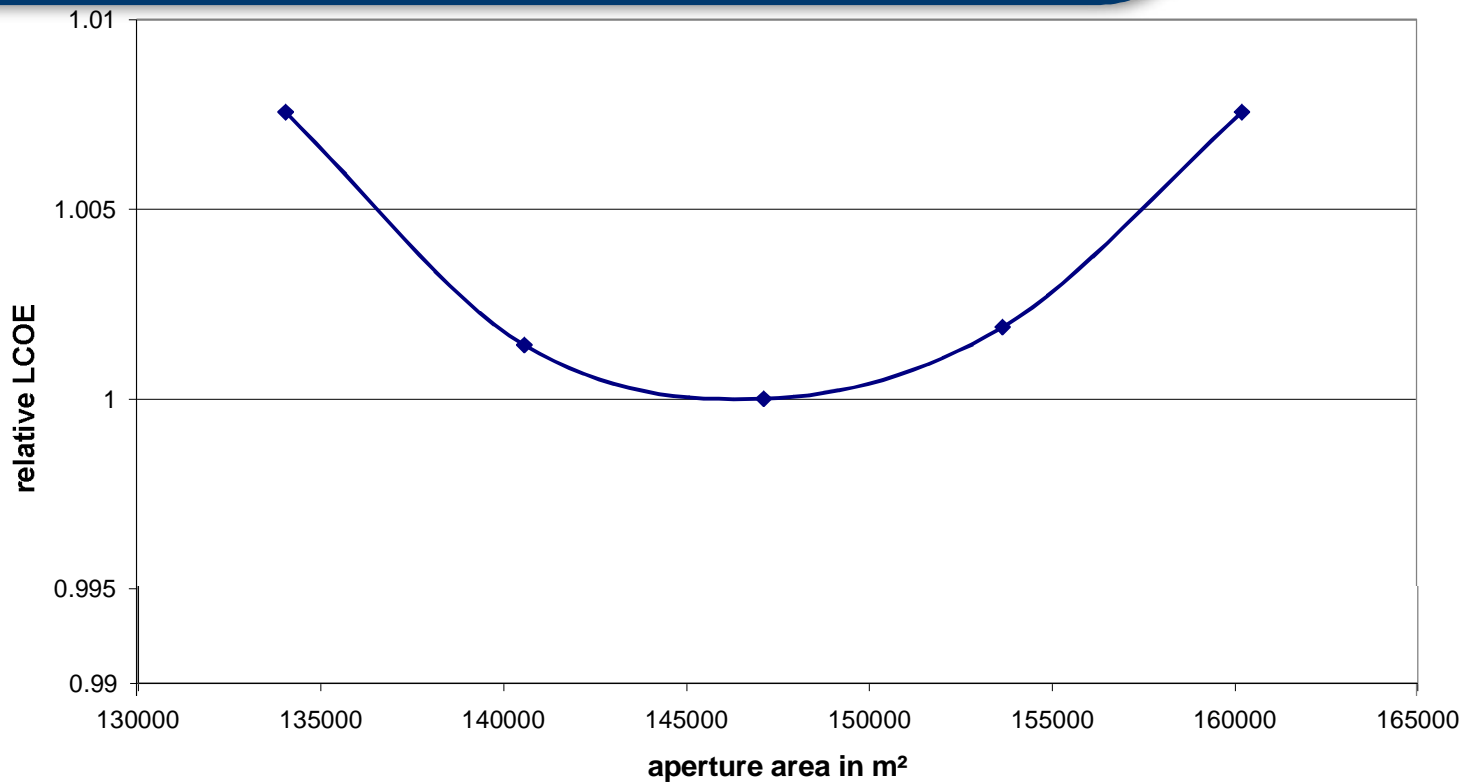
An increase in the field size increases the power output because the full load operating hours increase for a given DNI pattern but ...

- In addition to the power output, an Increase in field size also increases the Capex and dumping of steam (since power block capacity is fixed)
- A decrease in the field size decrease the Capex and Steam dumping but also increase the number of part load hours that reduces the efficiency and hence the power output.
- These dependencies are nonlinear and thus for given costs of the solar field and fixed power block size, an LCOE-optimal solar field size exists.

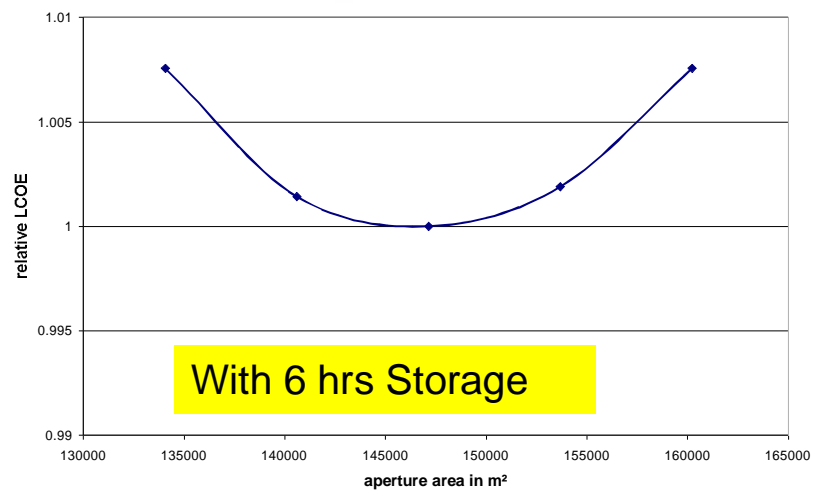
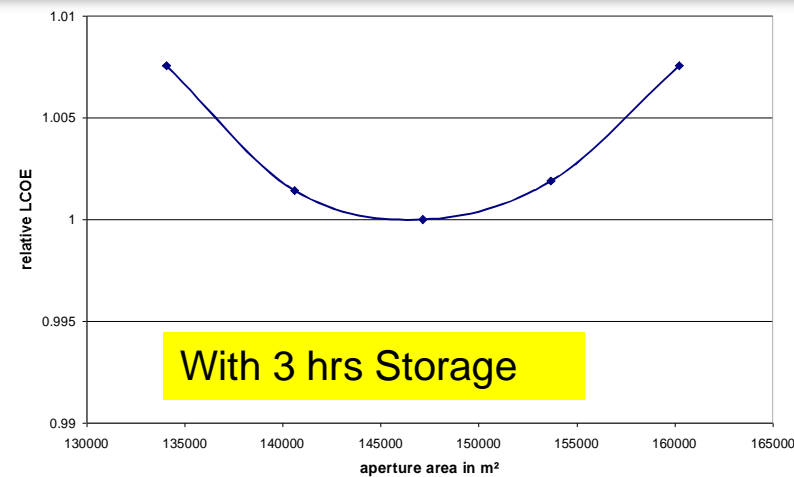




Calculation of field size for minimum LCOE



To arrive at this optimum size, iterative simulations have to be done by varying the solar field size and running the simulation model (with tmy) and calculating LCOE repeatedly.



- To consider the storage, Multi Variable Iterative Simulation is to be done
- For this first a value of storage is fixed say 3 hours and iteration for different solar field sizes leading to different LCOE are done.
- The storage size is then changed and the process is repeated.
- This is done for the entire range of storage hours that is possible
- Finally the Storage hours and the field size is fixed based on the absolute minimum out of all the above results.



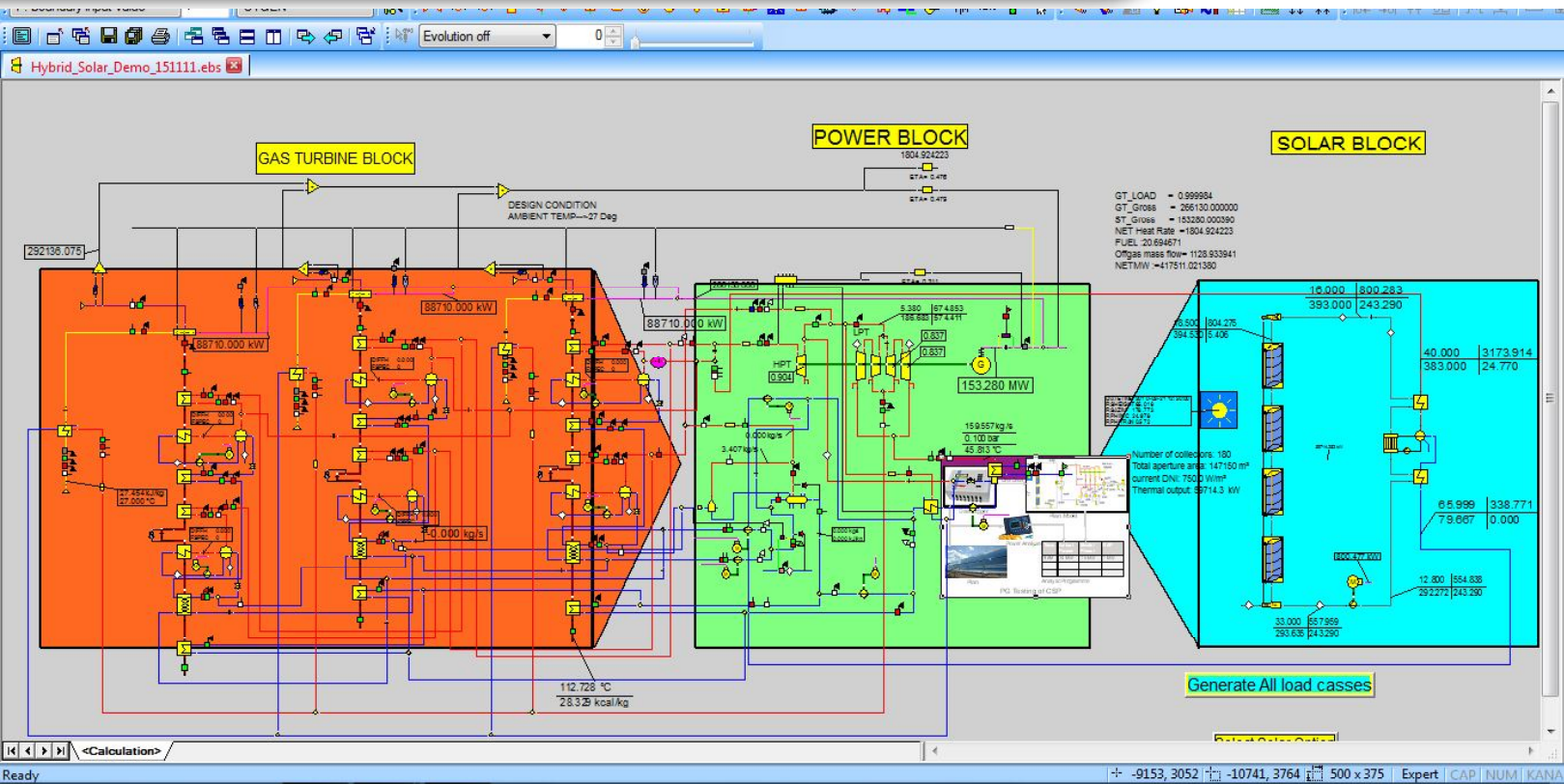
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Simulation of Hybridization schemes Developing HBD of the integrated plant



NTPC Anta 419.38 MW CCPP – Model for integration of 15 MW PT
Solar field in 153 MW ST.



Simulation of Hybridization schemes Finding the best injection point

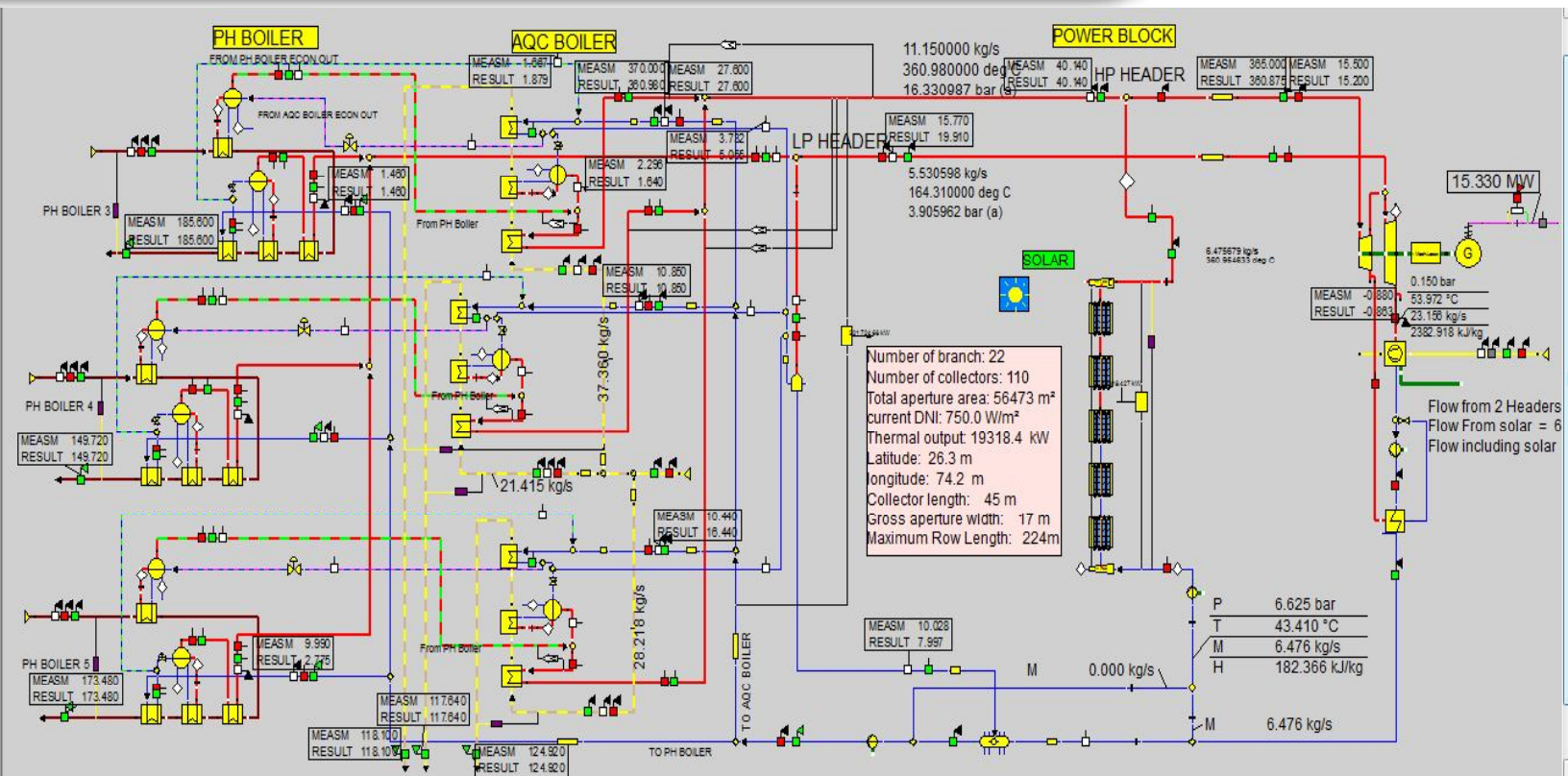


Steam injection options considered

1. To integrate the solar steam into the HP-drums of the existing HRSGs
2. To integrate the solar steam between two super heaters of the existing HRSGs
3. To integrate the solar steam of 370°C into the main steam (of 485°C) pipe via new mixing arrangement.
4. To superheat the solar steam of 370°C in a separate fired superheater to bring it to 485°C before integrating it into the main steam (of 485°C) pipe.
5. Solar steam to be used in a new Back-pressure Turbine Generator and exhaust of the BPST to be mixed with LP steam at LPT inlet.
6. Solar steam to be used in a new Condensing Turbine Generator and exhaust of the CST to be connected to condenser of the existing power plant.



Simulation of Hybridization schemes Finding the best extraction point



A cement plant in Rajasthan - Model for integration of a 5 MW Solar field into 14 MW WHRB

Water extraction points explored are CEP outlet and BFP inlet



Topics for discussion

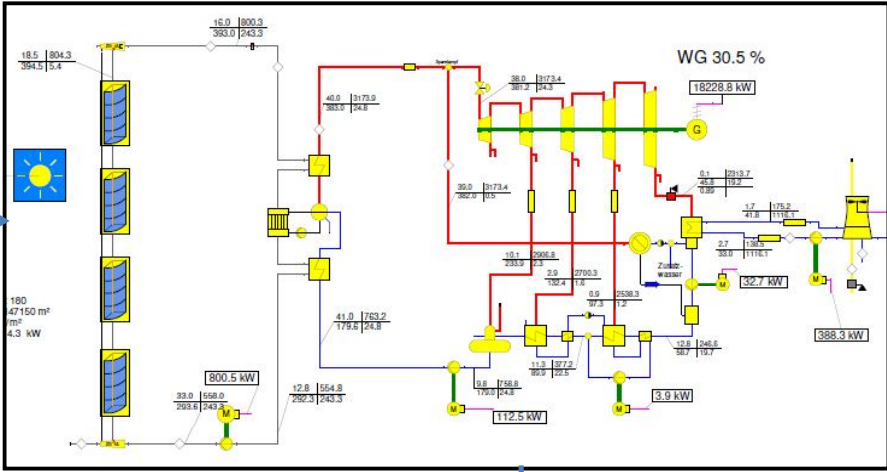


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Data Logger

DNI Data



Plant Model



Power Analyzer

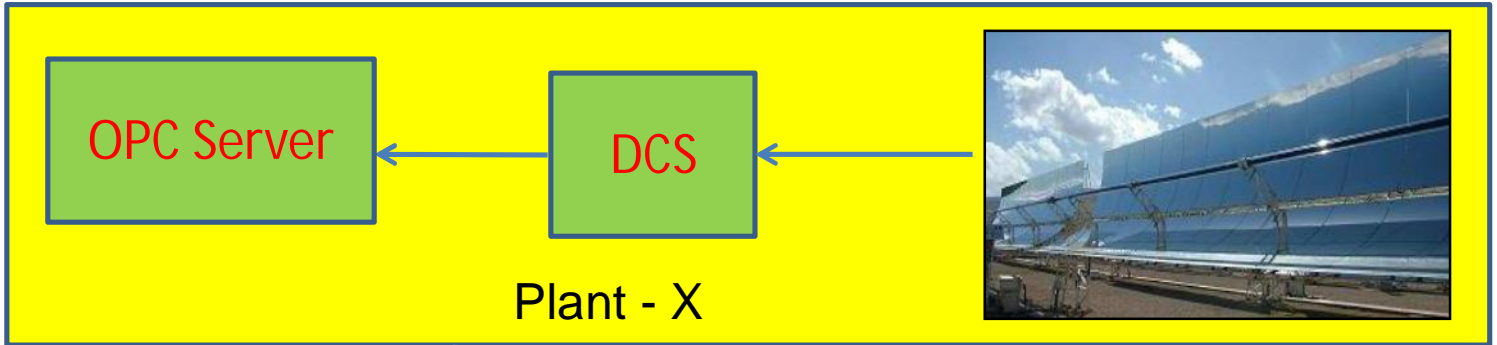


Plant

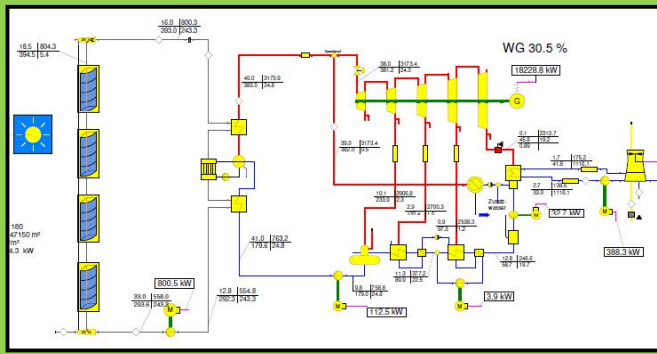
Time	Actual Power	Model Power	GAP
8 AM	14 MW	15 MW	1 MW

Analytic Programme

Simulations during PG Testing of CSP



DATA Remote Connectivity RESULTS



Plant Model

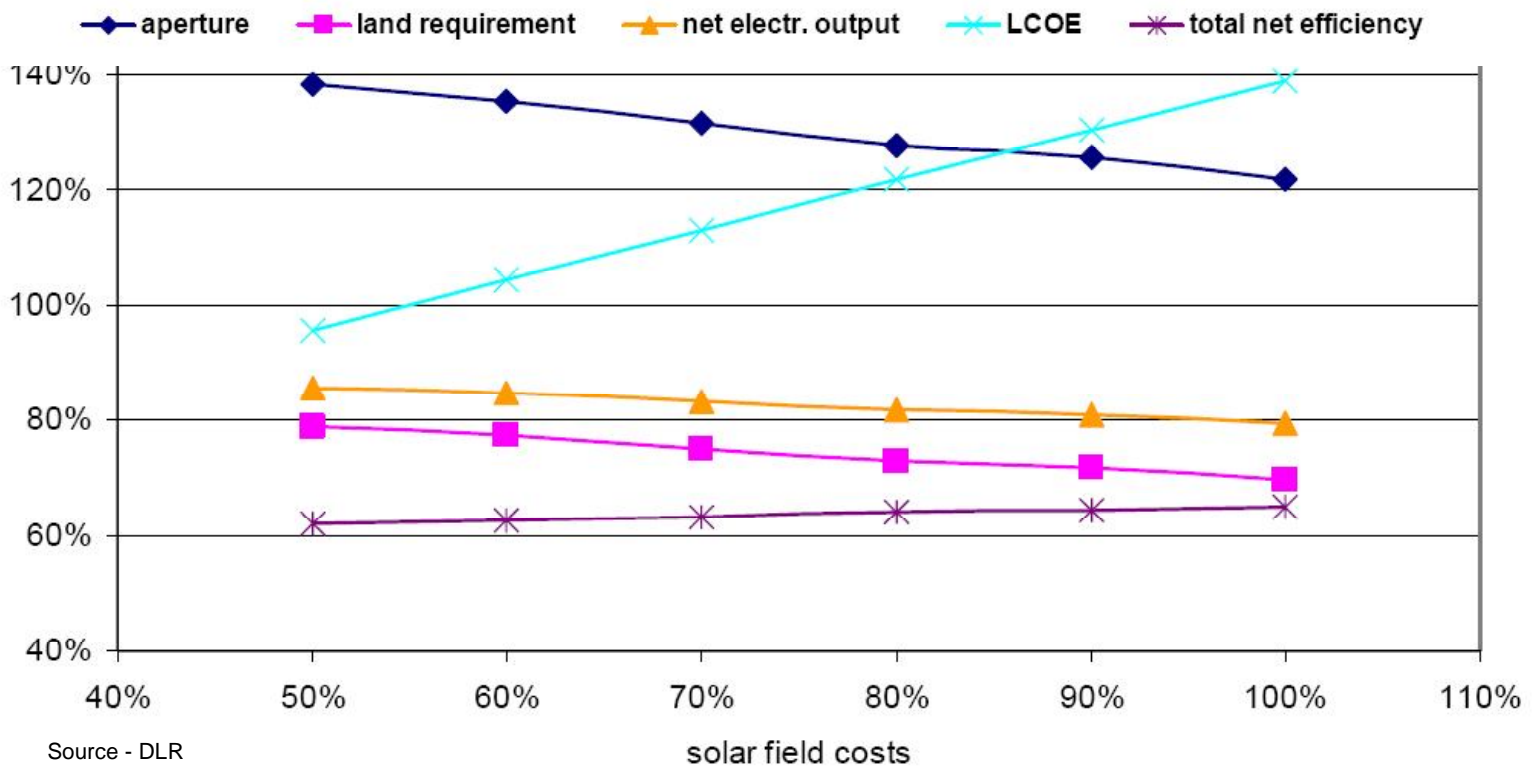
Time	Actual Power	Model Power	GAP
8 AM	14 MW	15 MW	1 MW

Analytic Programme

Simulation for Daily Performance monitoring of a Solar thermal plant



Case Study from DLR - Comparative study of PT and CLFR costing using Greenius S/W



Influence of the relative solar field costs of the linear Fresnel collector field (reference value is in each case the parabolic trough field with direct steam generation on the same site)



Thank
You

... Ideas & Solutions for Tomorrow

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Intelligent Combustion Optimisation as reaction to changing pulverised fuel properties – A Case Study

Dr .Peter Deeskow

12.04.2013



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- Plant details
- CO system „PIT Navigator“
- Targets
- Design of CO Solution
- Project execution
- Performance Test
- Results

Customers Targets

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Increasing boiler efficiency

- by reduction of average excess O_2
- by reduction of average flue gas temperature

- but keeping global and local CO level below certain limits to prevent wall corrosion

- for different mill combinations
- for different load demands
- for different coal blends

Plant Details

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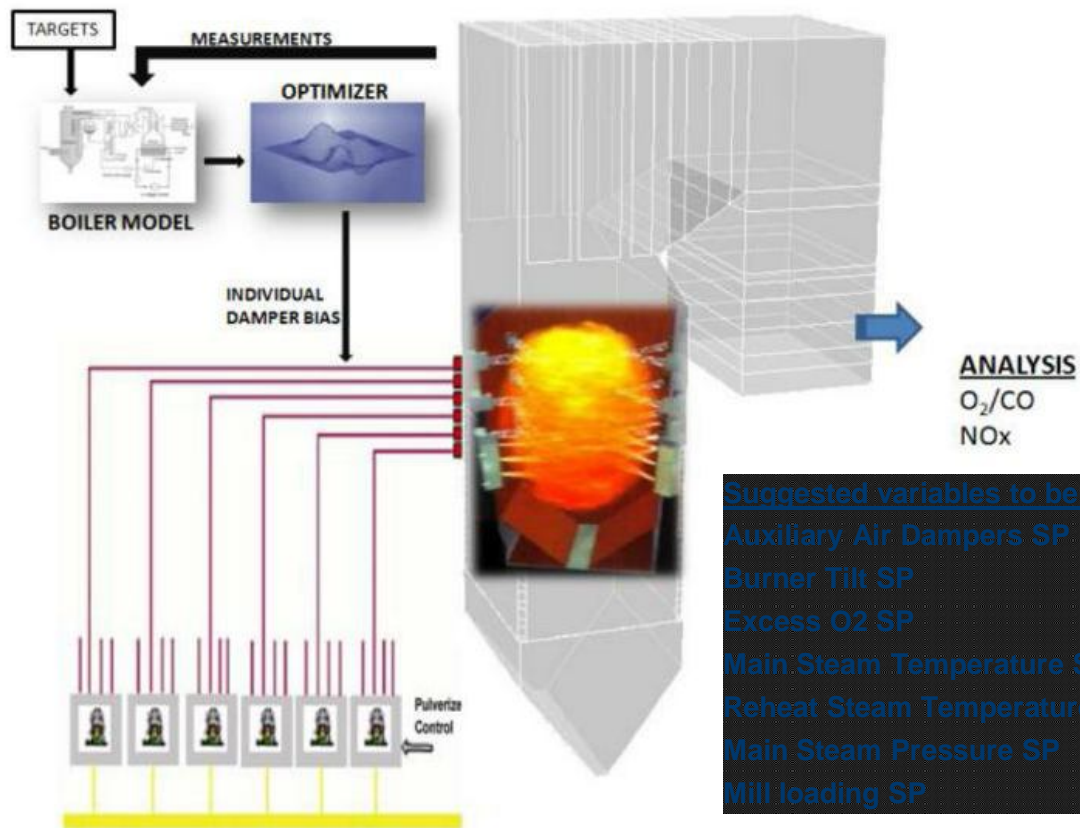
MALAKOFF Tanjung Bin Power station

- Unit #30
commissioned 2007
- 748MW_{el}
- 2350t/h steam
- IHI natural circulation
single drum with reheater
27.7m x 15.3m x 48.5m
- 30 LowNO_x Burners
each 13.4t/h pulverized coal from
different sources



Approach to Closed Loop Optimization

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Plant Audit

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- **On-site inspection**
 - mills
 - coal pipes
 - burners
 - boiler
 - control system
 - available measurements
 - available actuators
 - process interface
 - automatic vs. manual operation
 -
- **Data Mining on available process data**
 - estimation of controllability of combustion
 - identification of existing „weak“ control loops, e.g. steam temperature control
 - evaluation of optimisation potential
 -

Design of CO Deliverables / Guarantees

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Optimization core

- reduction of average excess O_2 ($\geq 0.6\%$ abs.)
- reduction of average flue gas temperature ($\geq 2.5^\circ\text{C}$)
- keeping certain (1st RH) metal temperatures below given limit

Online CFD

- visualisation of the impact of different coal types on combustion
- visualisation of combustion unbalances

Interfaces

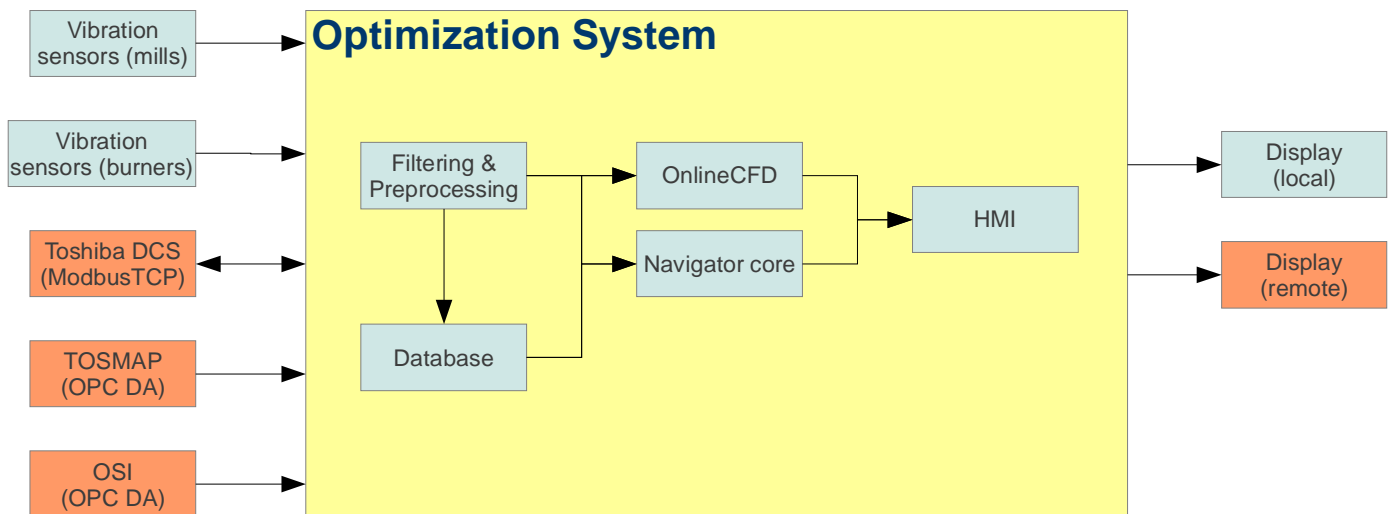
- process interfaces to DCS and OPC servers
- necessary changes in DCS for set-point biases
- setup of remote maintainance

Hardware

- mounting and connecting necessary computer hardware
- mounting and connecting vibration sensors and cabinets for mills and burners

Implementation Overview system setup

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Implementation Process interface

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DCS -> Optimization system

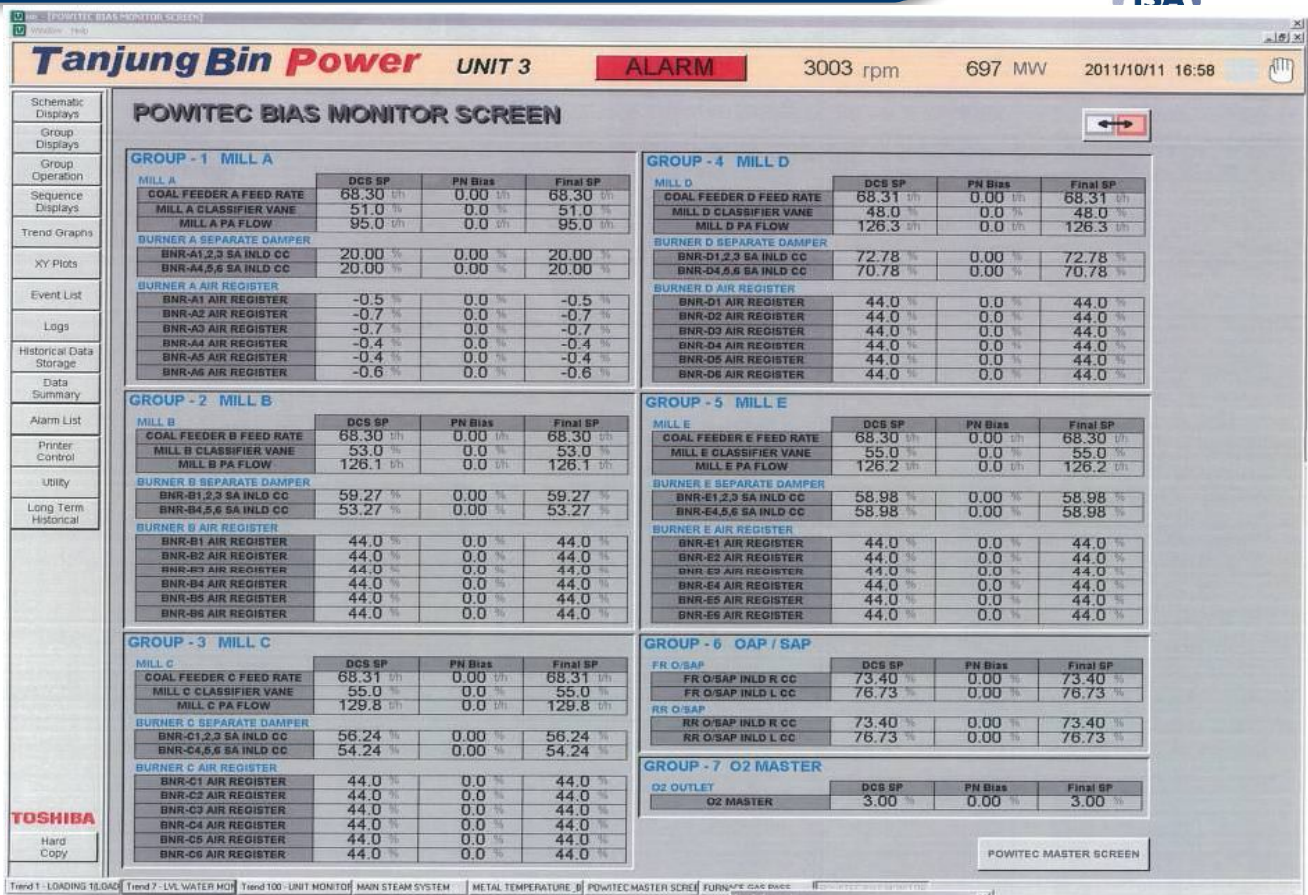
- air flows related to the boiler (burner + mills +OFA)
- coal flows into the mills
- emissions (furnace + chimney)
- flue gas temperatures in the furnace
- metal temperatures of super heaters and reheaters
- steam parameters of boiler (superheaters, reheaters, boiler)
- burner settings (swirl)
- mill parameters (motor amps, temperatures, pressure, speed, ...)
- ...

Optimization system -> DCS (biases)

- coal distribution between mills
- secondary air distribution between 10 groups feeding three burners each
- over fire air
- classifier vane of all mills
- o2 setpoint
- ...

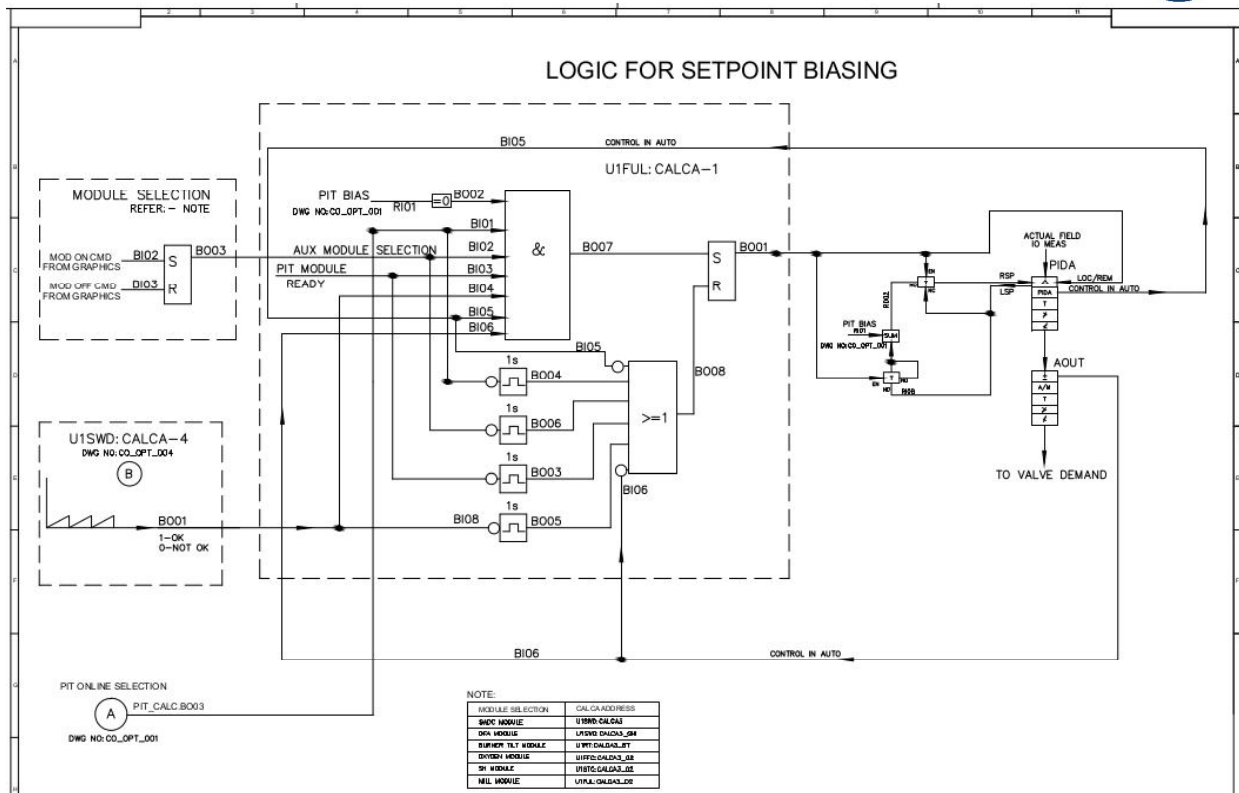
Implementation Bias Monitor

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Implementation Biasing & Loop tuning

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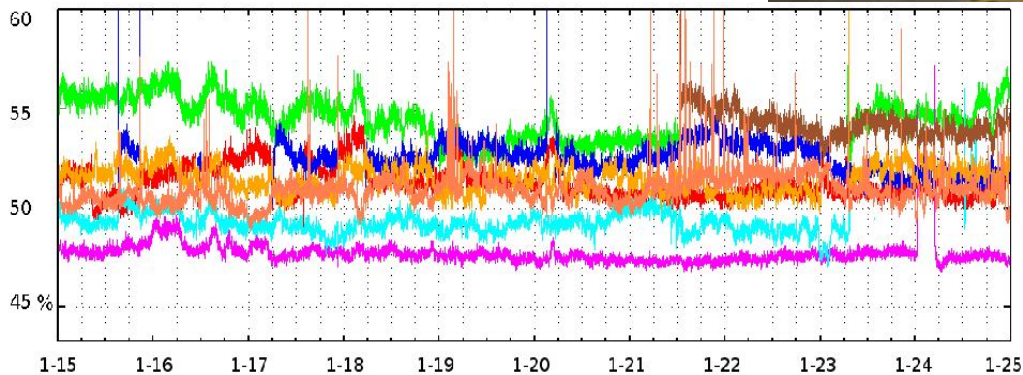


Implementation Vibration sensors (here: burners)

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- Fast sampling of vibration (better noise) sensors
- Vibration spectrum (frequency domain) instead of intensity used
- Result: Distribution of coal feed at each single burner at one mill



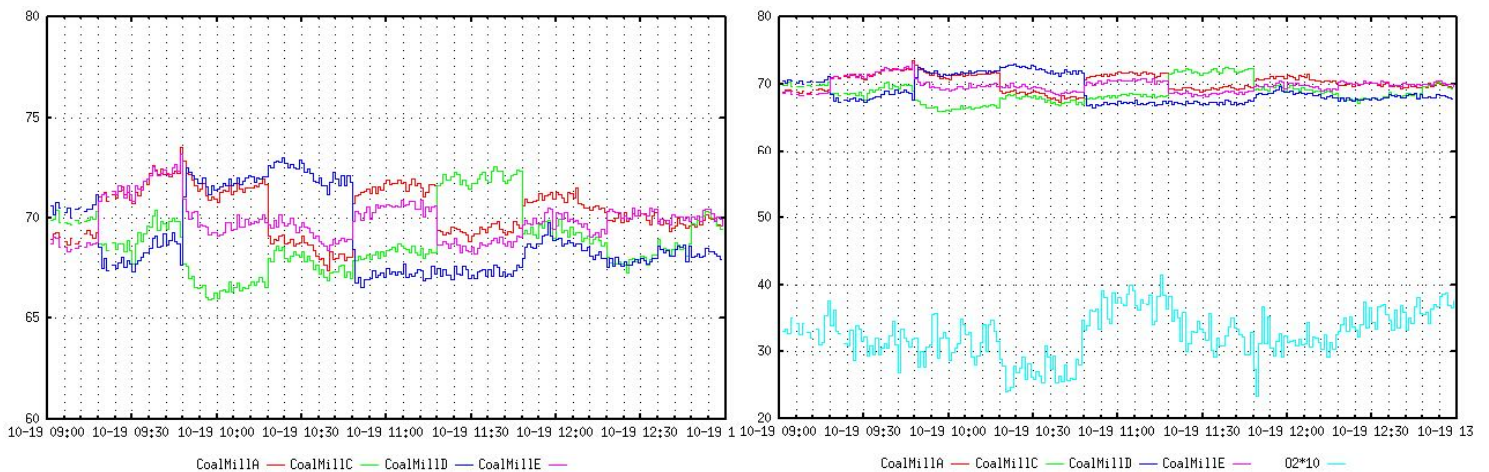
Implementation Process exploration

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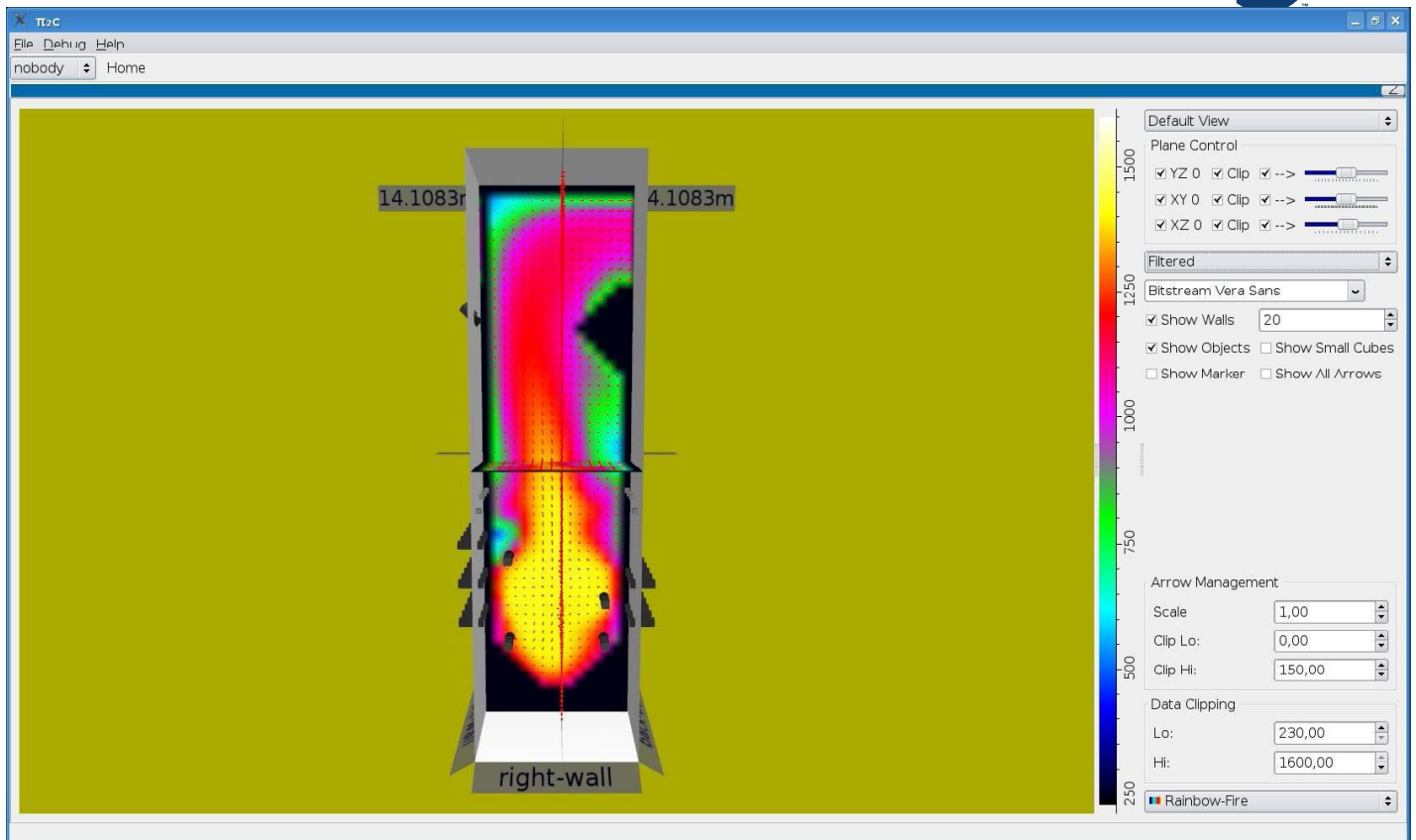
Optimization system should contain a module to carry out full automatic process exploration

- to acquire process data apart from normal operation following characteristic curves
- does not disturb „normal“ operation by maintaining production, limits, ...
- base of process data is expanded by potentially favourable working points



Implementation CFD

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Implementation Advanced Process Control (APC)

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- **A multi dimensional, model based controller is required**
- **The model is not „hand made“, but „tached“ from process data, e.g.**
 - existing process data (temperatures, volume & mass flows, pressures, ...)
 - coal distribution (see: vibration sensors at burners)
 - coal properties (not mentioned: vibration sensors at mills, ...)
 - targets (reduction of excess O₂, reduction of flue gas temperature, ...)
- **A ready to use model can be used for simulation**
 - What will happen if I would change a single set-point or a group of set-points?
- **Optimiser uses model to find best possible action plan with regards to targets**
- **Safety layer passes or blocks action plan to be carried out online**

Performance Test Choosing comparable periods

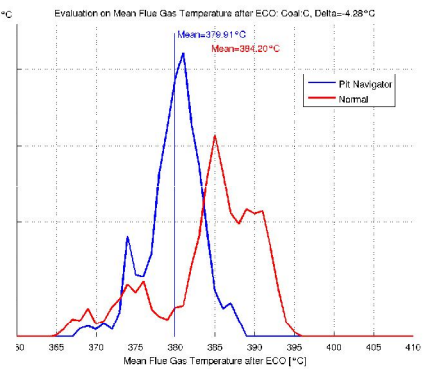
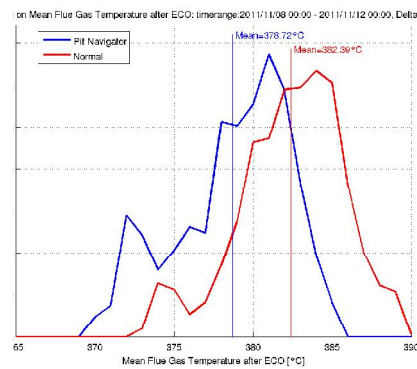
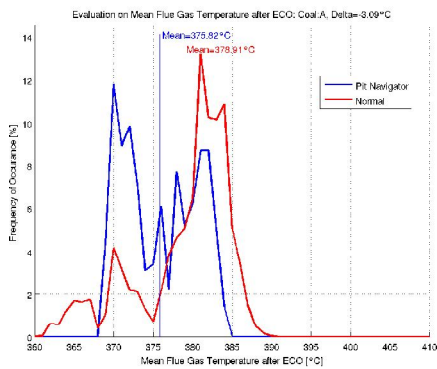
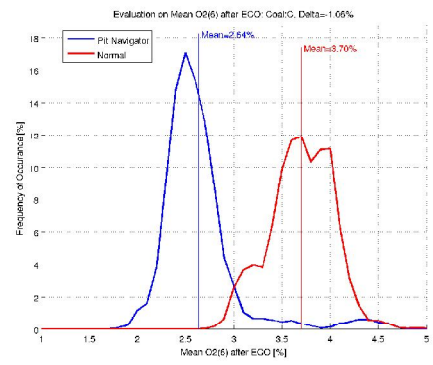
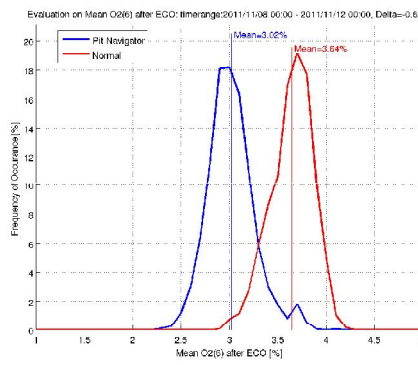
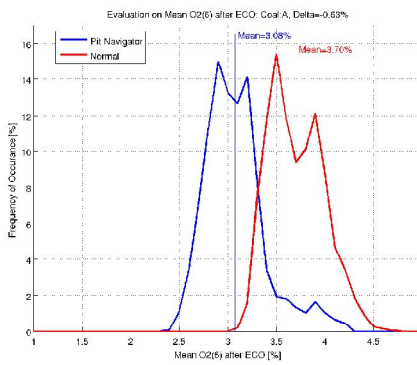
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Label	Coal type (Nav on)	Coal type (Nav off)	Gross power ~ΔMW	Deactivated Mill	Comparable
I	40% MSJ 60% DRY	30% PQ 70% DRY	7	D D	Yes
II	40% MSJ 60% DRY	40% MSJ 60% DRY	0,3	D D	Yes
III	20% MSJ 80% BYN	20% ENVB 80% BYN	10	B, C C	Yes
IV	40% KYN 60% DUI	40% PQ 60% DUI	13	C, A D	No, because of incompatible mill constellation
V	40% KYN 60% WHN	40% ADM 60% WHN	20	A D	No, because of incompatible mill constellation

Performance Test Distribution of O2 and exit gas temp.

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Performance Test Results for comparable periods

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Label	$\Delta O_2/\%$	$\Delta T/^\circ C$	CO/mg/Nm ³
I	-0,63	-3,09	91
II	-0,62	-3,67	72
III	-1,06	-4,28	90

Performance Test Overall Results

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- **O₂ reduced by 0.6% to 0.8% abs.**
- **Flue gas temperature reduced by up to 4°C**
- **Coal Flow decreased by 0.5 t/h/mill = 15.600t/a**
- **IDF/FDF savings = 2700 MWh/a**



**Thank
You**

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SUBSTATION AUTOMATION SYSTEM ESSENTIALS



SUBSTATION AUTOMATION SYSTEM TOPICS OF DISCUSSION



Current
Industry
Focus

System
Architecture

Elements of
SAS

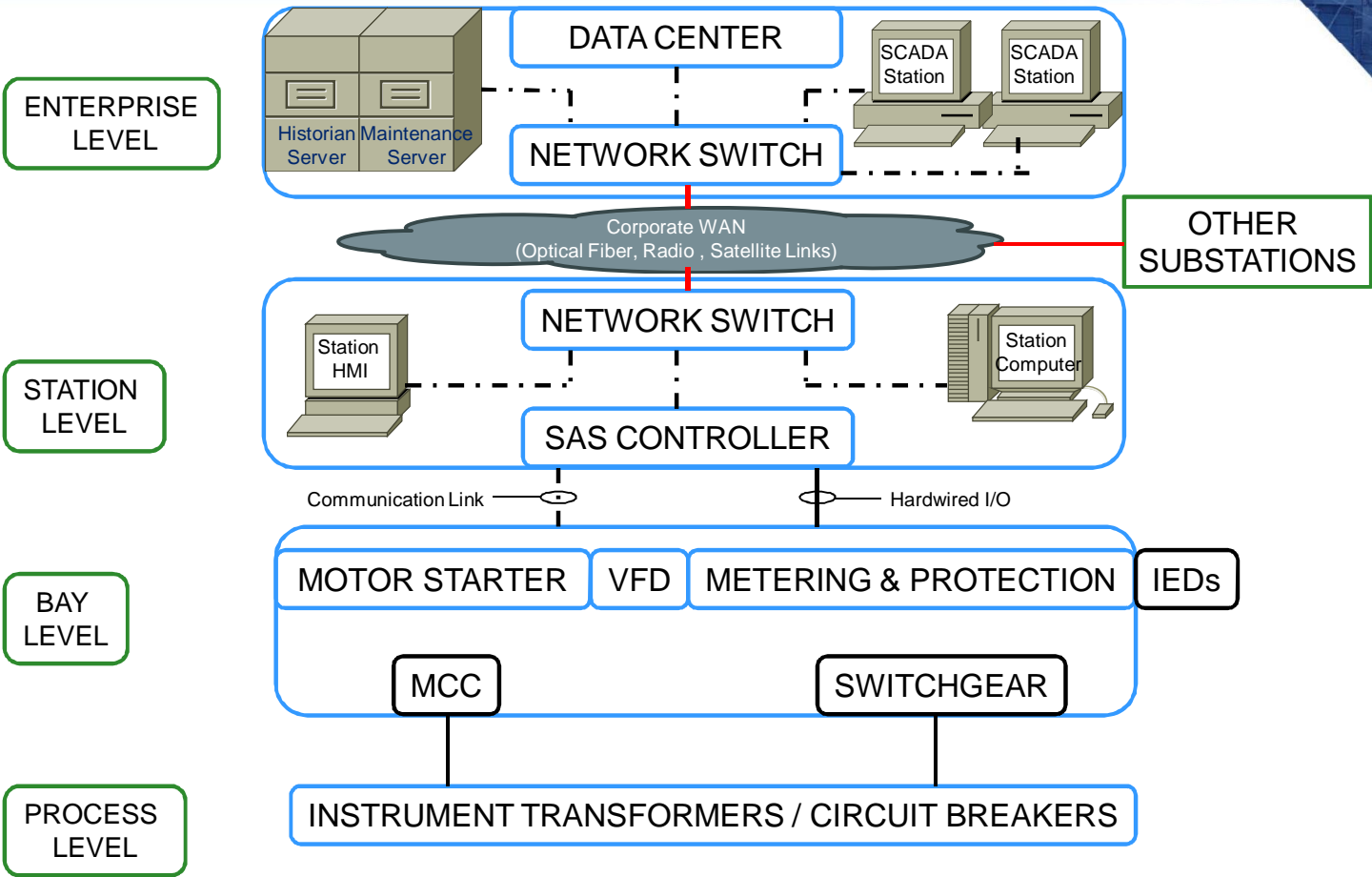
Challenges

SUBSTATION AUTOMATION SYSTEM INDUSTRY FOCUS



- ◆ Enhanced Reliability
 - Power available at all times
- ◆ Asset Management
 - Predictive Maintenance
- ◆ Improved Operation and Maintenance
 - Minimum Downtime
- ◆ Life Extensions
 - Better utilization of resources
- ◆ Smart Grid

SUBSTATION AUTOMATION SYSTEM SYSTEM ARCHITECTURE



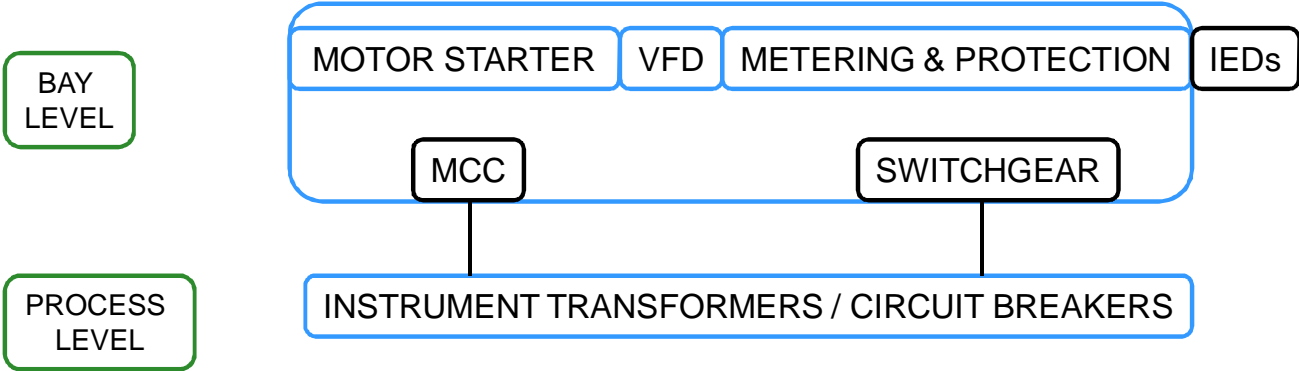
SUBSTATION AUTOMATION SYSTEM SYSTEM ARCHITECTURE



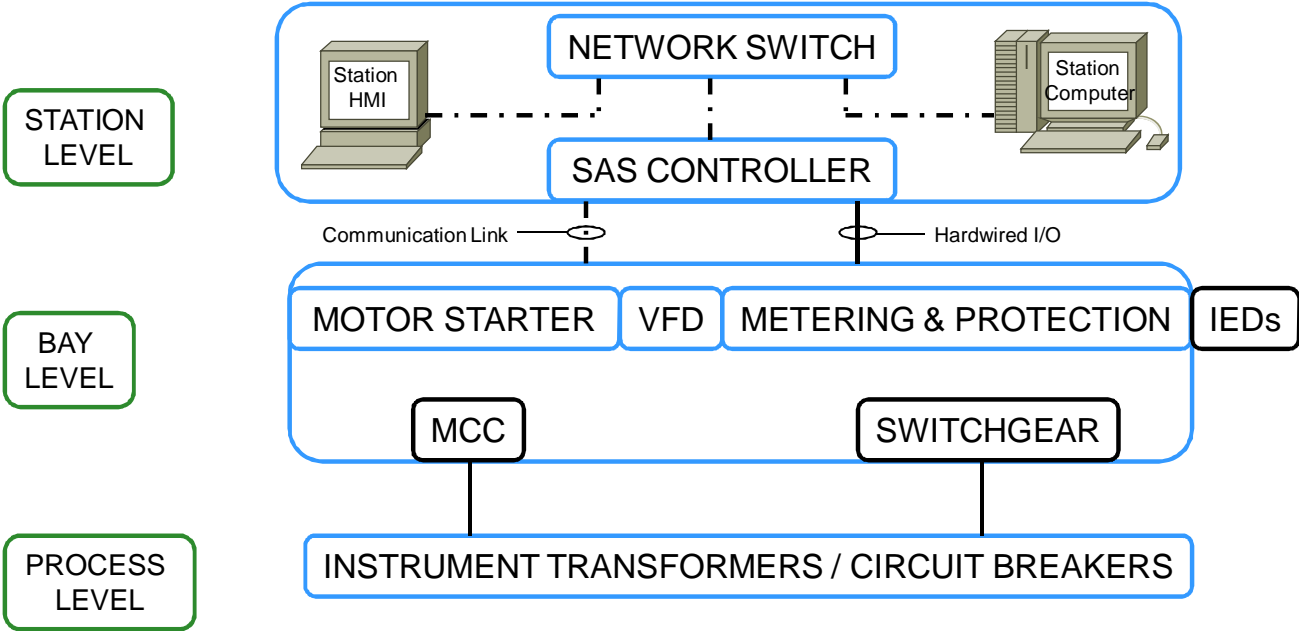
PROCESS
LEVEL

INSTRUMENT TRANSFORMERS / CIRCUIT BREAKERS

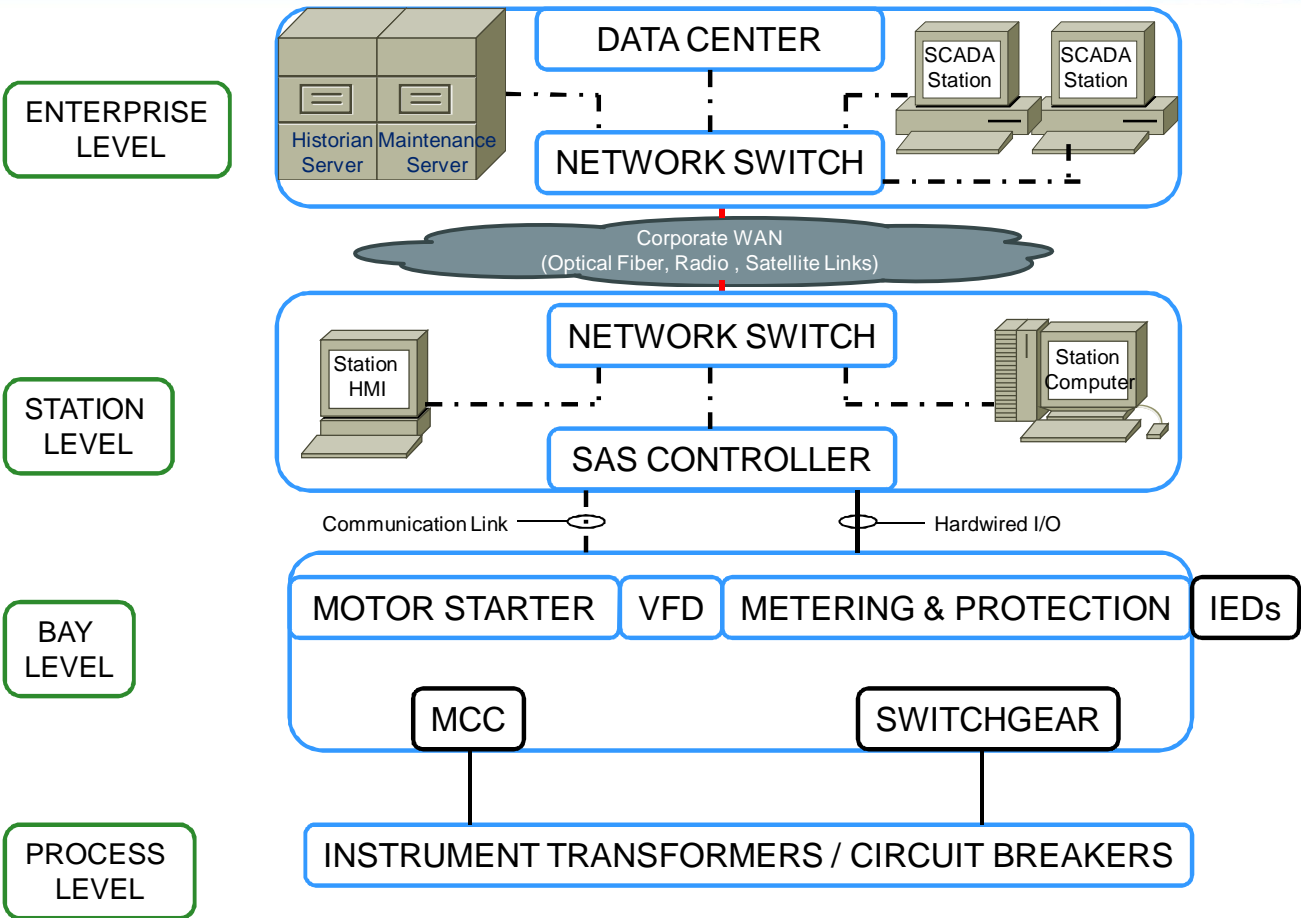
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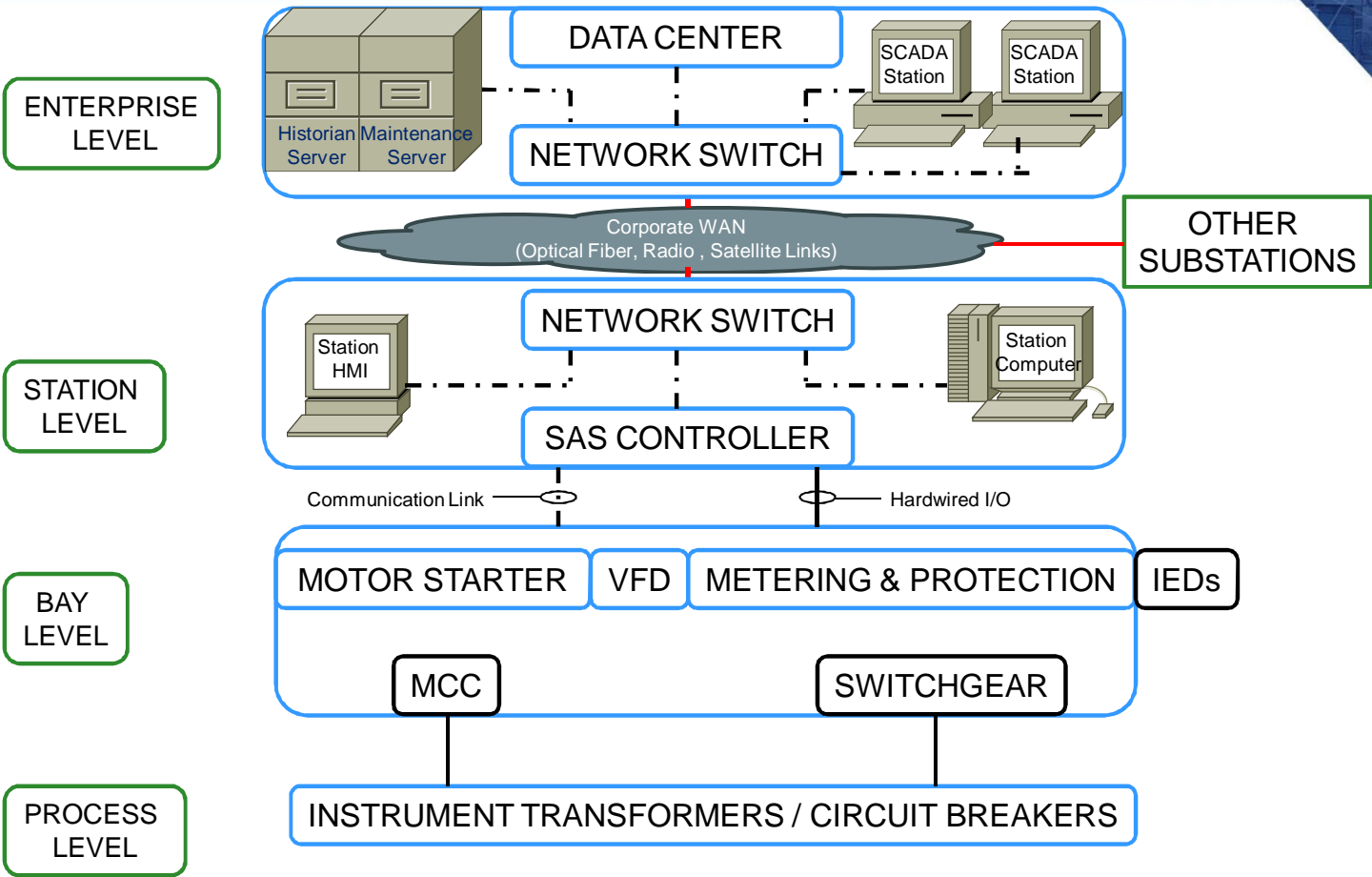
SUBSTATION AUTOMATION SYSTEM SYSTEM ARCHITECTURE



SUBSTATION AUTOMATION SYSTEM SYSTEM ARCHITECTURE



SUBSTATION AUTOMATION SYSTEM SYSTEM ARCHITECTURE



SUBSTATION AUTOMATION SYSTEM ELEMENTS OF SAS



- ◆ Intelligent Electronic Device (IED)
 - Key Element of SAS
 - Microprocessor based
 - Capability to integrate various functions (control, metering, protection and data acquisition) into a single device
 - Electronic Multifunction Meters, Digital Relays

SUBSTATION AUTOMATION SYSTEM

ELEMENTS OF SAS



◆ SAS Controller

- PLC or RTU based
- Polls IEDs for analog and status signals for monitoring and control of the substation
- Data concentrator for the overall SCADA
- Hardwired Input / Output for the primary equipment control and protection
- Manages Communications

SUBSTATION AUTOMATION SYSTEM ELEMENTS OF SAS



◆ Station Computer

- Server grade computer
- Accompanies SAS Controller

◆ User Interface HMI

- Provides view of essential information and activities in hierarchical displays
- Client to the Station Computer

SUBSTATION AUTOMATION SYSTEM ELEMENTS OF SAS



- ◆ Supervisory Control and Data Acquisition (SCADA) System
 - Resides at the Enterprise level of SAS
 - Collects time Critical operational data for monitoring and control of the substation
 - Instantaneous values and status like Volt, Ampere, KVA, KW, breaker status etc

SUBSTATION AUTOMATION SYSTEM ELEMENTS OF SAS



◆ Data Center

- Resides at the Enterprise level of SAS
- Collects time Critical operational data for monitoring and control of the substation
- Instantaneous values and status like Volt, Ampere, KVA, KW, breaker status etc
- Also collects non operational data like event summaries

SUBSTATION AUTOMATION SYSTEM COMMUNICATION



◆ Communication

- Most important element of SAS
- Key requirements of communication systems include, but not limited to,
 - High Speed IED to IED communication
 - Networkable throughout the enterprise
 - High availability
 - High reliability
 - Standards based
 - Multi vendor interoperability
 - Support for file transfer
 - Plug and Play
 - Support for security

SUBSTATION AUTOMATION SYSTEM COMMUNICATION



◆ Communication Contd...

- Several factors for selecting right protocol
 - The communicating devices SCADA to SAS controller or IED to IED etc.
 - Data requirements, Speed and reliability
 - Technology developments
 - Continuous vendor support for the life time
 - Non proprietary

SUBSTATION AUTOMATION SYSTEM CHALLENGES



- ◆ Meeting Performance Requirements
 - Response time, Safety and Reliability
 - Compromise between Cost and Performance
- ◆ Communication Protocol and Topology
 - Communication needs are different
 - Various available options with inherent constraints

SUBSTATION AUTOMATION SYSTEM CHALLENGES



- ◆ Technological Advances
 - Fast changing technology
 - Timing of installation
- ◆ Cyber Security
 - ANSI/ISA 99 and IEC/ISA 62443 recommendations
 - Firewalls, DMZ, Conduits, Defense in Depth security policies

SUBSTATION AUTOMATION SYSTEM BIBLIOGRAPHY

A blue banner with a globe and a substation background. The globe is on the right side, showing the Americas. The background of the banner shows a substation with power lines and towers.

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SUBSTATION AUTOMATION SYSTEM QUESTIONS





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Analysis of Power System Failure at IFFCO Aonla and subsequent measures to enhance reliability—a case study



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IFFCO

Introduction—the IFFCO Aonla Complex

IFFCO-Aonla Fertiliser complex consists of

- Two streams of Ammonia Plants and
- Four streams of Urea Plants. (approx 6600 MTPD product)
- Two nos. of Gas Turbine Generators (GTGs)
- Total Electrical power requirement of about 30MW
- Additionally there is back-up connection of capacity 4.5 MW. with the State Grid (UPPCL).and 2 nos. Auxiliary Mains Failure(AMF) DG sets 1MW each(approx)
- Ammonia Plants are highly energy intensive & critical
- Outage of Ammonia Plants are extremely costly.
- However Urea Plants outage are much less costly.

The Failures of Power System :

- There has been instances of failure of one GTG.
- This in turn caused tripping of second GTG as well as UPPCL feeder on overload
- This has caused major power outage at the complex including tripping of not only the Urea Plants but also the Ammonia Plants .
- By system design such power outage and tripping of both Ammonia plants are not supposed to happen,
- Such situation is very unsafe for plants and
- It was found attributable to the slow response of the Load Management System(LMS) PLC.

Actions Required :

For such power crisis condition it was felt prudent to ensure healthiness/running of

- at least one GTG,
- both Ammonia Plants (at least the Primary Reformers in worst case),
- Cooling water system and Lube oil system of major rotary machines.
- Tripping of all Urea Plants may be allowed to save one GTG and Ammonia Plants.
- Also actions to take place automatically through interlocks and communication gap/confusion and delays thereof are to be avoided for manual actions.
- Steam crisis must not get superimposed on power crisis.
- Plant operating procedures would be updated accordingly.