Milestone Review Flysheet 2018-2019

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Vehicle Properties	
Total Length (in)	122.5"
Diameter (in)	4"
Gross Lift Off Weigh (lb)	23.0992 lbs
Airframe Material(s)	G12 Fiberglass
Fin Material and Thickness (in)	Fiberglass (0.375 in)
Coupler Length(s)/Shoulder Length(s) (in)	Minimum 4"

Motor Properties		
Motor Brand/Designation	Cesaroni K1085WT	
Max/Average Thrust (lb)	2.654/2.454	
Total Impulse (lbf-s)	5.32	
Mass Before/After Burn (lb)	5.357/2.714	
Liftoff Thrust (lb)	450.5	
Motor Retention Method	Aeropack 75mm Retainer	

Stability Anal	ysis
Center of Pressure (in. from nose)	81.2251
Center of Gravity (in. from nose)	96.1526
Static Stability Margin (on pad)	3.71
Static Stability Margin (at rail exit)	5.51784
Thrust-to-Weight Ratio	6.54:1
Rail Size/Type and Length (in)	96"
Rail Exit Velocity (ft/s)	66.445

Ascent Analysis	
Maximum Velocity (ft/s)	674.9606
Maximum Mach Number	0.61
Maximum Acceleration (ft/s^2)	693.85
Target Apogee (ft)	4600
Predicted Apogee (From Sim.) (ft)	5257.94

Recovery System Properties - Overall	
Total Descent Time (s)	72.457
Total Drift in 20 mph winds (ft)	2541.570637

Recovery System Properties - Energetics		
Ejection System Energetics (ex. Black Powder)		F4 Black Powder
Energetics Mass - Drogue Chute (grams)	Primary	1.9907904
	Backup	2.78710656
Energetics Mass - Main Chute (grams)	Primary	3.1532088
	Backup	4.41449232
Energetics Mass - Other	Primary	
(grams) - If Applicable	Backup	

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Recovery System P	Properties - I	Recovery Electronics
Primary Altimeter Make/Model		Stratologger CF Flight Computer
Secondary Altimeter Mal	ke/Model	RRC3 Flight Computer
Other Altimeters (if app	licable)	
Rocket Locator (Make/	Model)	Whistle GPS
Additional Locators (if applicable)		APRSDroid
Transmitting Frequencies (all - vehicle and payload)		***Required by CDR*** (Complete on pages 3 and 4)
Describe Redundancy Plan (batteries, switches, etc.)	The rocket has a dual redundancy system where the two altimeters are on two completely different circuits and are not connected in any way. They are also two different flight computers so if one has a bug, the other will be able to execute the commands still.	
Pad Stay Time (Launch Configuration)	The rocket will be able to sit on the launch pad for at least 2 hour minimum	

Recovery System Properties - Drogue Parachute					
Ma	nufacturer/Mo	del	Fruity Chutes		
Size o	or Diameter (in	or ft)	18"		
Main Altim	neter Deployme	ent Setting	Apogee		
Backup Alti	meter Deploym	ent Setting	1 seconds after Apogee		
Velocit	y at Deploymen	it (ft/s)	97	97.936	
Terminal Velocity (ft/s)		79.87			
Recovery Harness Material, Size, and Type (examples - 1/2 in. tubular Nylon or 1 in. flat Kevlar strap)		1" Tubular Nylon			
Recovery Harness Length (ft)		25 ft			
Harness/Airframe Interfaces Machine-clo tub		osed stainless st ular nylon shoc	eel eye bolts, k cord		
Kinetic	Section 1	Section 2	Section 3	Section 4	
Energy of Each Section (Ft-lbs)	710.810709	303.782223	898.880706		

Recovery System Properties - Main Parachute				
Ma	nufacturer/Mo	del	Fruity Chutes	
Size o	or Diameter (in	or ft)	72"	
Main Altime	ter Deploymen	t Setting (ft)	600	
Backup Altim	eter Deployme	nt Setting (ft)	500	
Velocit	y at Deploymen	ıt (ft/s)	79	9.87
Terr	ninal Velocity (f	rt/s)	16.41	
Recovery Harness Material, Size, and Type (examples - 1/2 in. tubular Nylon or 1 in. flat Kevlar strap)		1" Tubular Nylon		
Recovery Harness Length (ft)		25 ft		
Harness/Airframe Interfaces Machine-clo tub		osed stainless st ular nylon shoc	eel eye bolts, k cord	
Kinetic	Section 1	Section 2	Section 3	Section 4
Energy of Each Section (Ft-lbs)	30.00569949	12.82366456	37.94476364	

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	Device of		
	Overvi	ew	
Payload 1 (official payload)	The payload is a rover that has a camera attached to the top. The rover is cyli moving. The task of the rover after being released is to find a colored band or to the band, the rover will then take a picture with the camera and store it on have complet	ndrical in shape with two wheels and a t the rocket and move towards the rocket an SD card inside the rover. The programed its task.	ail to stabilize the rover while it is et. Once it has located and moved m will then stop and the rover will
	Overvi	ew	
Payload 2 (non-scored payload)			

Test Plans, Status, and Results	
Ejection Charge Tests	Build up the rocket as though it were flight ready. Then, the charge will be ignited via wires out to a 9V battery at a safe distance (25 ft). A successful test is defined by the rocket separating at the designed point and the parachutes fully being ejected from the body tube. There should be no damage to the rocket body, parachute, or surrounding area. Both drogue and main chute ejections will be tested for both subscale and full scale vehicles. These tests will be performed as soon as the vehicle is ready.
Sub-scale Test Flights	The subscale will be flown at an organized launch on a CTI J295. It will be launched twice, the first time without the air brakes live to test the altitude without the air brakes. The air brake electonics will still be inside the rocket for this flight, but it won't be powered. The second test flight will test the air brakes and how close it can get the vehicle to our desired altitude. The air brakes will be ground tested before flying on the rocket. The launch is scheduled for December 8th, 2018 on Lucerne Dry Lake with ROC. The payload will NOT be flown on the subscale and instead replaced with ballast.
Vehicle Demonstrati on Flights	The full scale will be flown twice before the Huntsville launch. The first will be without the air brakes active to test the altitude of the rocket. After ground testing the rover release system, it will be flown on the first flight to test it in flight conditions. A second flight will include live air brakes to test how close the air brakes can get the vehicle to the desired altitude. The fullscale launch is currently set for January 12, 2019. Alternate dates for the launch are February 2nd and 9th.
Payload Demonstrati on Flights	The payload will be ground tested as soon as it has been completed. In addition to the rover being ground tested, we will test the entire release system from start to finish while grounded. After there is proof that the system has been designed correctly, the system will be launched with the fullscale launch on January 12th. It will be flown during both flights. Batteries will be switched as necessary.
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Transmitter #1			
Location of transmitter:	Big Red Bee		
Purpose of transmitter:	GPS on the Payload		
Brand		RF Output Power (mW)	16 mW
Model		Specific Frequency used by team (MHz)	433MHz **can be moved easily
Handshake or frequency hopping? (explain)	No		
Distance to closest e-match or altimeter (in)	33.5 inches		
Description of shielding plan:	Will add Super Shield from MG Chemicals around sensitive electonics (eg Avionics Bay)		

Transmitter #2			
Location of transmitter:	Whistle GPS		
Purpose of transmitter:	GPS on the rocket vehicle		
Brand		RF Output Power (mW)	unknown
Model		Specific Frequency used by team (MHz)	Cellphone Frequencies
Handshake or frequency hopping? (explain)	No		
Distance to closest e-match or altimeter (in)	71.5 inches		
Description of shielding plan:	Will add Super Shield from MG Chemicals around sensitive electonics (eg Avionics Bay)		

Transmitter #3		
Location of transmitter:		
Purpose of transmitter:		
Brand	RF Output Power (mW)	
Model	Specific Frequency used by team (MHz)	
Handshake or frequency hopping? (explain)		
Distance to closest e-match or altimeter (in)		
Description of shielding plan:		

Transmitter #4		
Location of transmitter:		
Purpose of transmitter:		
Brand	RF Output Power (mW)	
Model	Specific Frequency used by team (MHz)	
Handshake or frequency hopping? (explain)		
Distance to closest e-match or altimeter (in)		
Description of shielding plan:		

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Iransmitter #5		
Location of transmitter:		
Purpose of transmitter:		
Brand	RF Output Power (mW)	
Model	Specific Frequency used by team (MHz)	
Handshake or frequency hopping? (explain)		
Distance to closest e-match or altimeter (in)		
Description of shielding plan:		

Transmitter #6		
Location of transmitter:		
Purpose of transmitter:		
Brand	RF Output Power (mW)	
Model	Specific Frequency used by team (MHz)	
Handshake or frequency hopping? (explain)		
Distance to closest e-match or altimeter (in)		
Description of shielding plan:		

Additional Comments







