# Mechanical Transfer System

Educational Training Equipment for the 21st Century

Bulletin 171-1G

# **Purpose**

The Hampden Model H-MTS-3 Mechanical Transfer System is designed to provide students with an understanding of mechanical drives and linkages. This will provide the foundation needed for the study of more advanced machines, such as industrial robots. For example, students will investigate: proportional speed drives; rotary and linear output; intermittent drives; levers; slidercrank; quick return and fourbar mechanisms.

### Description

The Hampden Model H-MTS-3 Mechanical Transfer System consists of a stationary base and all of the breadboarding components needed to perform the twenty-five drive and fifteen linkage experiments in the manual based on material prepared by the Technical Education Research Center. Included also, are a fractional horsepower DC motor, balance scales, and tools. As students assemble the various experimental mechanisms, they gain valuable manipulative skills along with an appreciation for such things as tolerance and alignment.

All of the equipment necessary to perform the forty experiments comes complete in a steel case with carrying handle and locking detachable front cover.

#### **Topics for Drive Experiments**

- Mechanical Components
- 3. Gear Teeth
- 4. Displacement
- Velocity Ratio
- 6. Torque Ratio
- 7. Simple Trains
- 8. Internal Gears
- 10. Helical Gears
- 11.
- 12.
- 13. Worm and Wheel
- 14. **Counter Rotators**
- 15.
- 16.
- 17.
- 18. **Belt Drives**
- 19. **Pulley Blocks**
- 20. **Differential Hoists**
- 21. Chain Drives

- 24. Rotary Cams

- 2. Gear Diameters

- 5.

- 9. Planetary Gear Trains
- **Bevel Gears**
- Rack and Pinion
- Mechanical Differentials
- Spring Mechanics
- Inertial Effect

- 22. Toothed Belts
- 23. Disk Drives
- 25. Universal Joints



# H-MTS-3

#### **Mechanical Transfer System**

#### Topics for Linkage Experiments

- 26. Class-One Levers
- 27. Class-Two Levers
- 28. Class-Three Levers
- 29. Four-Bar Introduction
- 30. Crank-Rocker Mechanisms
- 31. Drag-Link Mechanism
- 32. Four-Bar Summary
- 33. Slider Crank Mechanisms
- 34 Quick Return Mechanism I
- 35. Introduction to the Geneva Mechanism
- 36. Loading Geneva Mechanism
- 37. Sliding-Link Mechanism
- 38. Quick Return Mechanism II
- 39. Computing Mechanisms (Calculus)
- 40. Rachet Mechanisms

## **Optional Equipment**

#### H-MTS-3-CDL Computer Data Logging **Package**

Consists of:

Hampden HPT-100A Digital Photo Tachometer Hampden H-REM-LCD Load Cell Hampden H-MGI-A I/O Interface Module including Genie Software

BPS-12P Variable AC/DC **Power Supply** 



HPT-100A Digital Photo **Tachometer** 



All Hampden units are available for operation at any voltage or frequency



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