NEW

RIEGL VQ°-580 II

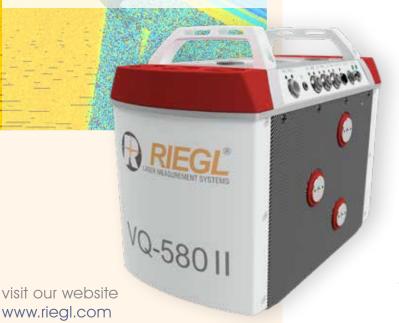
- high accuracy ranging based on RIEGL Waveform-LiDAR technology
- high laser pulse repetition rate up to 2MHz
- measurement rate up to 1,250,000 measurements/sec
- perfectly linear and parallel scan lines
- wide field of view of 75°
- excellently suited to measure on snow & ice
- interfaces for up to 5 optional cameras
- mechanical and electrical interface for IMU/GNSS integration
- removeable storage card and integrated Solid State Disk (SSD) for data storage
- compact, & lightweight design
- compatible with stabilized platforms and even small hatches
- seamless integration and compatibility with other RIEGL ALS systems and software packages

In further development of the *RIEGL* VQ-580 Airborne Laser Scanner Series – the new *RIEGL* VQ-580 II presents itself in a completly new design that successfully takes up the already proven qualities and leads them to a new standard of performance and user-friendliness.

Its new sophisticated design allows to further reduce the overall weight and enables the seamless integration into stabilized platforms, e.g. standard gyromounts, and also into even small hatches. The scanner is well suited for the use in manned aircrafts like helicopters, small fixedwing aircrafts, or ultra-light planes.

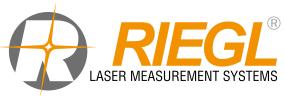
Based on *RIEGL*'s proven Waveform-LiDAR technology, the VQ-5801I provides highly accurate point clouds, excellent vertical target resolution, calibrated reflectance readings, and pulse shape deviation for unsurpassed information content on each single measurement. With a measurement rate of up to 1,250,000 measurements/second and an extremely wide field of view of 75°, the scanner offers itself as the first choice for airborne surveying applications like corridor mapping, city modeling, and agriculture & forestry. The laser wavelength makes it especially suited for measurements on ice and snow.

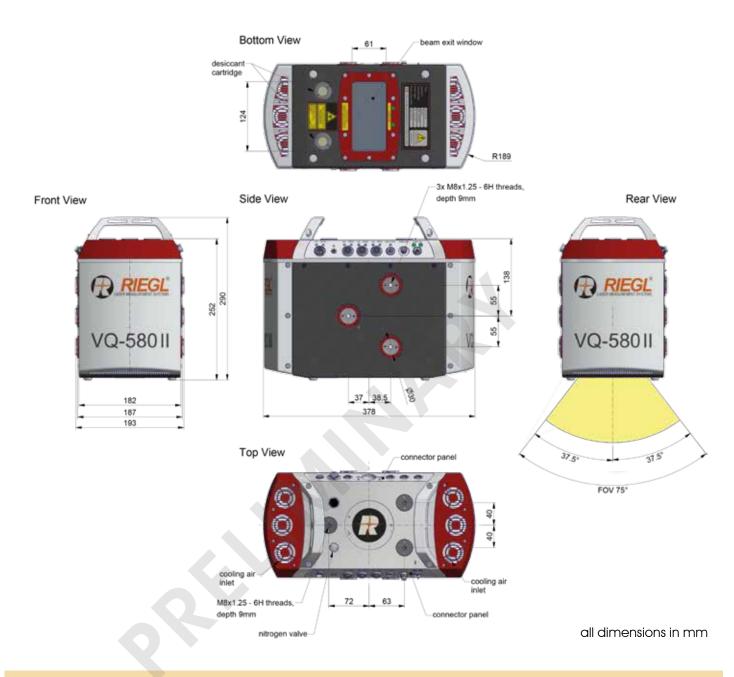
An easy to remove CFast® storage card and an integrated Solid State Disk and/or the option for streaming the scan data via LAN TCP/IP interface are provided for data transfer and storage.



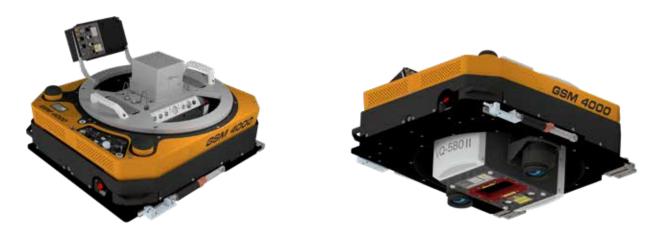
Typical applications include

- Corridor Mapping
- Agriculture & Forestry
- Especially suited for Glacier Mapping and Snowfield Mapping
- Moist Grassland Mapping
- City Modeling

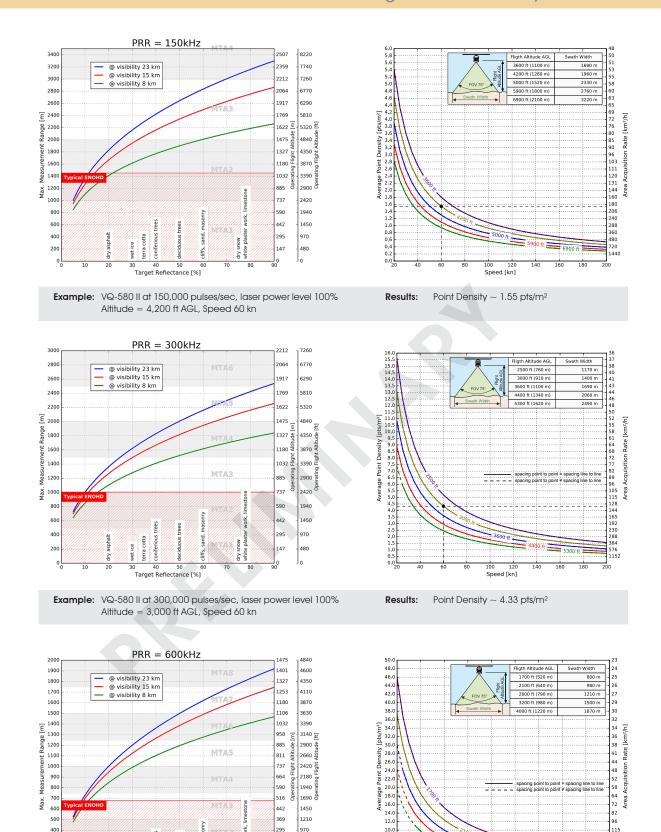




RIEGL VQ®-580 II Installation Example



RIEGL VQ-580 II installed on GSM-4000 stabilized platform to be used in a helicopter or fixed-wing aircraft



The following conditions are assumed for the Operating Flight Altitude AGL

Example: VQ-580 II at 600,000 pulses/sec, laser power level 100%

Altitude = 3,200 ft AGL, Speed 60 kn

- ambiguity resolved by multiple-time-around (MTA) processing
- $\bullet \ \text{target size} \geq \text{laser footprint} \\$

300

200

- average ambient brightness
- roll angle $\pm 5^{\circ}$

Results:

 \bullet operating flight altitude given at a FOV of +/- 37.5°

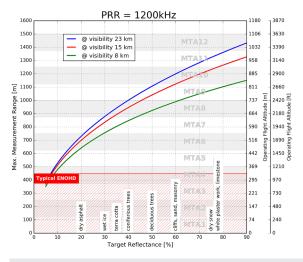
Point Density ~ 8.12 pts/m²

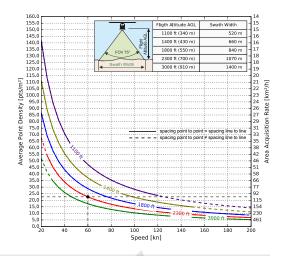
221

147 - 480

730

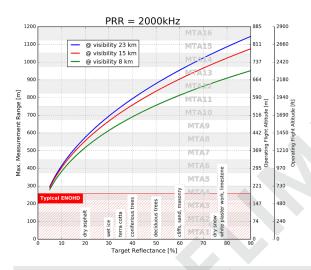
Maximum Measurement Range & Point Density RIEGL VQ®-580 II

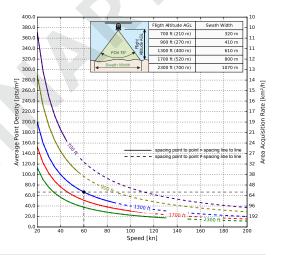




Example: VQ-580 II at 1,200,000 pulses/sec, laser power level 100% Altitude = 2,300 ft AGL, Speed 60 kn

Results: Point Density ~ 22.58 pts/m²





Example: VQ-580 II at 2,000,000 pulses/sec, laser power level 100% Altitude = 1,300 ft AGL, Speed 60 kn

Results: Point Density ~ 66.60 pts/m²

The following conditions are assumed for the Operating Flight Altitude AGL

- ambiguity resolved by multiple-time-around (MTA) processing
- $\bullet \ \text{target size} \geq \text{laser footprint} \\$
- average ambient brightness
- roll angle $\pm 5^{\circ}$
- \bullet operating flight altitude given at a FOV of +/- 37.5°

Laser Product Classification

Class 3B Laser Product according to IEC 60825-1:2014

The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007.

The instrument must be used only in combination with the appropriate laser safety box.



Range Measurement Performance

Measuring Principle

echo signal digitization, online waveform processing, time-of-flight measurement, multiple target capability

Laser Pulse Repetition Rate PRR 1)	150 kHz	300 kHz	600 kHz	1200 kHz	2000 kHz
Max. Measuring Range $^{2 3 }$ natural targets $\rho \geq 20$ % natural targets $\rho \geq 60$ %	1850 m	1350 m	1000 m	750 m	550 m
	2850 m	2150 m	1600 m	1200 m	950 m
Max. Operating Flight Altitude $^{2)}$ Above Ground Level (AGL) natural targets $\rho \geq 20$ % natural targets $\rho \geq 60$ %	1350 m	1000 m	750 m	550 m	400 m
	4450 ft	3280 ft	2450 ft	1800 ft	1300 ft
	2100 m	1600 m	1200 m	900 m	700 m
	6900 ft	5250 ft	3950 ft	2950 ft	2300 ft
NOHD ⁵⁾	160 m	110 m	70 m	40 m	30 m
ENOHD ⁵⁾	1020 m	710 m	480 m	310 m	200 m
Max. Number of Target per Pulse (1)	15	15	15	9	5

2) Typical values for average conditions and average ambient brightness. In bright sunlight, the max. range is shorter than under an overcast sky.

3) The maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km.

Range ambiguities have to be resolved by multiple-time-around processing. Typical values for reflectivity $\rho \geq 60\%$, max. effective FOV 75°, additional roll angle \pm 5°

5) Nominal Ocular Hazard Distance (NOHD) and Extended Nominal Ocular Hazard Distance (ENOHD), based upon MPE according to IEC 60825-1:2014, for non-persisting beam viewing (less than 600 laser pulses within a time period of 10 s) and non overlapping beam footprints.

NOHD and ENOHD increase when number of laser pulses exceeds this limit (persistent viewing).

6) If more than one target is hit, the total laser transmitter power is split and, accordingly, the achieveable range is reduced

Minimum Range Accuracy 7) 9) Precision 8) 9)

Laser Pulse Repetition Rate 10)

Max. Effective Measurement Rate

Echo Signal Intensity Laser Wavelength Laser Beam Divergence

7) Accuracy is the degree of conformity of a measured quantity

to its actual (true) value.

8) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.

9) One sigma @ 150 m range under RIEGL test conditions.

20 m 20 mm $20 \, \text{mm}$ up to 2000 kHz

up to 1 250 000 meas./sec. (@ 2000 kHz PRR & 75° scan angle)

provided for each echo signal

near infrared 0.25 mrad 11)

10) User selectable.
 11) Measured at 1/e² points, 0.25 mrad corresponds to an increase of 25 mm of beam diameter per 100 m distance.

Scanner Performance

Scanning Mechanism Scan Pattern Scan angle range Total Scan Rate Angular Step Width Δ θ Angle Measurement Resolution

12) The minimum scan rate depends on the selected laser PRR. 13) The angular step width depends on the selected laser PRR.

rotating polygon mirror parallel scan lines $\pm 37.5^{\circ} = 75^{\circ}$ 30 12) - 300 lines/sec. $0.002^{\circ} \leq \Delta \ \vartheta \leq 0.24^{\circ \ 13) \ 14)}$

 0.001°

14) The maximum angular step width is limited by the maximum scan rate.

Data Interfaces

Configuration Scan Data Output Synchronization

Camera Interface

LAN 10/100/1000 MBit/sec LAN 10/100/1000 MBit/sec

Serial RS232 interface, TTL input for 1 pps synchronization pulse, accepts different data formats for GNSS-time information

5x power, RS232, 1 pps, trigger, exposure

Data Storage

Permanently Installed Data Storage Removable Data Storage

Solid State Disc SSD, 1 TByte

Cardholder for CFAST®15) storage cards (up to 256 GByte)

15) CFast is a registered trademark of CompactFlash Association.

Technical Data RIEGL VQ®-580 II

General Technical Data

Power Supply Input Voltage Power Consumption Main Dimensions (L x W x H) Weight

without integrated IMU/GNSS with integrated IMU/GNSS

Humidity Protection Class Max. Flight Altitude

operating & not operating

Temperature Range

18 - 34 V DC

typ. 70 W, max. 220 W 1)

378 mm x 193 mm x 252 mm (without mounted carrying handles)

9.9 kg 10.3 kg

non condensing

IP54, dust-proof and splash-proof

18500 ft (5600 m) above MSL (Mean Sea Level)

 -5° C up to $+40^{\circ}$ C (operation) / -10° C up to $+50^{\circ}$ C (storage)

Integrated IMU & GNSS (optional) 2)

IMU Accuracy Roll, Pitch Heading IMU Sampling Rate Position Accuracy (typ.)

horizontal

vertical

 0.015° 0.035° 200 Hz

 $\leq 0.05 \, \text{m}$ $\leq 0.1 \text{ m}$

Max. scan rate, all heaters in operation.
 Accuracy specifications for post-processed data.



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