

So far we have considered the symmetries of ODEs.

If  $y' = F(x, y)$  is invariant under

$$\bar{x} = x + \epsilon X(x, y) + o(\epsilon^2)$$

$$\bar{y} = y + \epsilon Y(x, y) + o(\epsilon^2)$$

then Lie's invariance condition is

$$Yx + (Yy - Xx)F - xyF^2 = XF_x + YF_y \quad (1)$$

If we introduce the infinitesimal operator

$$\Gamma = X \frac{\partial}{\partial x} + Y \frac{\partial}{\partial y}$$

and its 1st extension

$$\Gamma^{(1)} = \Gamma + Y(x) \frac{\partial}{\partial y'}$$

where  $\frac{dy}{d\bar{x}} = \frac{dy}{dx} + Y(x)\epsilon + o(\epsilon^2)$

then (1) can be written as

$$\Gamma^{(1)} \Delta \Big|_{\Delta=0} = 0$$

where  $\Delta = y' - F(x, y)$

Note: we have a formula for  $\Upsilon(x)$  as

$$\Upsilon(x) = D_x(\Upsilon) - y' D_x(x)$$

We then extended to 2<sup>nd</sup> order ODE.

Lie's equivalence condition

$$\Gamma^{(2)} \Delta \Big|_{\Delta=0} = 0$$

where  $\Delta = y'' - F(x, y, y')$

$$\Gamma^{(2)} = \Gamma^{(1)} + \Upsilon(x, y) \epsilon + o(\epsilon^2)$$

where

$$\Upsilon(x, y) = D_x(\Upsilon(x)) - y'' D_x(x)$$

This extends to any order we wish.

Note

$$\bar{y}'' = y'' + \Upsilon(x, y) \epsilon + o(\epsilon^2)$$

Now we turn to PDE. Suppose we have  
 some 1st order PDE

$$F(t, x, u, u_t, u_x) = 0 \quad (2)$$

Say  $u_t = u_x^2$

Can we find the invariances (symmetries)  
 of this. We introduce infinitesimal trans

$$\bar{t} = t + T(t, x, u)\epsilon + O(\epsilon^2)$$

$$\bar{x} = x + X(t, x, u)\epsilon + O(\epsilon^2)$$

$$\bar{u} = u + D(t, x, u)\epsilon + O(\epsilon^2)$$

extended transformations

$$\bar{u}_t = u_t + D_t\epsilon + O(\epsilon^2)$$

$$\bar{u}_x = u_x + D_x\epsilon + O(\epsilon^2)$$

substitution of (2) gives (to order  $\epsilon^2$ )

$$T F_t + X F_x + D F_u + D_t F_{u_t} + D_x F_{u_x} = 0 \quad (3)$$

where  $F(t, x, u, u_t, u_x) = 0$

If we introduce the infinitesimal operator

$$\Gamma = T \frac{\partial}{\partial t} + X \frac{\partial}{\partial x} + U \frac{\partial}{\partial u}$$

of 1st extension

$$\Gamma^{(1)} = \Gamma + D(t) \frac{\partial}{\partial t} + D(x) \frac{\partial}{\partial x}$$

Lie invariance condition (2) can be written as

$$\Gamma^{(1)} \Delta \Big|_{\Delta=0}$$

where  $\Delta = F(t, x, u, u_t, u_x)$  The same as for  $-D(t)$ .

Now we need formulas for  $D(t)$  &  $D(x)$ .

so we consider (we will use Jacobians)

$$\begin{aligned} \frac{\partial \bar{u}}{\partial \bar{t}} &= \frac{\partial(\bar{u}, \bar{x})}{\partial(\bar{t}, \bar{x})} = \frac{\partial(\bar{u}, \bar{x})}{\partial(t, x)} \Big/ \frac{\partial(\bar{t}, \bar{x})}{\partial(t, x)} \\ &= \begin{vmatrix} \bar{u}_t & \bar{u}_x \\ \bar{x}_t & \bar{x}_x \end{vmatrix} \Big/ \begin{vmatrix} \bar{t}_t & \bar{t}_x \\ \bar{x}_t & \bar{x}_x \end{vmatrix} \end{aligned}$$

we define total differential operator

$$D_t = \frac{\partial}{\partial t} + u_t \frac{\partial}{\partial u} + u_{tt} \frac{\partial}{\partial u_t} + u_{tx} \frac{\partial}{\partial u_x} + \dots$$

$$D_x = \frac{\partial}{\partial x} + u_x \frac{\partial}{\partial u} + u_{tx} \frac{\partial}{\partial u_t} + u_{xx} \frac{\partial}{\partial u_x} + \dots$$

so

$$\frac{\partial \bar{u}}{\partial \bar{E}} = \frac{\begin{vmatrix} u_t + \varepsilon D_t(\bar{u}) & u_x + \varepsilon D_x(\bar{u}) \\ \varepsilon D_t(x) & 1 + \varepsilon D_x(x) \end{vmatrix}}{1 + \varepsilon D_x(x)} + o(\varepsilon^2)$$

$$= \frac{u_t + \varepsilon \left[ D_t(\bar{u}) + u_t D_x(x) - u_x D_t(x) \right]}{1 + \varepsilon \left[ D_t(\bar{u}) + D_x(x) \right]} + o(\varepsilon^2)$$

$$= u_t + \varepsilon \left[ D_t(\bar{u}) + u_t D_x(x) - u_x D_t(x) \right] \cdot \left\{ 1 - \varepsilon \left[ D_t(\bar{u}) + D_x(x) \right] \right\} + o(\varepsilon^2)$$

$$= u_t + \varepsilon \left[ D_t(\bar{u}) + u_t D_x(x) - u_x D_t(x) - u_t D_t(\bar{u}) - u_t D_x(x) \right] + o(\varepsilon^2)$$

giving

$$\bar{u}_T = u_t + \epsilon \left[ D_t(u) - u_t D_t(t) - u_x D_x(x) \right] + O(\epsilon^2)$$

$$\text{so } \bar{D}[t] = D_t(u) - u_t D_t(t) - u_x D_x(x)$$

A similar calculation gives

$$\bar{D}[x] = D_x(u) - u_t D_x(t) - u_x D_x(x)$$

Ex calculate the symmetries of

$$u_t = u_x^2$$

Let's Inv. Cond.

$$\bar{D}[t] = 2u_x \bar{D}[x]$$

$$\text{so } \bar{D}_t + D_u u_t - u_t (T_t + T_u u_t) - u_x (X_t + X_u u_t)$$

$$= 2u_x \left[ \begin{aligned} &D_x + D_u u_x - u_t (T_x + T_u u_x) \\ &- u_x (X_x + X_u u_x) \end{aligned} \right]$$

now let  $u_t = u_x^2$  & isolate coeff w.r.t  $u_x$

$$1) \quad T_t = 0 \quad 1a$$

$$u_x) \quad -X_t = 2T_x \quad 1b$$

$$u_x^2) \quad T_u - T_t = 2T_u - 2X_x \quad 1c$$

$$u_x^3) \quad -X_u = -2T_x - 2X_u \quad 1d$$

$$u_x^4) \quad -T_u = -2T_u \quad 1e$$

so (1e) says  $T_u = 0 \Rightarrow T = A(t, x)$

from 1d  $X_u = -2T_x = -2A_x$

so  $X = -2A_x u + B(t, x)$

from 1c  $T_u = 2X_x - T_t = -4A_{xx}u + 2B_x - A_t$

so  $D = -2A_{xx}u^2 + (2B_x - A_t)u + C(t, x)$

from 1a  $T_t = 0$

$$\Rightarrow -2A_{xx}u^2 + (2B_x - A_t)u + C_t = 0$$

$$\Rightarrow A_{xx} = 0 \quad 2B_x - A_t = 0 \quad C_t = 0 \quad (2)$$

From (b) when  $2D_x + X_t = 0$

$$\Rightarrow -4A_{xxx}u^2 + 2(2B_{xx} - A_{tx})u + 2Cx - 2A_{tx}u + B_t = 0$$

$$\Rightarrow -4A_{xxx} = 0 \quad 3a$$

$$4B_{xx} - 4A_{tx} = 0 \quad 3b$$

$$2Cx + B_t = 0 \quad 3c$$

3a gives

$$A = a_1(t)x^2 + a_2(t)x + a_3(t)$$

$a_1, a_2, a_3$  are fcts

$$3a \Rightarrow a_1 = c_1 \text{ const.}$$

$$3b \text{ gives } B_{xx} = A_{tx} = a_2'(t)$$

$$B = \frac{a_2'(t)}{2}x^2 + b_1(t)x + b_2(t) \quad b_1, b_2 \text{ are fcts}$$

$$3c \quad Cx = -\frac{1}{2}B_t = -\frac{1}{2} \left\{ \frac{a_2''}{2}x^2 + b_1'x + b_2' \right\}$$

$$C = -\frac{a_2''}{12}x^3 - \frac{b_1'}{4}x^2 - \frac{b_2'}{2}x + c(t)$$

$c$  is fct.



2.6.1 gives

$$2 \left[ a_2'' x + b_1' \right] - \left[ a_2'' x + a_3'' \right] = 0$$

$$\Rightarrow 2a_2'' - a_2'' = 0 \quad 2b_1' - a_3'' = 0$$

$$2.6) \quad a_2''' = 0 \quad b_1'' = 0 \quad b_2'' = 0 \quad c' = 0$$

we solve these giving

$$a_2 = c_2 t + c_3$$

$$a_3 = c_4 t^2 + c_9 t + c_{10}$$

$$b_1 = c_4 t + c_5$$

$$b_2 = c_6 t + c_7$$

$$c = c_8$$

giving

$$T = c_1 x^2 + (c_2 t + c_3) x + c_4 t^2 + c_9 t + c_{10}$$

$$X = -2 \left( 2c_1 x + c_2 t + c_3 \right) u + \frac{c_2}{2} x^2 + (c_4 t + c_5) x + c_6 t + c_7$$

$$D = -4c_1 u^2 + (c_2 x - c_9 + 2c_5) u - \frac{c_4}{4} x^2 - \frac{c_6 x}{2} + c_8$$