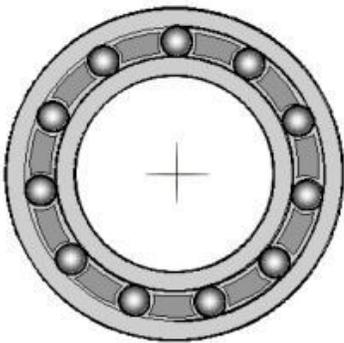


Rolling element bearing problems

- High frequency trend data is most important
- Spectral and timebase data is needed for evaluation of the failure stage
- Machine rpm is necessary
- Bearing manufacturer and part number is helpful (BE)
- Enveloping data is always adding value and on low speed machinery it is necessary



$$ORBP = \frac{N\Omega}{120} \left(1 - \frac{d}{D} \cos \alpha \right)$$

$$IRBP = \frac{N\Omega}{120} \left(1 + \frac{d}{D} \cos \alpha \right)$$

$$FTF = \frac{\Omega}{120} \left(1 - \frac{d}{D} \cos \alpha \right)$$

$$BSF = \frac{D\Omega}{120d} \left(1 - \left(\frac{d}{D} \cos \alpha \right)^2 \right)$$

N = number of elements

Ω = shaft rotation speed

d = rolling element diameter

D = pitch diameter

α = element contact angle

ORBP = Outer ring failure

IRBP = Inner ring failure

FTF = Cage failure

BSF = Roller failure

Failure Stages

Rolling Element Bearing Defects

Stage 1

- > Defects located below the surface.
- > Very High frequency (5KHz to ~30KHz).
- > *Greasing may save the bearing*

Stage 2

- > Defects appear to surface, still need a microscope to see
- > HF trending still the best method
- > *Enveloped Spectrum may show defects.*
- > High frequency acceleration spectrum has the data at the high end too

Stage 3

- > Defects become visible.
- > *Vibration on Bearing Related (Prime Spike) and Rotor Region become clearly visible.*
- > Replace bearing.

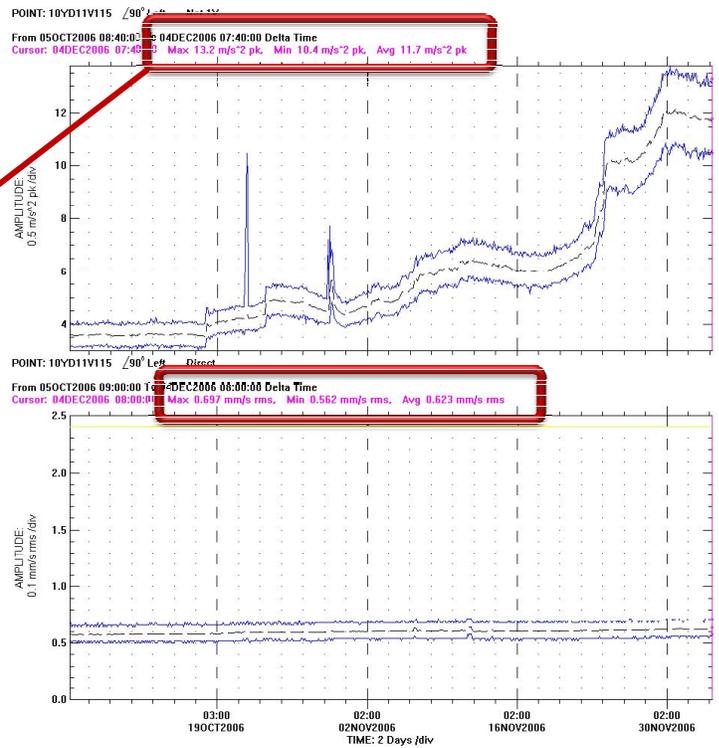
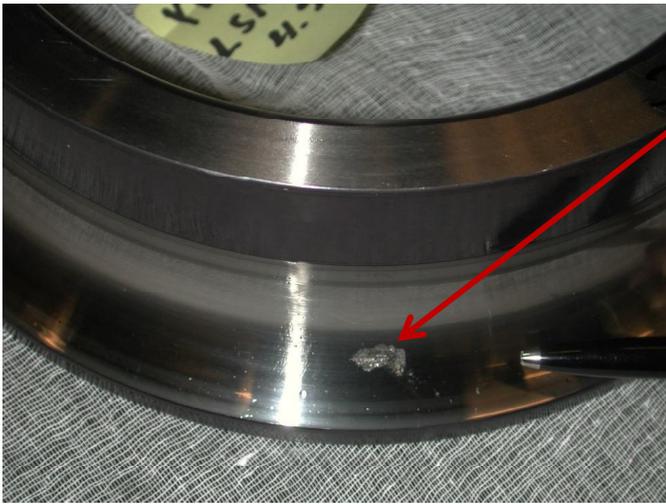
Stage 4

- > *Defects can lead to a catastrophic failure.*
- > Vibration increases in the Rotor Related Region (1/4X to 3X)
- > Stop machine and fix bearing(s) and other damaged parts

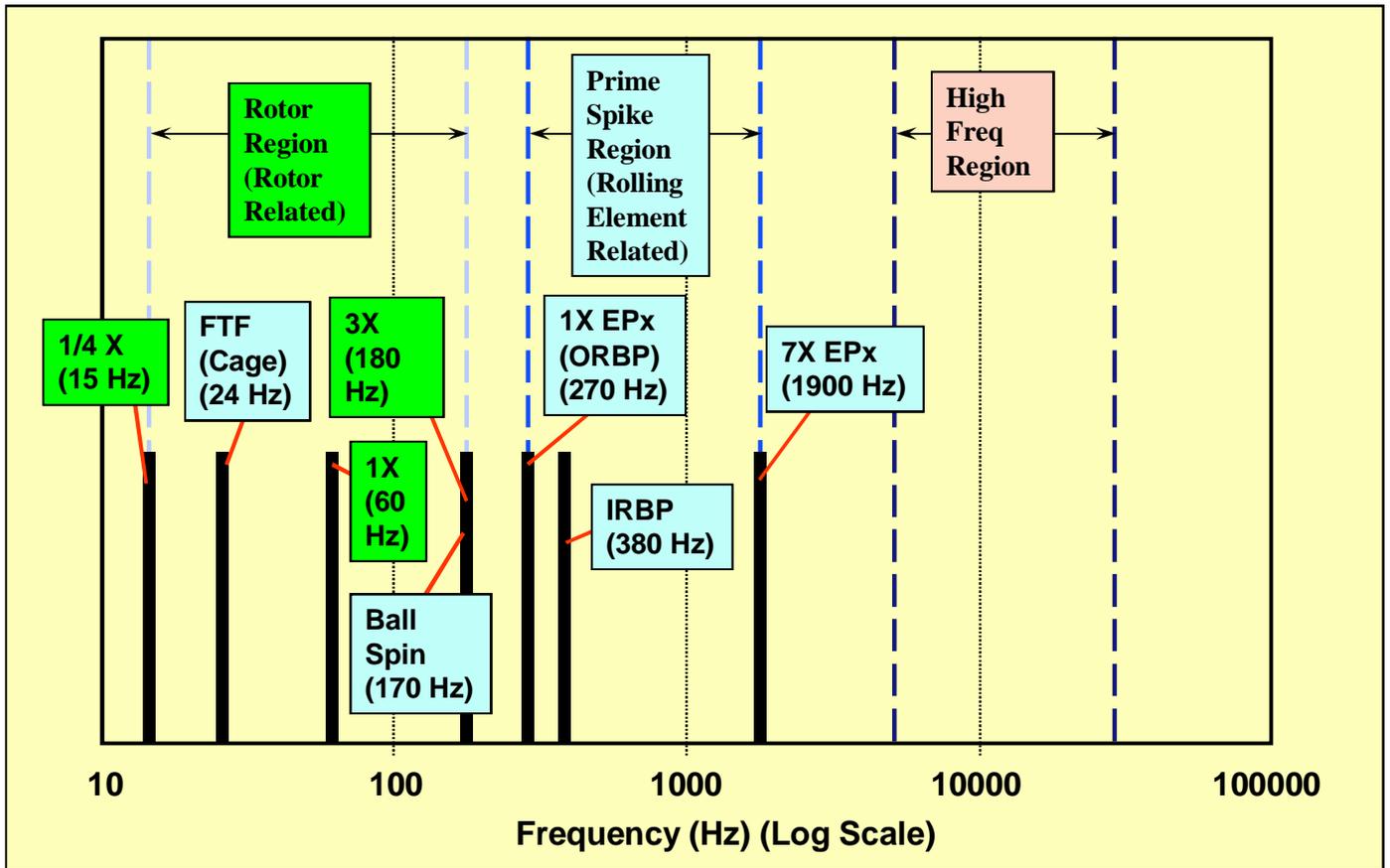
Monitoring REB

Case Nuclear reactor circulation pump 1/2:

Online



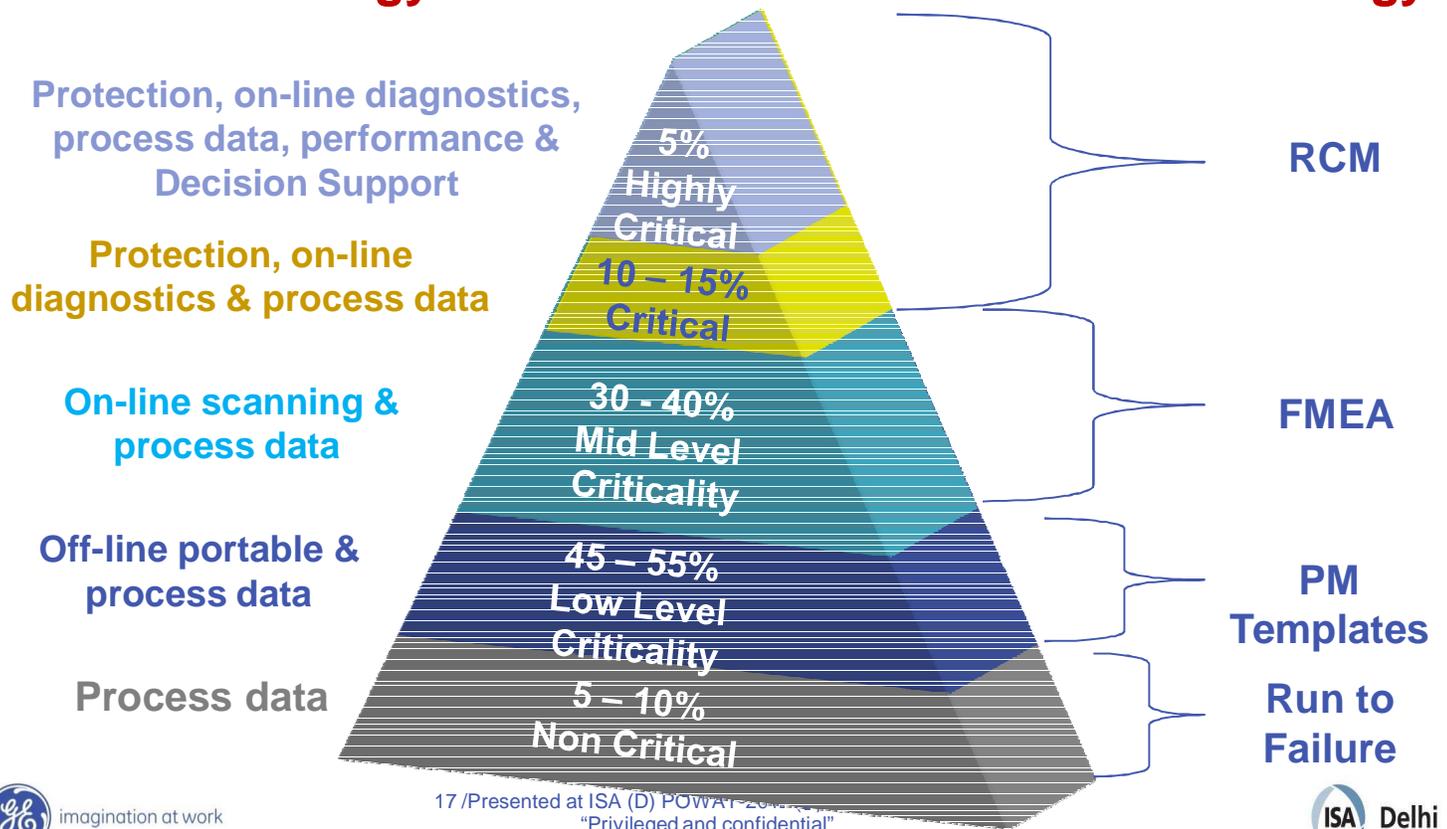
Frequencies of Interest (Example of one of the rolling element bearing frequencies)



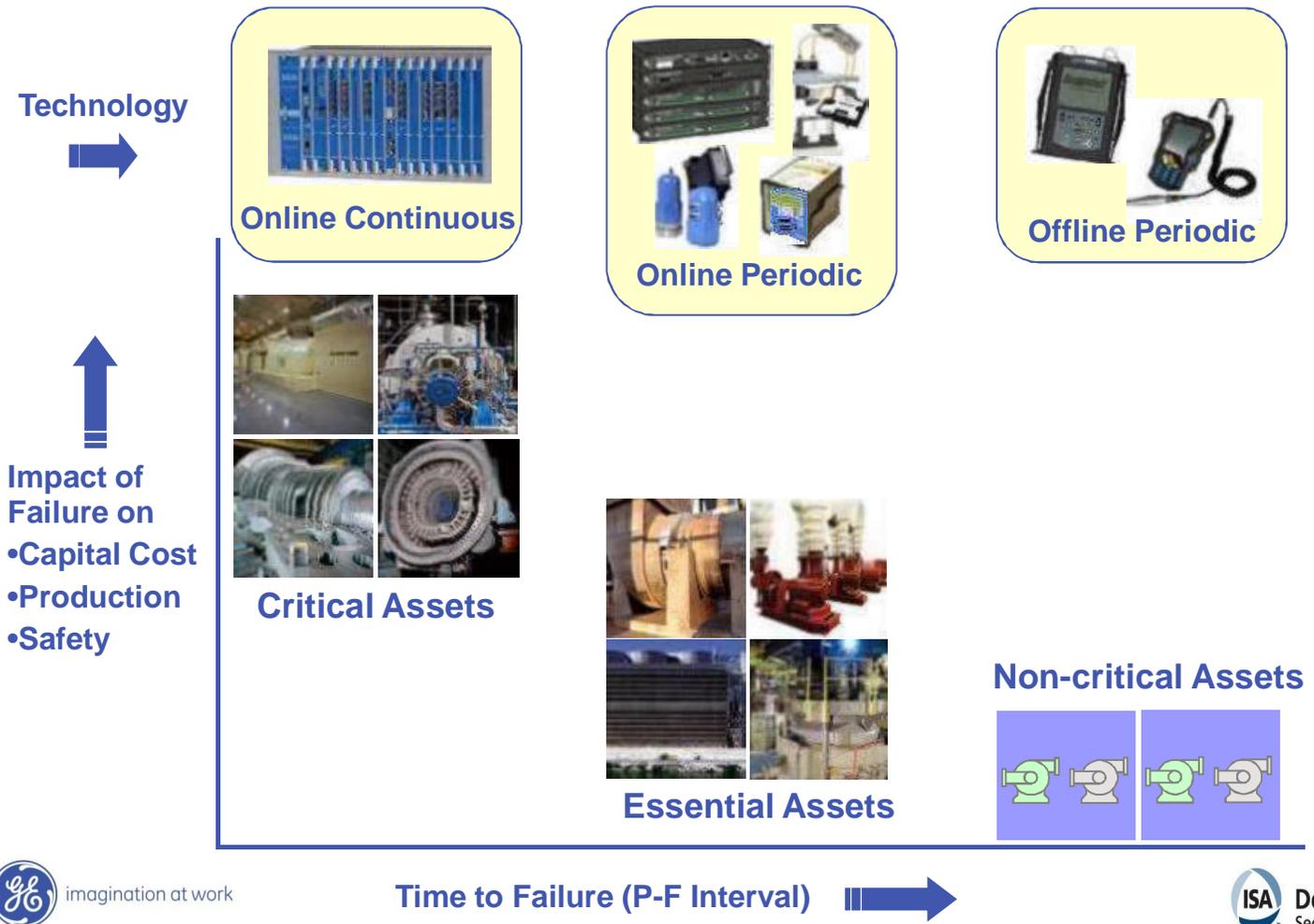
Plant equipment criticality

Technology

Maintenance Strategy



Technology...appropriate to asset criticality



Predicting safe operating time

Fault types:

Start up faults, caused by faults in

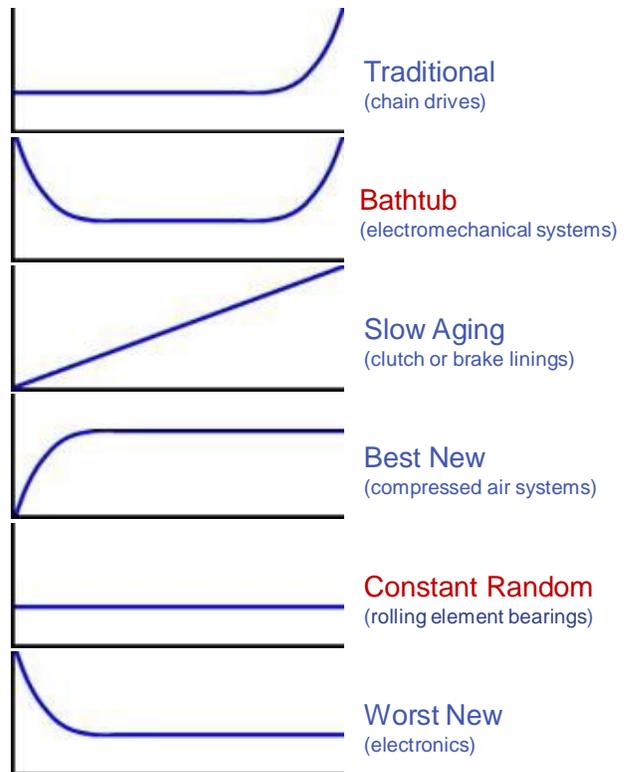
- Design
- Manufacturing
- Transportation
- Assembly
- Service
- Standby
- Startup

Random faults, caused by faults in

- Material
- External effects

Wear, caused by

- Normal wear
- Looseness
- Material degradation
- Overloading
- Environment



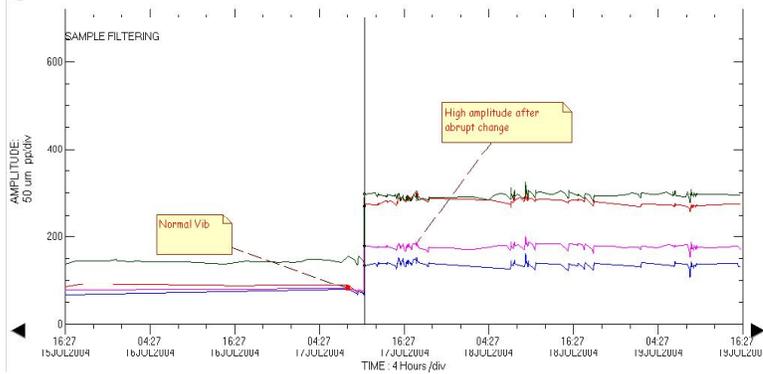
Monitor
Critically

Detect
Early

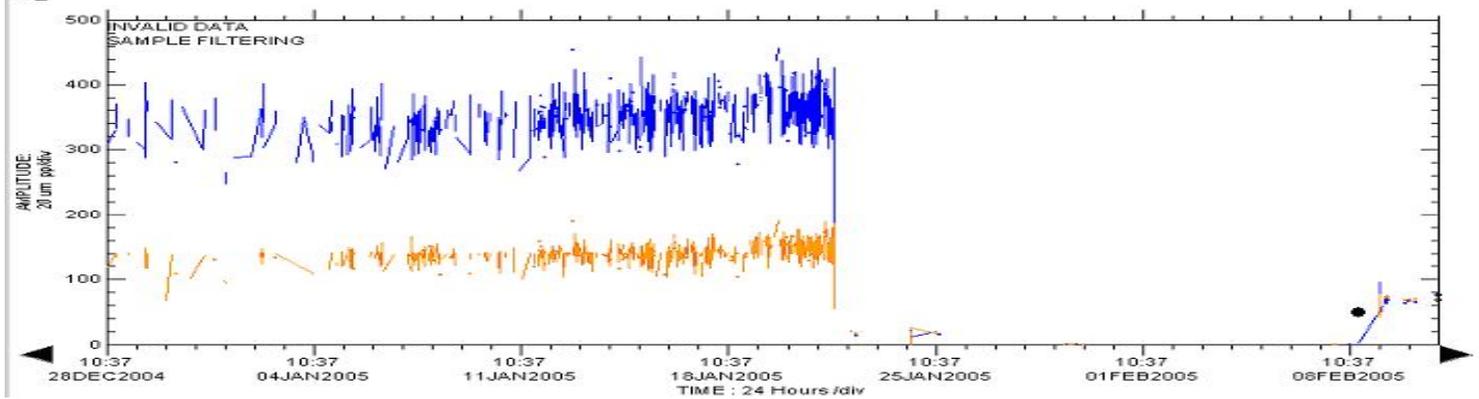
Diagnose
Quick & Precise

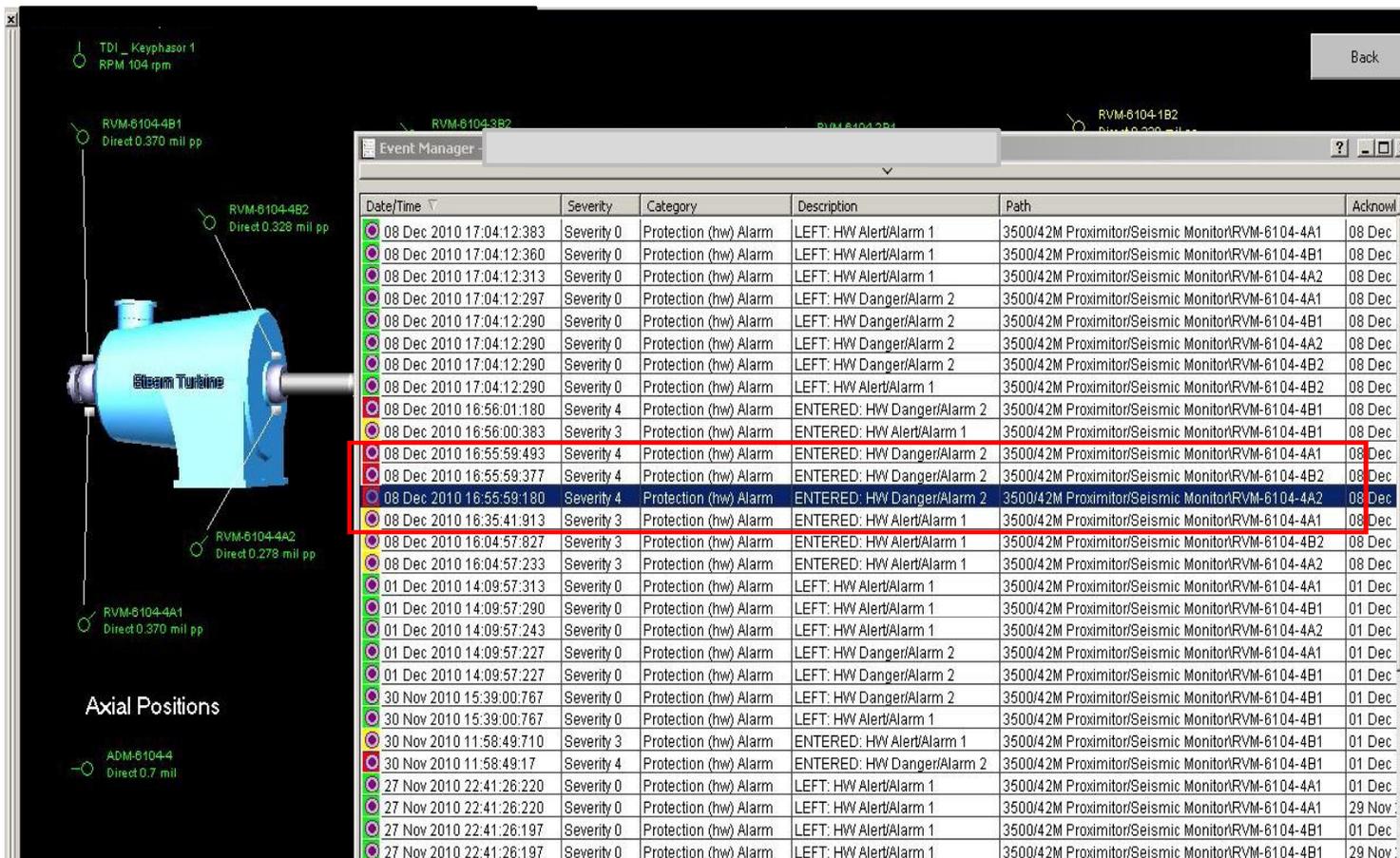
Mitigate
Risk of Operation

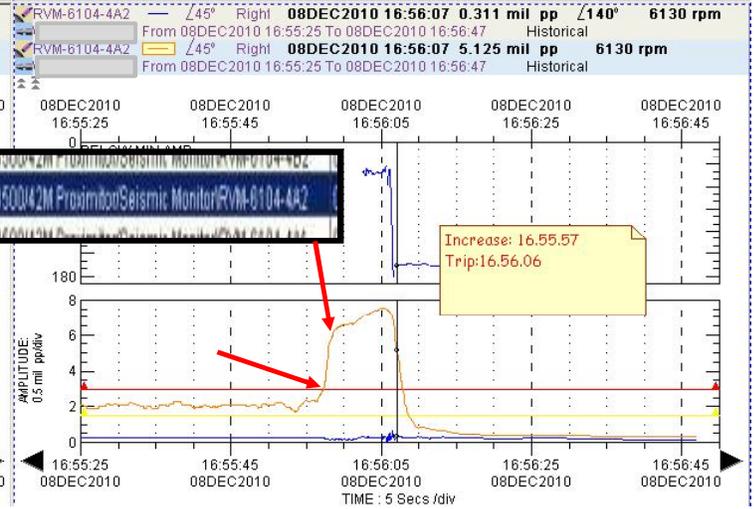
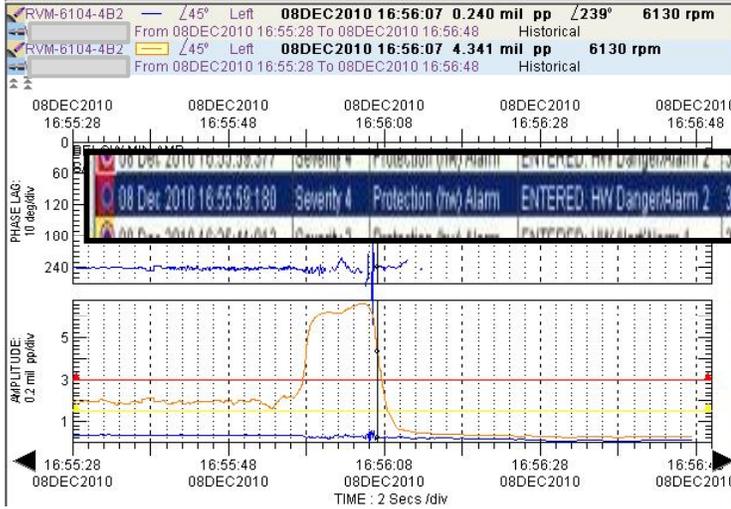
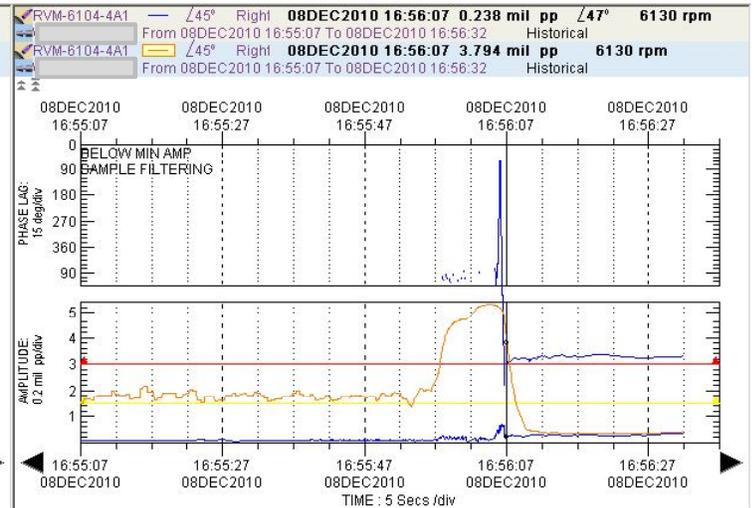
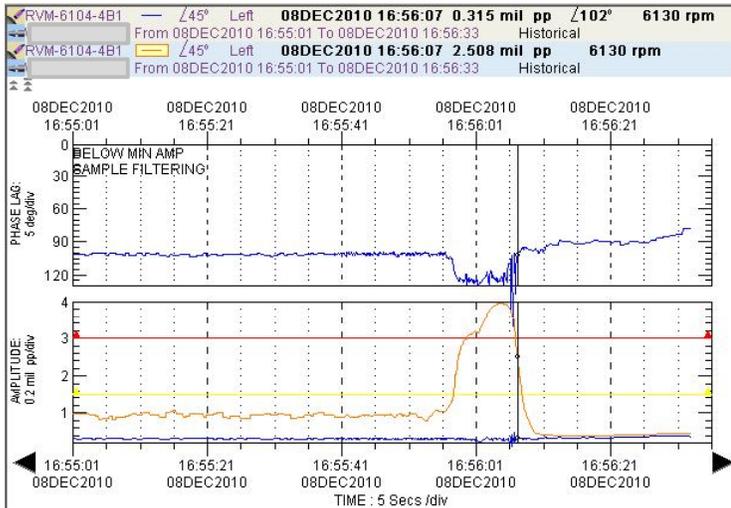
VIB-4Y	—	∠20° Left	Direct	17JUL2004 10:53:32	271 um pp	3020 rpm
Unit#1	From 15JUL2004 16:27:12 To 19JUL2004 16:27:12		Historical			
VIB-4X	—	∠70° Right	Direct	17JUL2004 10:53:29	135 um pp	3021 rpm
Unit#1	From 15JUL2004 16:27:12 To 19JUL2004 16:27:12		Historical			
VIB-5Y	—	∠20° Left	Direct	17JUL2004 10:53:27	297 um pp	3021 rpm
Unit#1	From 15JUL2004 16:27:12 To 19JUL2004 16:27:12		Historical			
VIB-5X	—	∠70° Right	Direct	17JUL2004 10:53:32	178 um pp	3020 rpm
Unit#1	From 15JUL2004 16:27:12 To 19JUL2004 16:27:12		Historical			



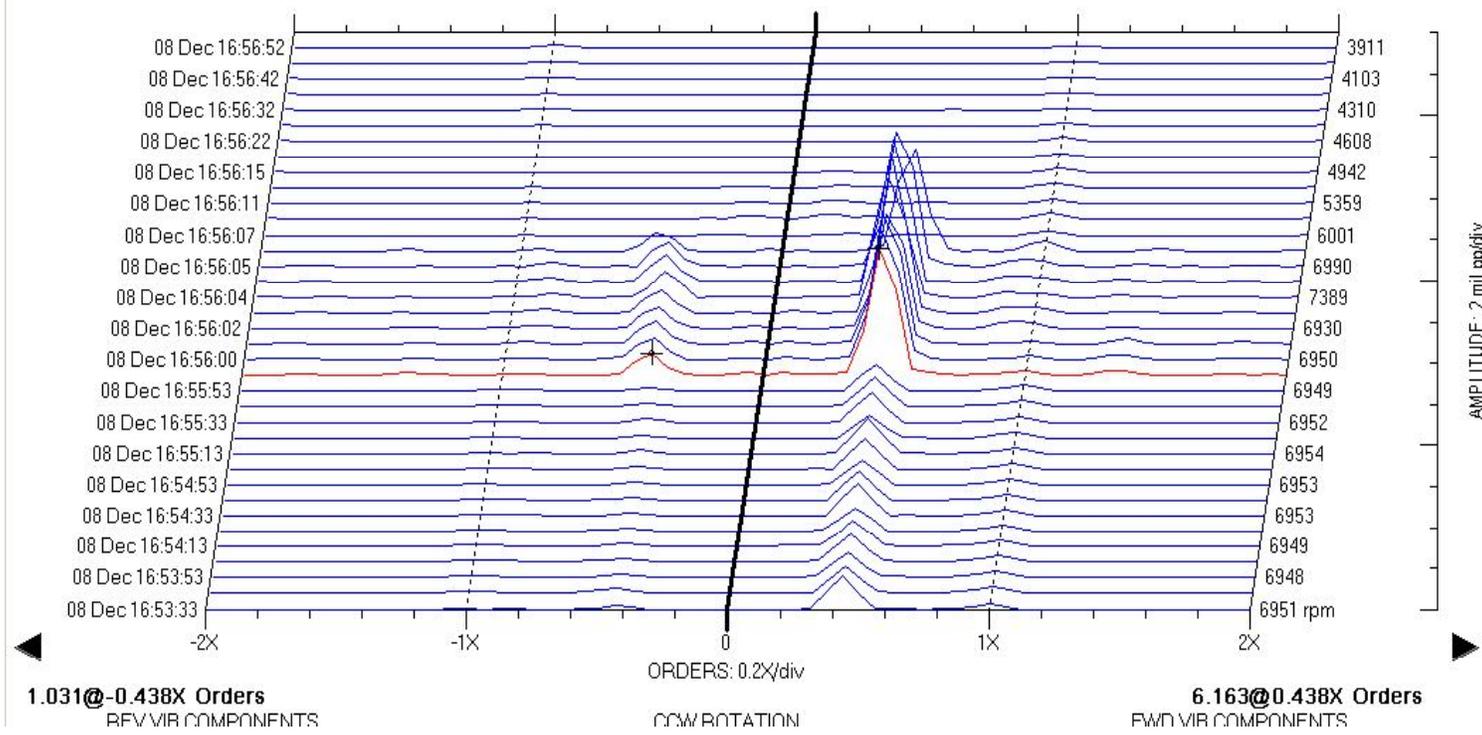
VIB-4Y	—	∠20° Left	Direct	11FEB2005 09:53:31	76 um pp	NA
Unit#1	From 28DEC2004 11:08:14 To 11FEB2005 11:08:14		Historical			
VIB-4X	—	∠70° Right	Direct	11FEB2005 09:53:31	68 um pp	NA
Unit#1	From 28DEC2004 11:08:14 To 11FEB2005 11:08:14		Historical			





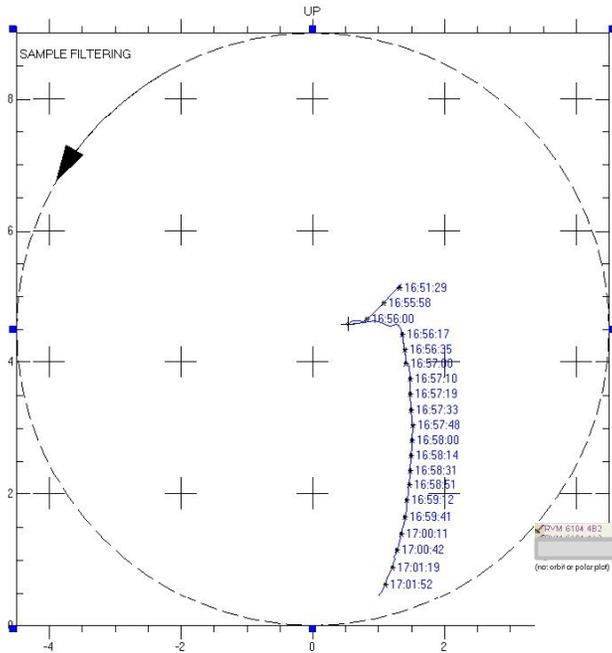


RVM-6104-4B2 /45° Left Full Spectrum
 RVM-6104-4A2 /45° Right
 From 08Dec2010 16:53:33 To 08Dec2010 16:56:52 HW Danger/Alarm 08Dec2010 16:56:00
 Hanning SPECTRAL LINES: 1024 RESOLUTION: 0.063X
 FS: 0-64 X SMPR: 128/16



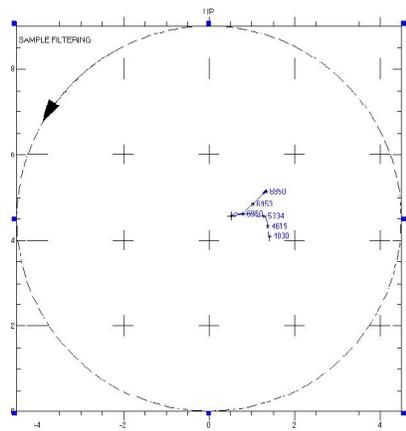
RVM-6104-4B2 45° Left REF: 9.692 V 08DEC2010 17:03:42 97 rpm 0.573 (0.534, 4.586) 08DEC2010 16:56:05
 RVM-6104-4A2 45° Right REF: 9.617 V 08DEC2010 17:03:42 97 rpm 0.724
 From 08DEC2010 16:51:29 To 08DEC2010 17:02:29 HW Danger/Alarm

not orbit or polar plot)

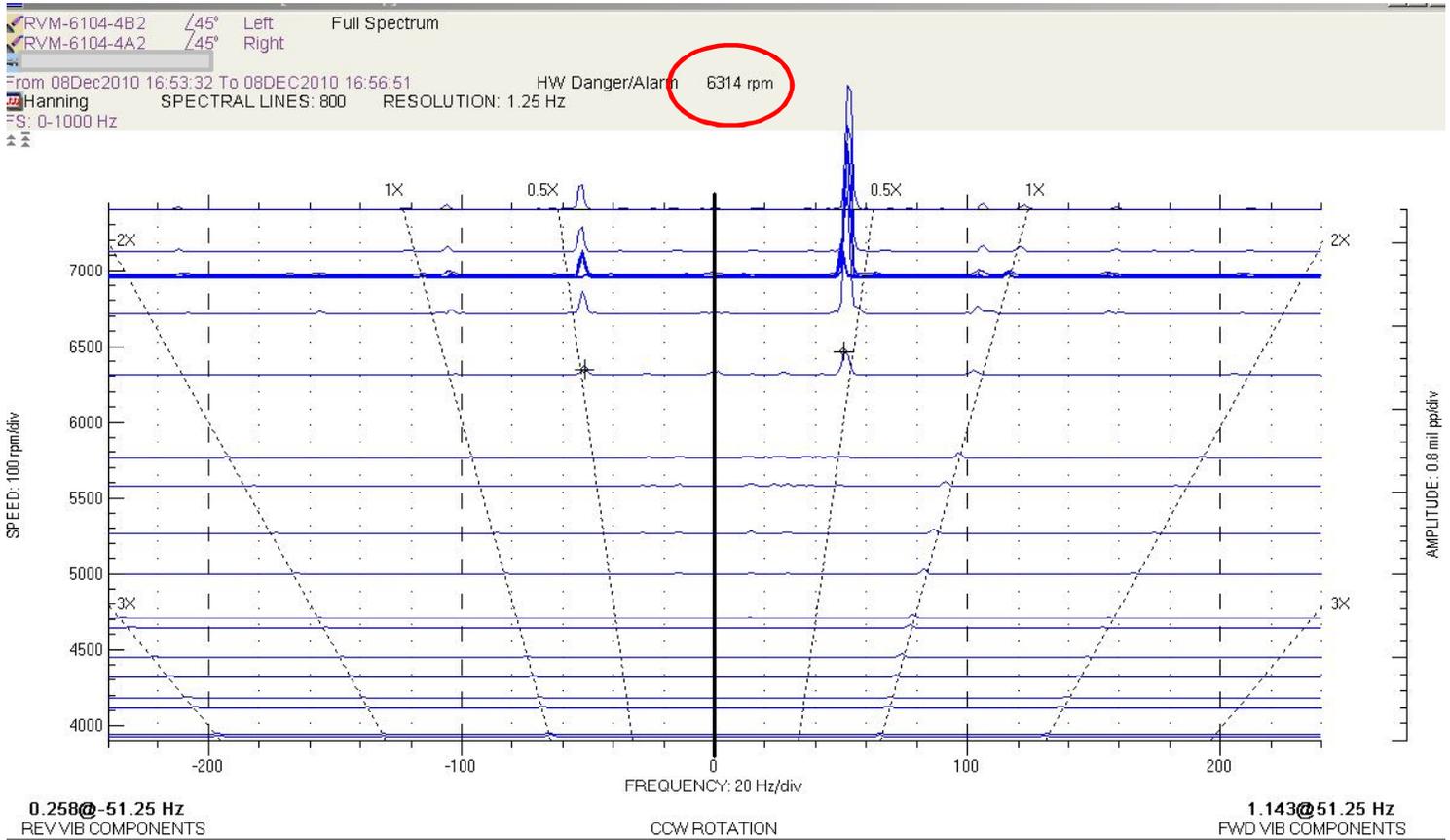


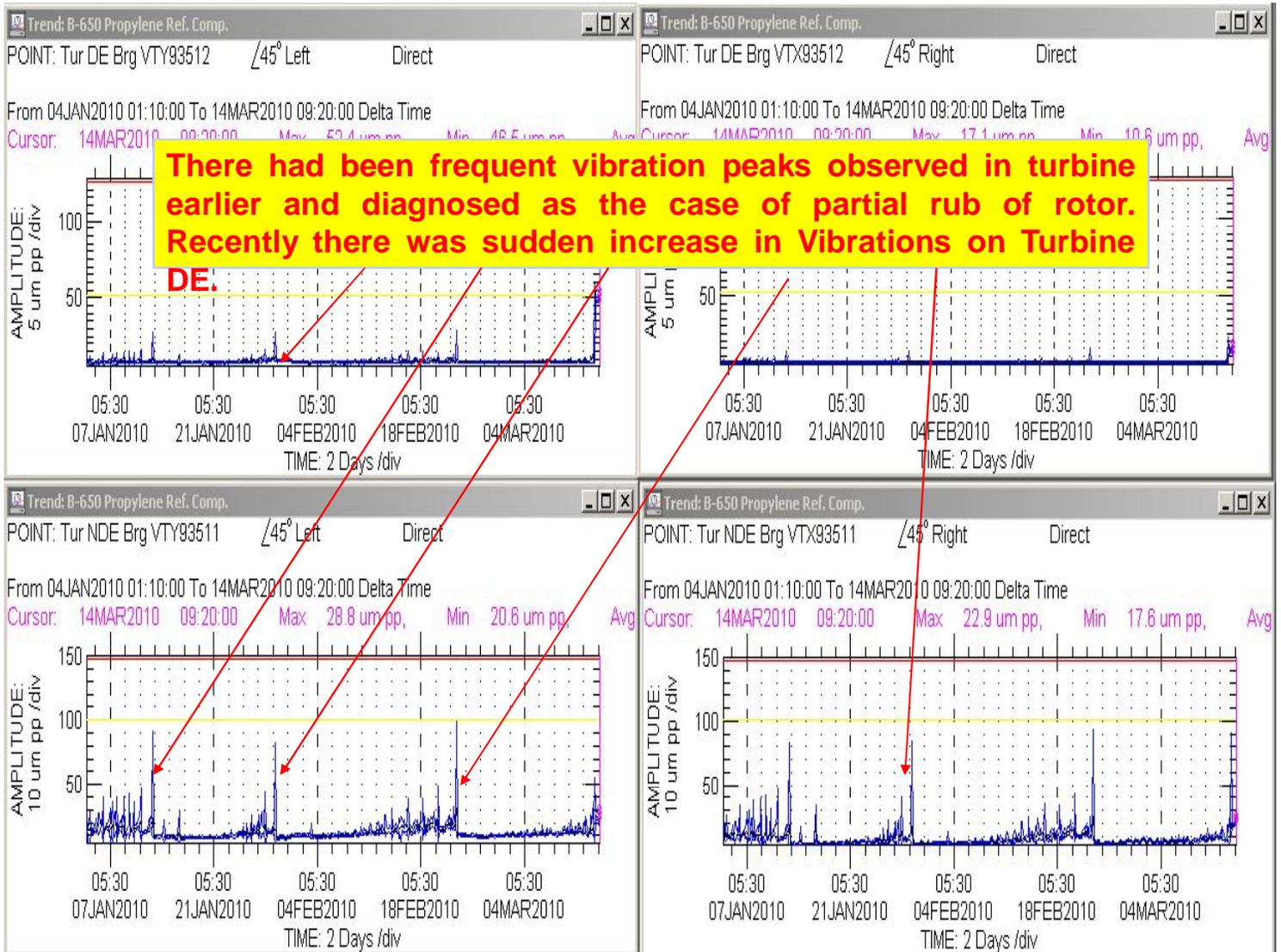
RVM-6104-4B2 45° Left REF: 9.692 V 08DEC2010 17:03:42 97 rpm 0.573 (0.516, 4.568) 0767
 RVM-6104-4A2 45° Right REF: 9.617 V 08DEC2010 17:03:42 97 rpm 0.719
 From 08DEC2010 16:46:59 To 08DEC2010 16:56:59 HW Danger/Alarm

AMPLITUDE: 0.5 mil/div



AMPLITUDE: 0.5 mil/div



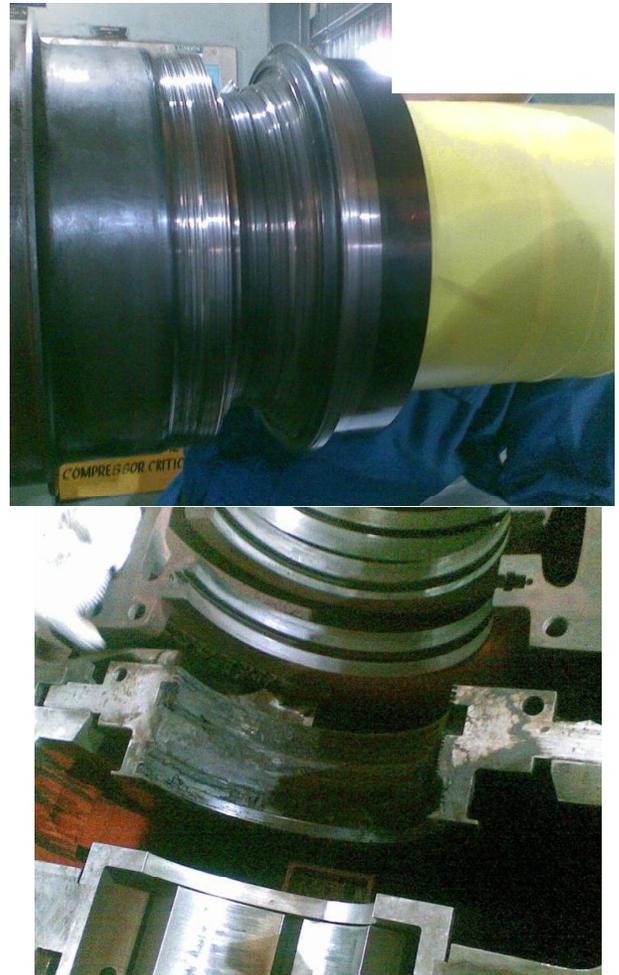


NDE side Shaft Damage

Since Aug 2007, Turbine has been showing periodic spikes at NDE side. Machine has tripped twice on high vibration in this period.

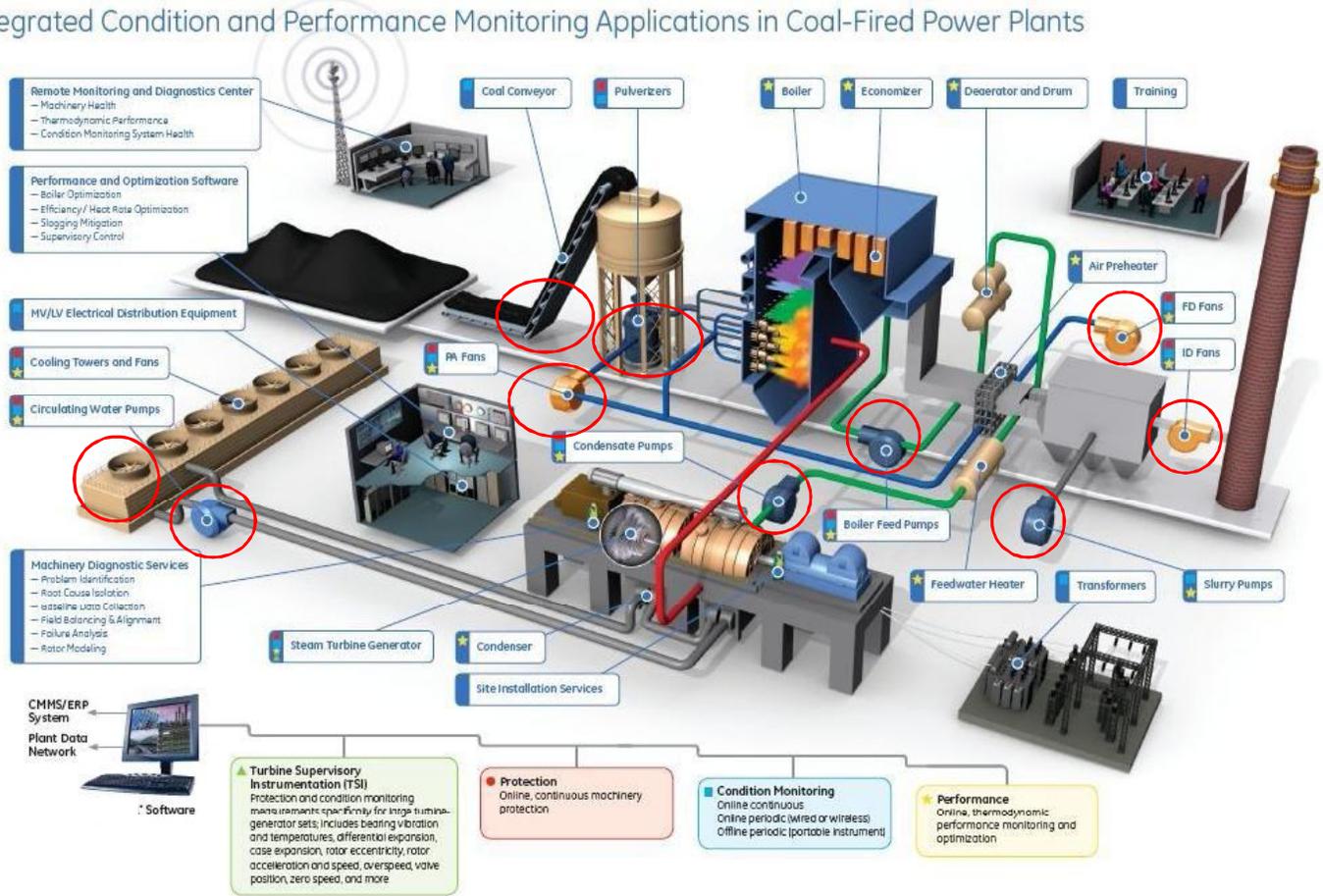
This is found to be due to heavy coke deposition and rubbing at NDE side oil labyrinth

Rubbing with coke has caused deep scoring and grooving on corresponding shaft area for 100 mm width and 35 mm deep



Essential Machines in Thermal Power Plant

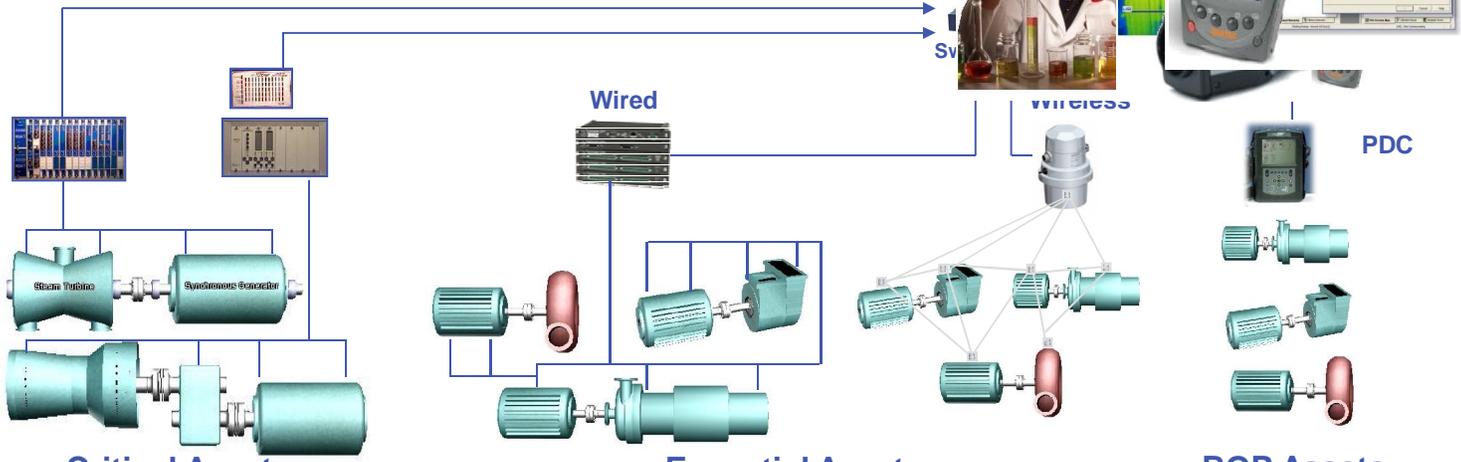
Integrated Condition and Performance Monitoring Applications in Coal-Fired Power Plants



Asset management platform

Online - Continuous monitoring & protection

Online – Periodic (scanning) monitoring



Critical Assets

- Gas Turbines
- Steam Turbines
- Generators
- Pumps
- Etc.

Essential Assets

- Fans
- Pumps
- Blowers
- Motor
- Etc.

BOP Assets

- Vibration
- Portable Devices
- Lube Oil
- Thermography
- MCA, etc...



Thank you!

Back Up

Determining Business Impact

Maintenance Strategies

Safety

- > Could a machine failure cause people to be injured?

Environment

- > Could a failure release hazardous materials or result in a fine by exceeding permitted levels?

Process

- > Could a failure reduce production capability?

Maintenance

- > Could a failure require repair work? Are parts expensive?

Quality

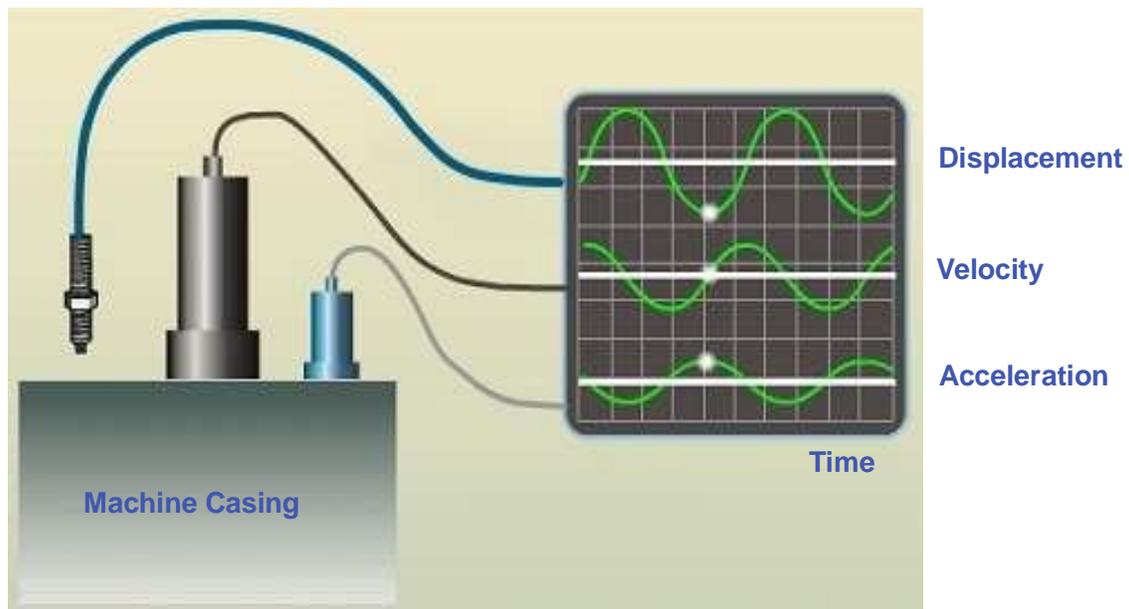
- > Could a failure reduce the quality of the product being produced by the business?

**What is the
FINANCIAL
impact of a
machine failure on
the business?**



Machine Casing Example

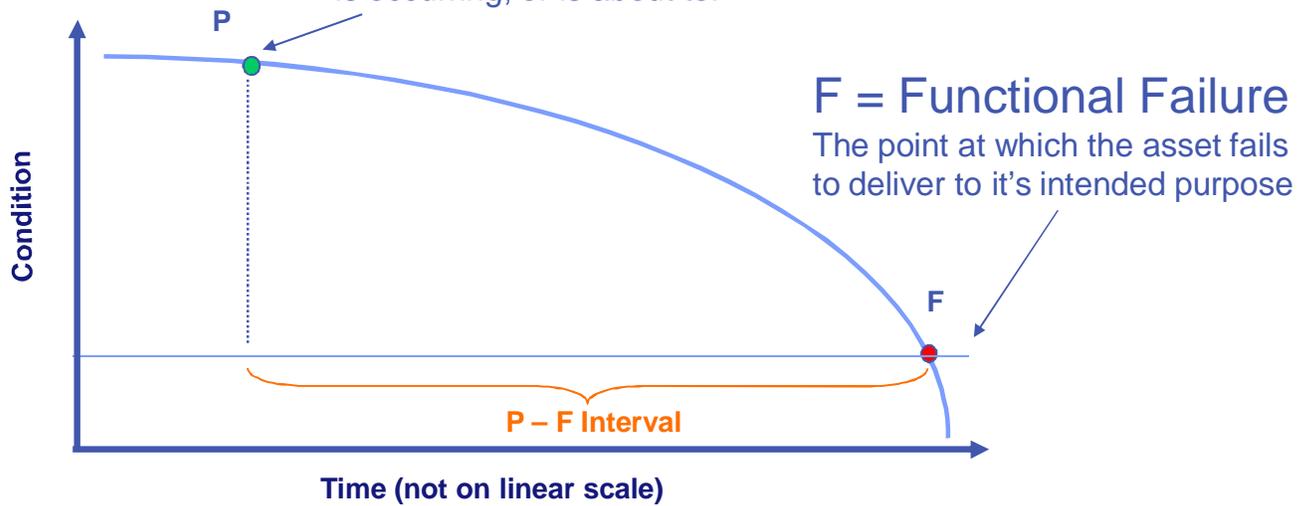
Physical Parameters



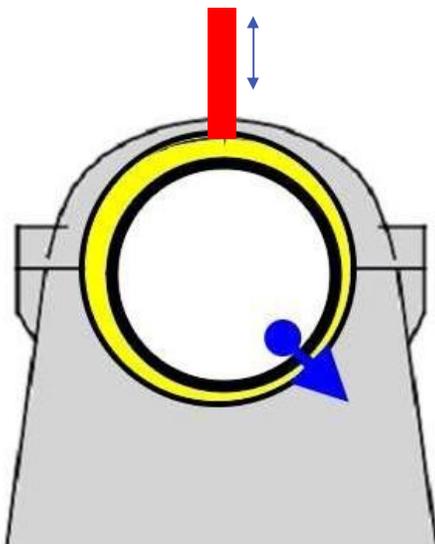
P-F interval

P = Potential Failure

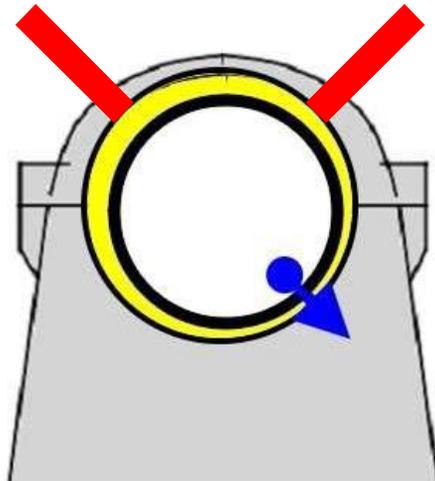
An identifiable condition that indicates a functional failure is occurring, or is about to.



On essential assets P-F interval runs into numbers of days

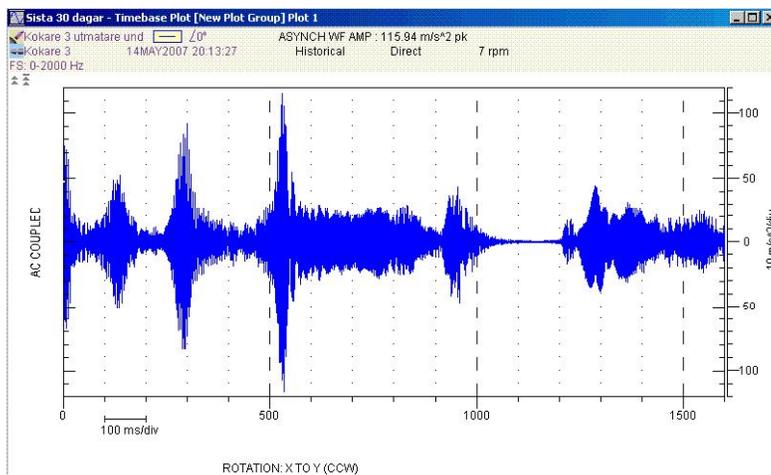


A single vibration sensor can only measure motion in one direction.



A pair of vibration sensors can measure motion in two directions at once.

Online Scanning Monitoring



Lubrication problem on a slow speed machine

- Very high acceleration peak >100 m/s²
- Clear indication of loss of lubrication

Online, scanning or portable?

Online:

- Protection is needed = failure can happen in seconds
- Operating stages vary rapidly (in seconds)
- Safety and large production losses



Scanning:

- Failure may happen too fast for PDC
- Accessibility
- Safety
- Operation stages do vary, but are not constantly changing
- Vibration data quality, especially at high frequency end
- Early problem detection
- Reduction of manpower



PDC:

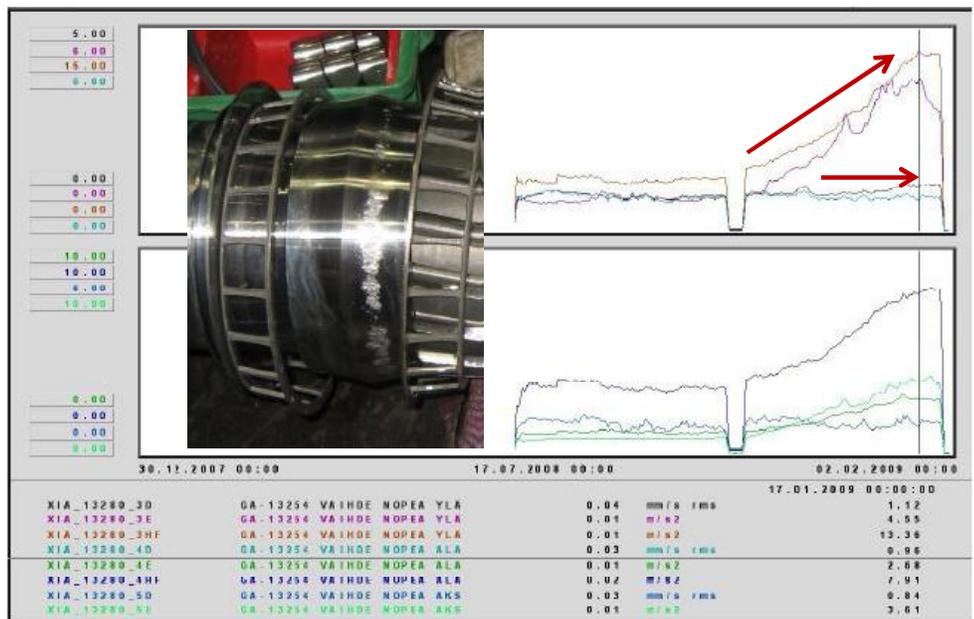
- When failure development takes weeks
- Should always be in place to complement online/scanning systems
- In the starting phase of a CM program usually the first system to be used
- Bedegatory constraints



Online Scanning Monitoring

Seawater pump gearbox REB failure case:

Scanning



Overhaul in Sept'08... increase in high frequency trend upward, no increase in Velocity trend

Jan'09... bearing opened and inner ring failure was observed

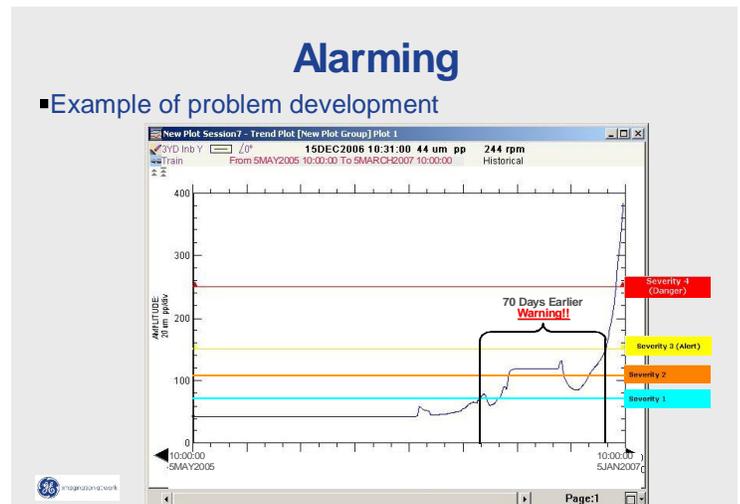
Predicting safe operating time

Generally *fault prediction is based on assumption that the value of the symptom is higher when the fault is more severe.*

*When a failure development is recognized it may require **additional measurements or added monitoring with same or additional technique***

Overhaul date is defined by

- > predicted danger
- > how rapid the fault development is
- > secondary failures
- > how true the danger limit is
- > failure history
- > MTBF
- > allowed failure
- > known overhaul dates
- > loss of production
- > uptime requirements
- > total costs, etc

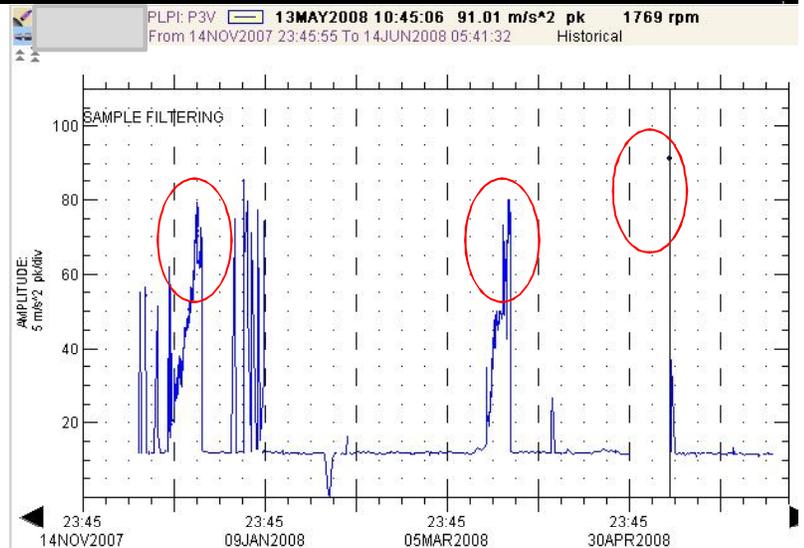
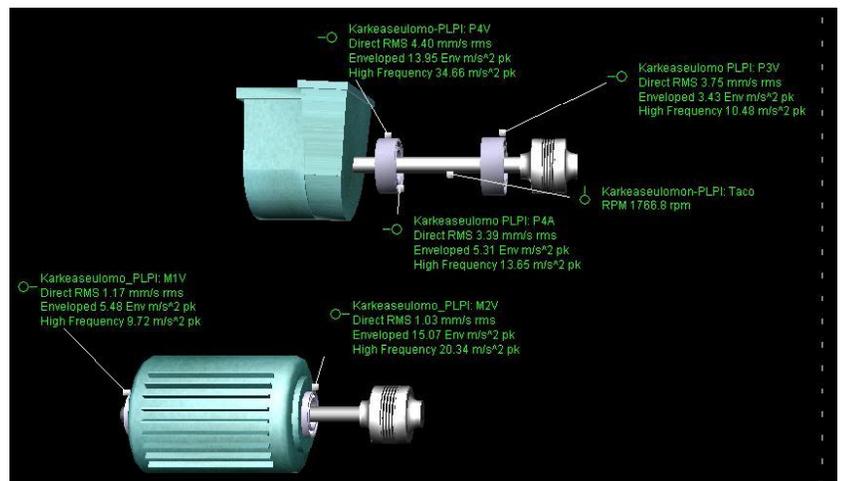


Bearing failures

Improper lubrication

Belt driven fan – DE Brg
direct input cards
Accelerometer

Problems on Fan DE
In the past several bearing failures
now caught in time with HF
measurement 3 times in
6 months



Selection of transducer

Selection of Monitoring System

Preparedness for Surprises

Terminology

The four main maintenance strategies are:

- Reactive Maintenance (RM)
- Preventive Maintenance (PM)
- Predictive Maintenance (PdM)
- Proactive Centered Maintenance (PCM)



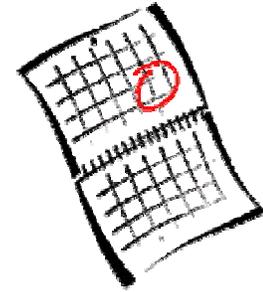
Terminology

Reactive maintenance (RM):

- Maintenance performed after a failure or after an obvious, unforeseen threat of immediate failure.
- In reactive maintenance, machines are operated in a run-to-failure (RTF) mode
- Daily maintenance activities are driven by unforeseen problems from assets breaking down without detection of the impending failure.



Terminology



Preventive Maintenance (PM):

- Maintenance tasks conducted at regular, scheduled intervals based on average statistical/anticipated lifetime to avoid failure
- Includes inspection, service and/or replacement
- Intervals may be calendar or operating time.

Terminology



Predictive Maintenance (PdM):

- **Maintenance based on the actual asset condition (objective evidence of need)**
- **Assessment data obtained from in-situ, non-invasive tests and operating & condition measurements**
- **Also referred to as Condition Based Maintenance (CBM).**

Terminology

Proactive-Centered Maintenance (PCM):

- **A program of continuous maintenance optimization**
- **Based on feedback from Root Cause Failure Analysis (RCFA) repairs, quantitative PM's, PdM routines, CM systems and operations.**



Terminology – other acronyms...

- **MTBE:** Mean Time Between Events
- **MTBF:** Mean Time Between Failure
- **MTBR:** Mean Time Between Repairs
- **MTTR:** Mean Time To Repair
- **MRO:** Maintenance, Repair, Overhaul
- **OEM:** Original Equipment Manufacturer
- **O&M:** Operating and Maintenance
- **ERP:** Enterprise Resource Planning

Terminology

Condition Monitoring (CM):

- The process of recording measurements that define condition without disrupting operation
- Examples are vibration, fluid & electrical characteristics and thermal gradients
- Measurements are compared to their limits.

Terminology

Reliability Centered Maintenance (RCM):

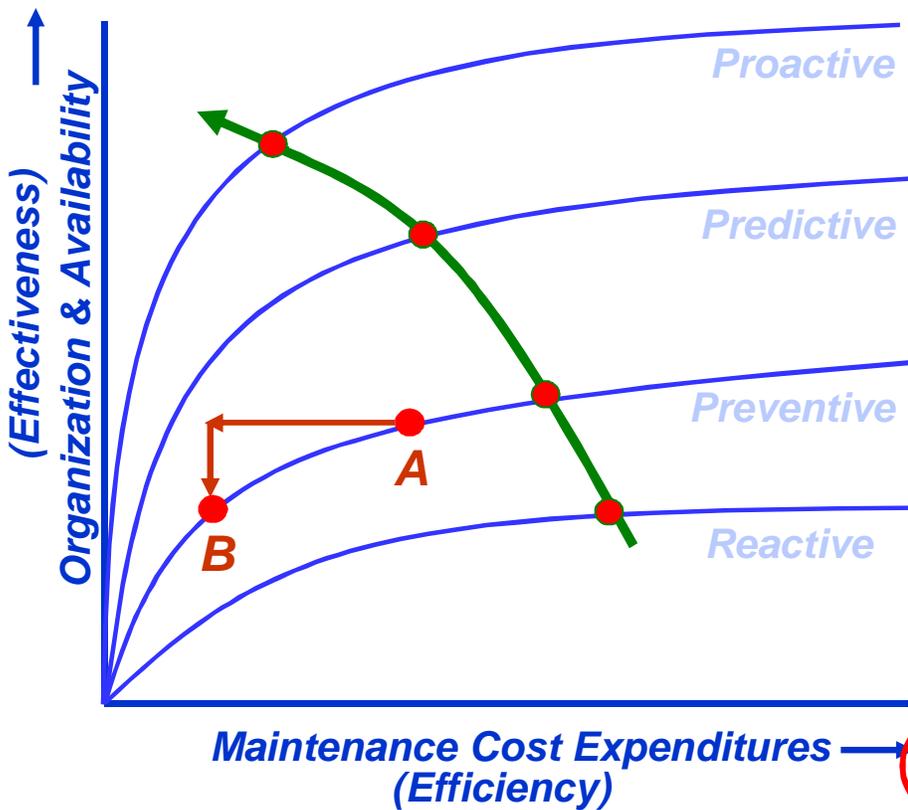
- A systematic, disciplined process to ensure safety and mission compliance that defines system boundaries and identifies system functions, functional failures, and likely failure modes for equipment and structures in a specific operating context.
- RCM develops a logical identification of the causes and effects (consequences) of system and functional failures to arrive at an efficient and effective asset management strategy to reduce the probability of failure.

Terminology

Functional Failure:

- The System is no longer capable of performing the intended function.
- For example, a pump that is designed to produce 100 gpm at 200 psi is considered to have functionally failed if it can only produce 90 gpm at 200 psi.

Maintenance strategies



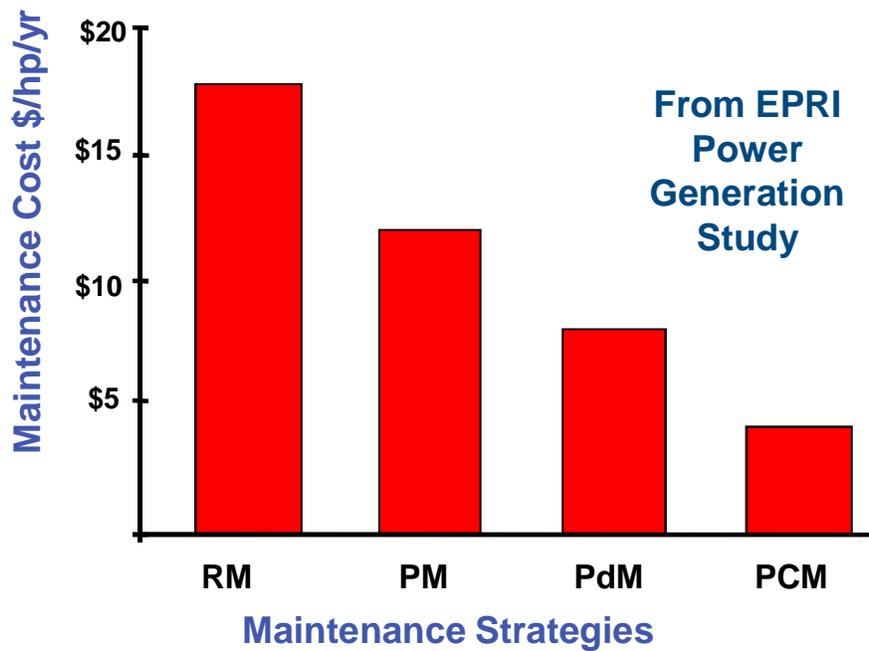
Type of maintenance	Top Quartile	Lower Quartile
Proactive	>20%	0% >65%
Predictive	>45%	~12%
Preventive	>25% ~86%	~31%
Reactive	<10%	~55%

100%
100%

Sources:

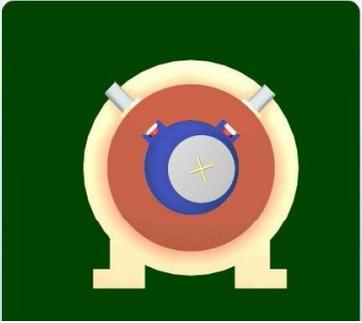
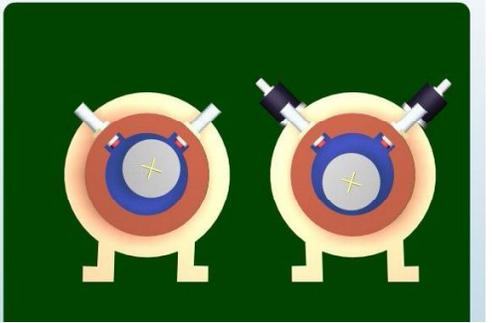
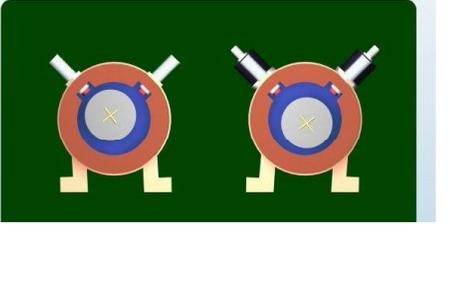
- Society of Maintenance & Reliability Professionals Survey
- The Business Case for Reliability
Robert DiStefano, John Schultz

Comparative maintenance spend



Note: This chart represents established programs

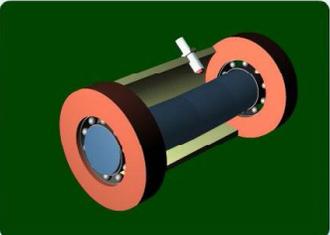
Case 1: Transducer selection for fluid film bearing considering Case to mass ratio

<p>Stiff</p> <p>The heavy case, light rotor and stiff support means that the case of the machine should experience a minimal amount of motion. XY shaft relative displacement transducers are the appropriate choice. If the bearing stiffness is very large, there may be a vibration nodal point at or near the bearing, and the displacement probes should be located at least a shaft diameter away from the bearing.</p> 	<p>Soft</p> <p>The heavy case and light rotor imply that a minimal amount of case motion will occur, but the soft support implies that the case may experience significant motion. If investigation reveals that case motion is always less than 30% of the shaft relative motion, XY shaft relative displacement transducers may be adequate. The safest choice is to use XY dual probe transducers and measure absolute displacement.</p> 
<p>Stiff</p> <p>The light case and heavy rotor imply that significant case motion will occur, but the stiff support implies that the case motion may be minimal. If investigation reveals that case motion is always less than 30% of the shaft relative motion, XY shaft relative displacement transducers may be adequate. The safest choice is to use XY dual probe transducers and measure absolute displacement.</p> 	<p>Soft</p> <p>The light case, heavy rotor, and soft support means significant case motion will probably occur. Use XY dual probe transducers and measure absolute displacement.</p> 

Case 2: Transducer selection for antifriction bearing considering rotor type

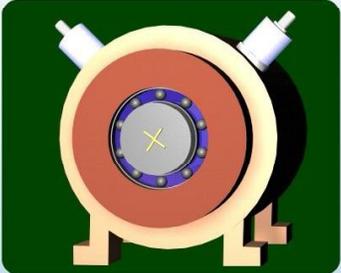
Stiff Close x

A flexible rotor and stiff support implies that the vibration will have a nodal point at the stiff rolling element bearing location. If this is the case, XY shaft relative displacement transducers mounted at least one shaft diameter away from the bearing may be the best choice. Casing velocity or acceleration transducers generally perform well with rolling element bearings, and REBAM transducers generally perform well with stiff supports, but a vibration nodal point at the bearing may limit the usefulness of these measurements.



Soft Close x

Even though the rolling element bearing itself is very stiff, if the remainder of the support structure is soft, the result will be a soft support. The soft support implies there will be casing motion, and XY case absolute velocity or acceleration is probably the best choice.



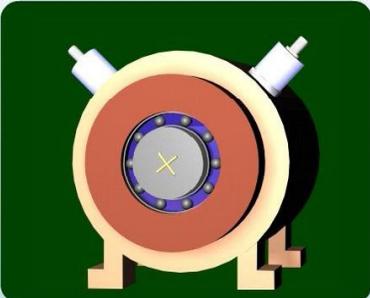
Stiff Close x

Casing velocity or acceleration transducers generally perform well with rolling element bearings, and REBAM transducers generally perform well with stiff supports. All should work for this configuration, which is common for rolling element bearing machines.

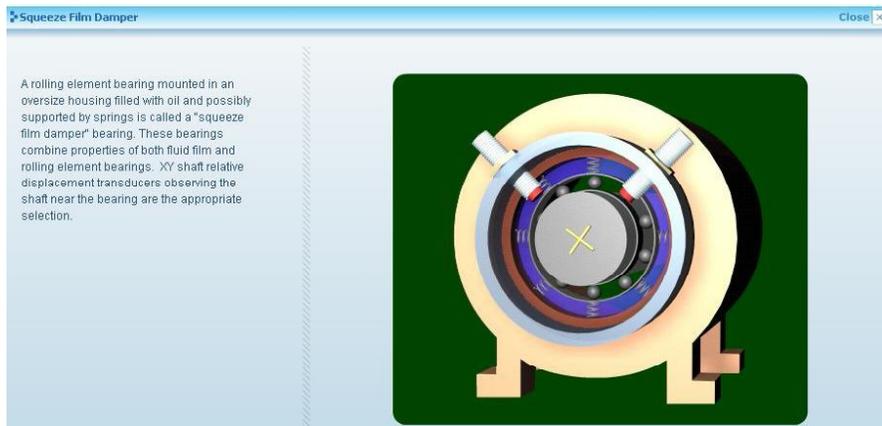


Soft Close x

Even though the rolling element bearing itself is very stiff, if the remainder of the support structure is soft, the result will be a soft support. The soft support implies there will be casing motion, and XY case absolute velocity or acceleration is probably the best choice.



Case 3: Transducer selection for squeeze film damper bearings





Case Study - Remote Operations and Monitoring of Power Station and Managing security with remote access.

origin

Presentation: ISA POWAT
2012

Location: The Grand, New
Delhi

Date : 13-14th Jan. 2012



Together we can
make a difference.™

Overview

Together we can
make a difference.™



Origin – Generation portfolio

Remote operational capability at Origin Power Stations

Establish remote operation for Peaking Power Station

Security measures considered and implemented

Centralised Remote Operations – Tangible Benefits and security threats.

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origin

Origin – Generation Portfolio



Origin Energy - Company Overview

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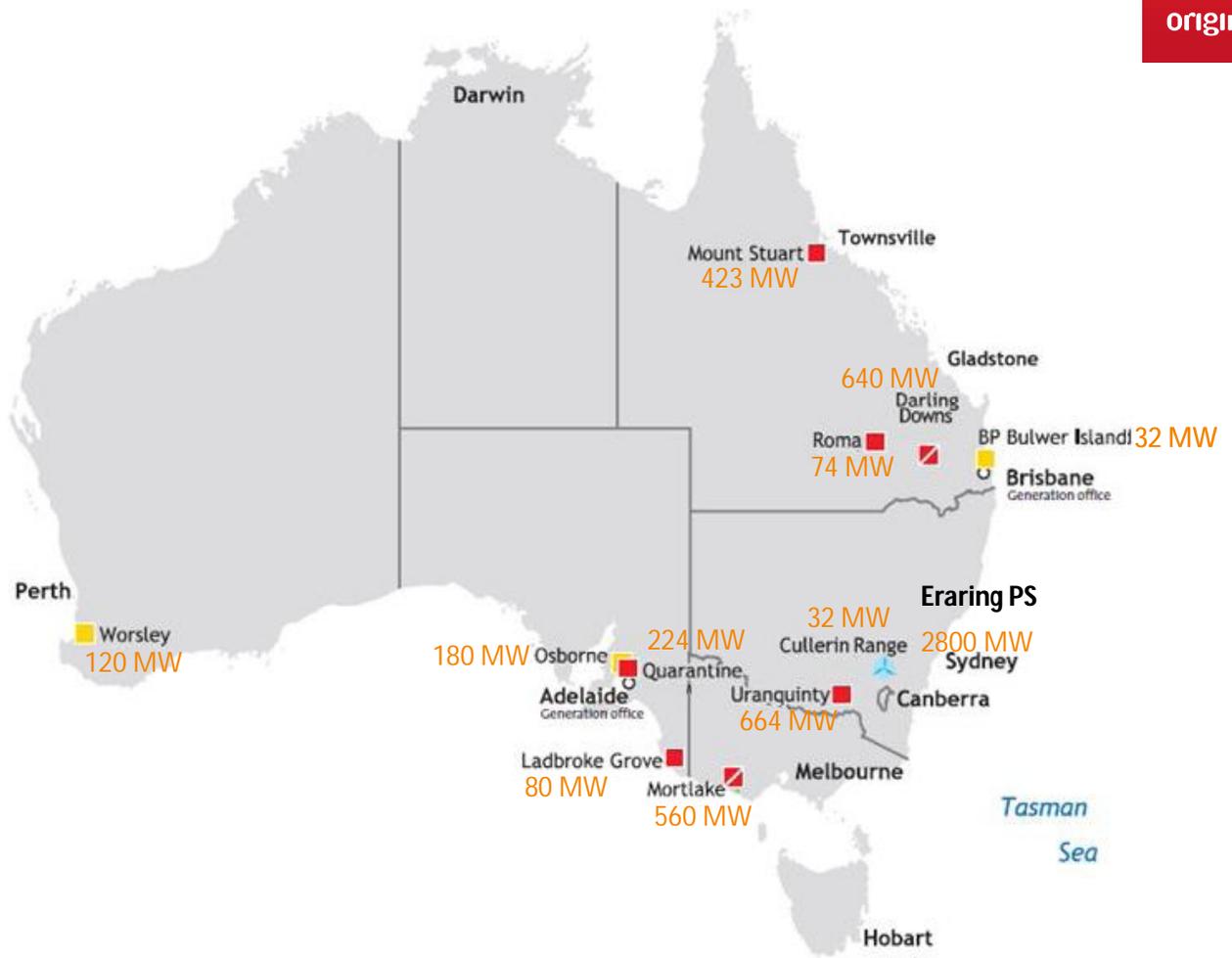
- 4500 Employees
- Major Business Units
 - Power Generation
 - Gas drilling, processing and pipeline distribution
 - Energy Trading
 - Energy Retailing
 - APLNG

One of the Australia's largest, most diversified generators with capacity and contractual arrangements in excess of 5,800 MW.

AND Australia's largest Energy Retailer with 4.6 million customer accounts.

Generation Portfolio

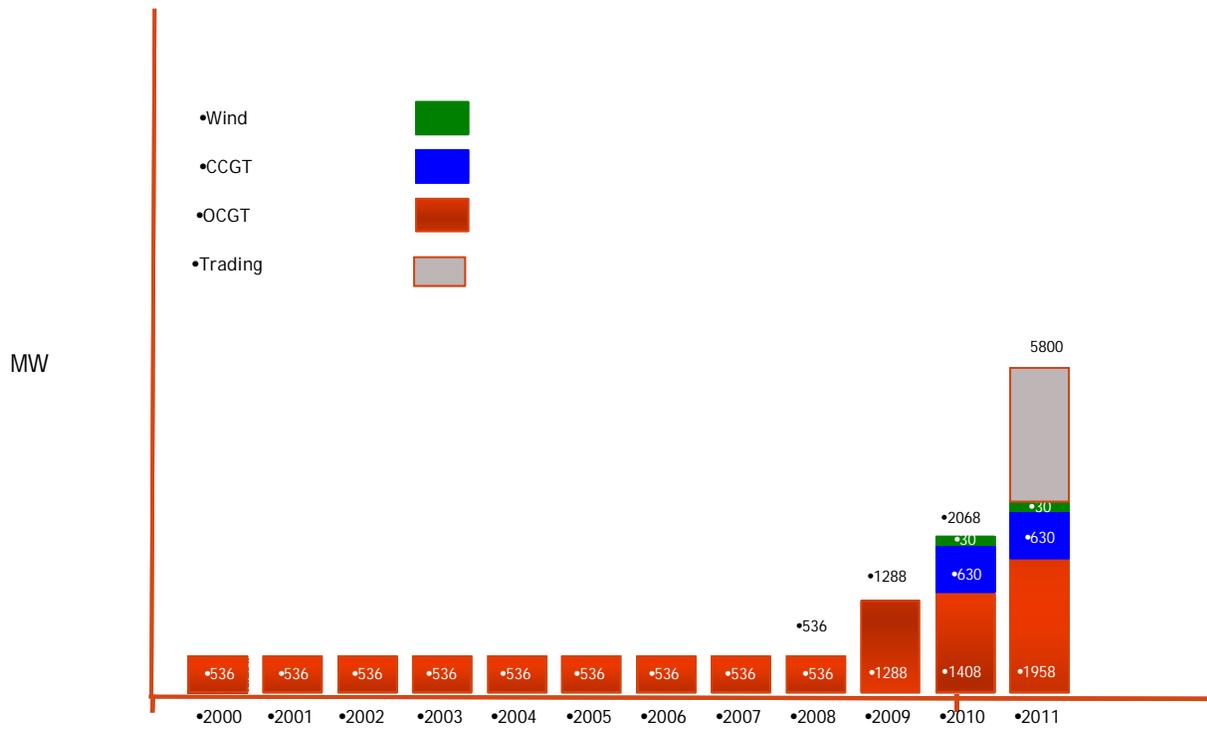
origin



Generation portfolio

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Together we can
make a difference.™

origin

Remote
operational
capability
at power
stations



Remote Operational Capability

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- Operated by NSPs like Powerlink and Electra-net
 - Roma Power Station - 74 MW
 - Ladbroke Grove Power Station - 80 MW
 - Quarantine Power Station - 224 MW
- Operated by Origin Generation
 - Mt Stuart Power Station (*Local operation*) - 423 MW
 - Darling Downs Power Station (*Local operation*) - 640 MW CCGT
 - Uranquinty Power Station (*operated by Traders - interim measure*) - 664 MW
 - Mortlake Power Station (*will be commissioned in early 2012*) - 580 MW

Remote Operation of peaking power station

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- Uranqui
- Siemens
- Control



Remote operational Requirements

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- Minimise reaction time to have units available and run up to full load.
- Maximise opportunity to trade electricity in volatile market.
- Optimise site resources.
- Increase availability and start reliability.
- Reduced risk of human intervention and error which has potential to cause delays.
- Buildup in house capability.
- Pilot trial project to support large scale growth in future.

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make a difference.™

origin

Establish
remote
operation
for peaking
power
station



Establish Remote Operation for Peaking Power Station

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make a difference.™



- Challenges to establish remote operation for peaking power Station.
- Overview of control system

Challenges to establish remote operation for peaking power Station.

Together we can
make a difference.™



- Train Commercial traders to operate power plant:
Plant Operational Competency Model which includes:
 - Plant Operational Training package
 - Customized HMI for Traders
 - Customised and Limited DCS hands on operational training.
 - Theory and practical test.
 - Final signoff to allow unit operation from customised HMI.

Challenges to establish remote operation for peaking power Station - Contd.

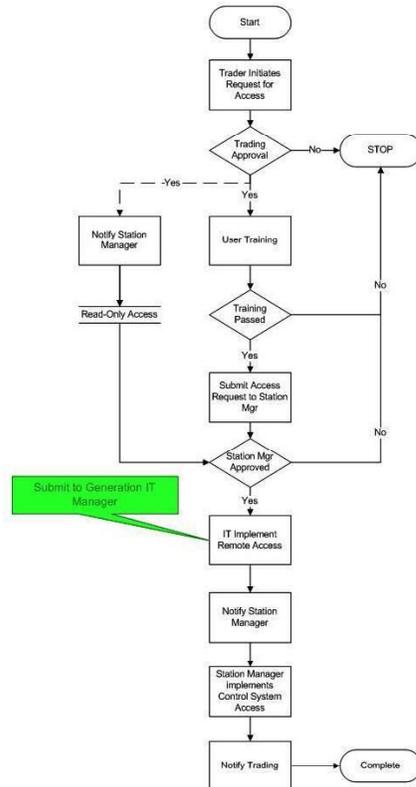
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- User Access Control
- Operational Procedures
- Customised logic design Strategy
- Documentation
- Alarm Escalation
- Emergency Trip situation
- Alarm Standardisation

User Access to Control System Application

Wednesday, January 27, 2010

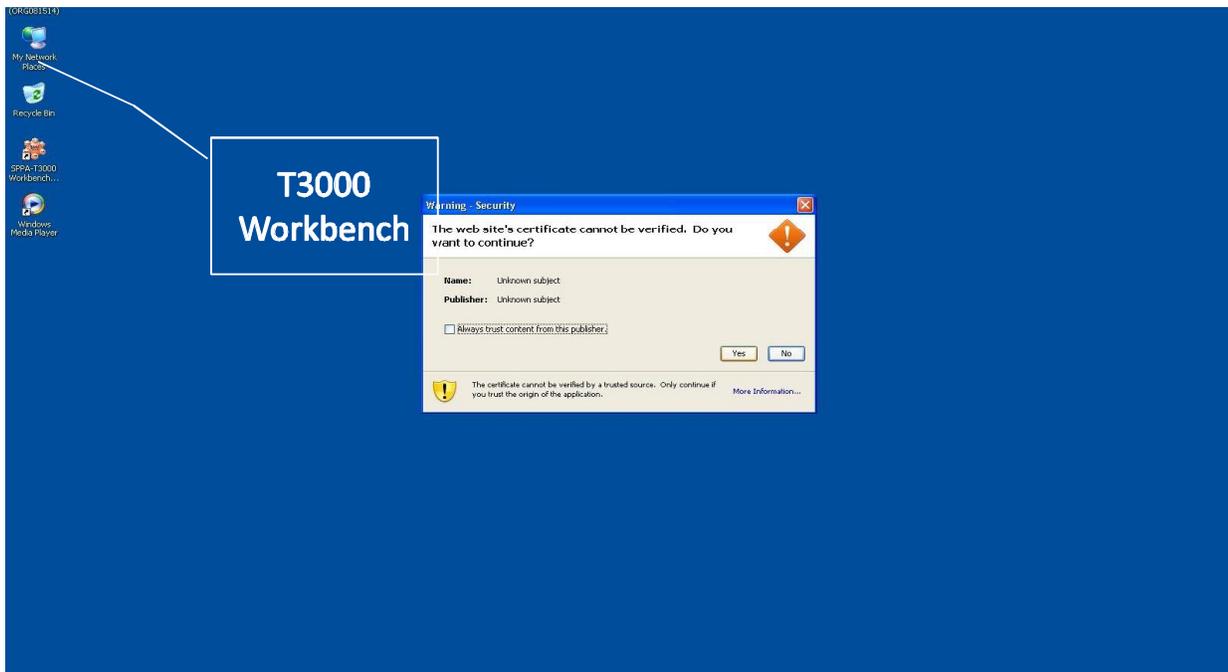


Connecting to Plant Control System (SPPA T3000) - Overview

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- Remote desktop into Client PC meant for dedicated T3000 workbench application.
- Open SPPA T3000 workbench application
- Only Authorised users can login.



Uranquinty Control System Access

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origin

- A login will be created for all authorized members of the trading team. Type in user specific Username and Password.
- User name: Specific to each individual trader
- Password: Specific to each individual trader



Customised HMI for Traders

- REMOTE OPERATION Screen with all GT's at a glance for Operations and Monitoring

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origin

The screenshot displays a software interface for remote operation of four gas turbines (GT 11, GT 12, GT 13, and GT 14). Each turbine's control panel is organized into several sections:

- GT START/STOP CONTROL:** Features a large green 'G' indicator, 'SGC GAS TURBINE' status (53), and buttons for 'GT START' and 'GT STOP'. It also shows 'RDY FOR START', 'BOP PERMISSIVE', and 'REM OPS ENABLE' indicators.
- TURB CTRL INDICATIONS:** A list of status indicators for 'RUN UP FUNCTION ACTIVE', 'SPEED CTRL ACTIVE', 'LOAD CTRL ACTIVE', 'OTC CTRL ACTIVE', and 'LOAD LMT CTRL ACTIVE'.
- EVAP COOLER:** Includes 'ON/OFF' controls, 'HUMIDITY' (44%), 'AMB AIR' (24.5 °C), and 'COMPR INLET' (34.7 °C) readings.
- PAG WATER:** Shows 'SGC PAG WATER' status (58), 'EON' (2302 h), and 'STARTS' (136).
- ACTIVE POWER SETPOINT:** Features a 'SETPOINT FROM AGC' (80.0 MW) and 'RAMP RATE FAST' controls.
- REACTIVE POWER SETPOINT:** Includes 'TO GT CTRL' (-0.5 Mvar) and 'TRANSFORMER TAP POSITION' (11).
- CURRENT CONDITIONS:** Displays 'CURRENT CONDITIONS MAX LOAD' (141 MW).

At the bottom, a legend indicates: **RED = OK, ON, Run, Open, Active.** **Green = Not Available, OFF, Closed.** The interface also shows a status bar with 'REMOTE OPERATION', 'REMOTE TRIP', and 'STATION SERVICES' indicators, along with the user 'trader' and date 'January 27, 2010 06:23:39'.

RED = OK, ON, Run, Open, Active.

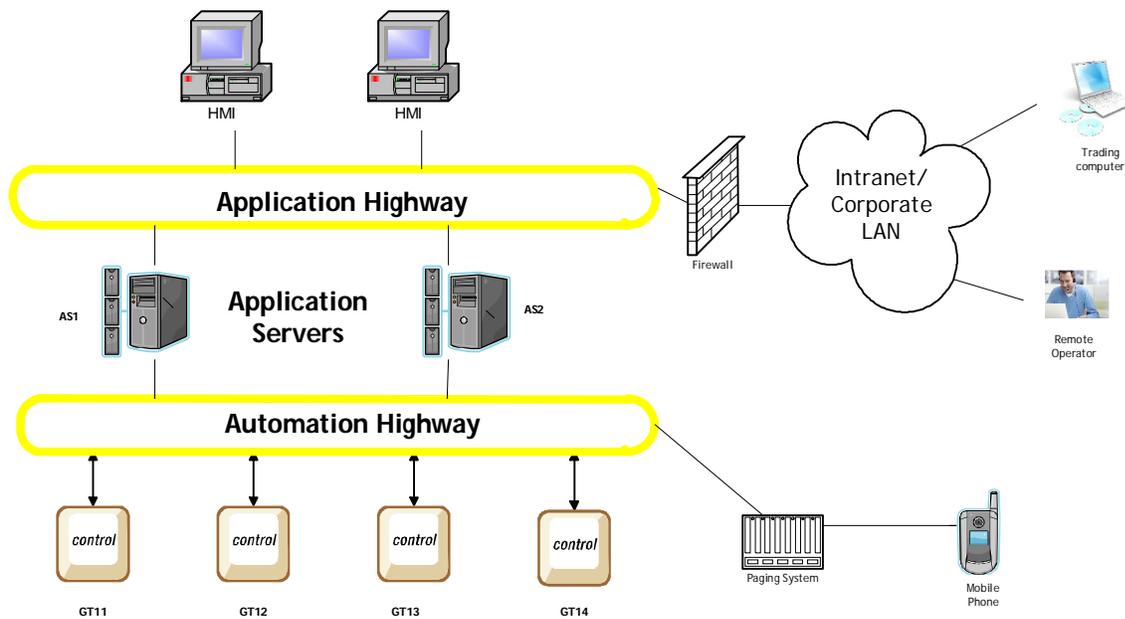
Green = Not Available, OFF, Closed.

DCS Network Architecture

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origin

Remote Operation & Monitoring



Remote Access Setup

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